



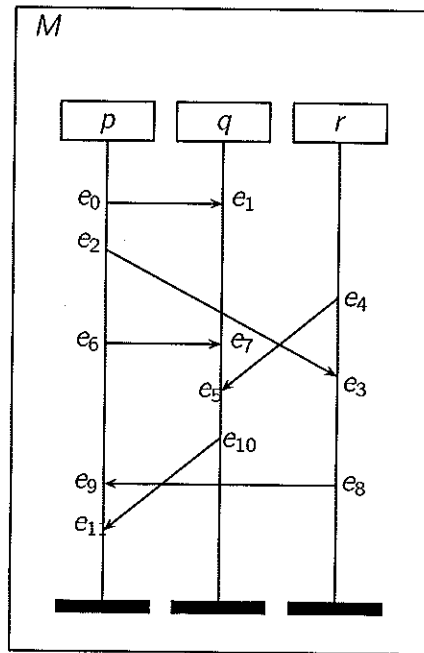
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Falak Sher, Sabrina von Styp

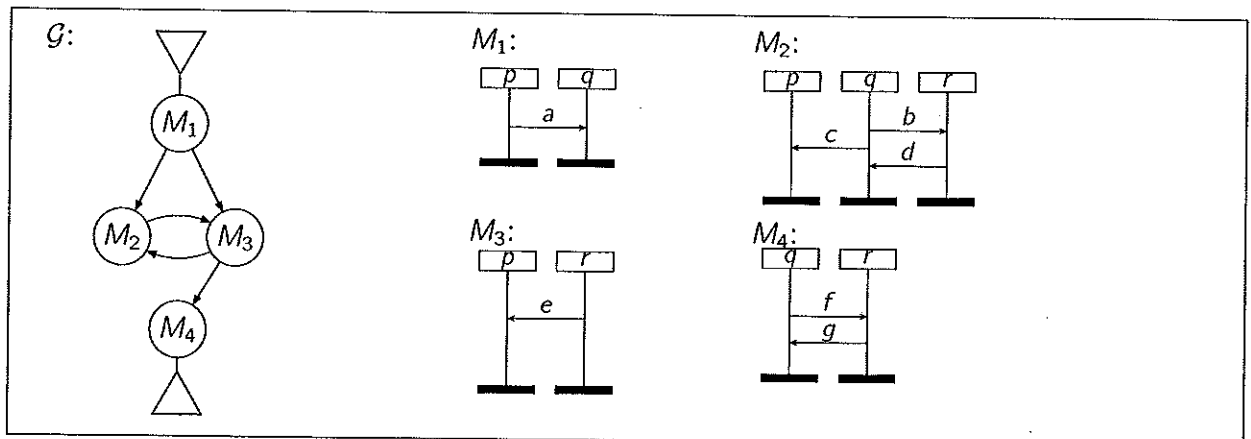
Exercise 1 (Races):

(5+5 points)

- a) Does the following MSC M have a race? If yes, indicate all pairs of events that form a race.



- b) Consider the following MSG \mathcal{G} . Is there a path so that \mathcal{G} has a race?



Solution: _____



Name:

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- a) The MSC M_1 has the following three races:
- e_7 and e_5
 - e_1 and e_5
 - e_9 and e_{11}
- b) The MSG M has a race on the path $M_1M_2M_3M_4$. The race is between receiving message c and e in process p .



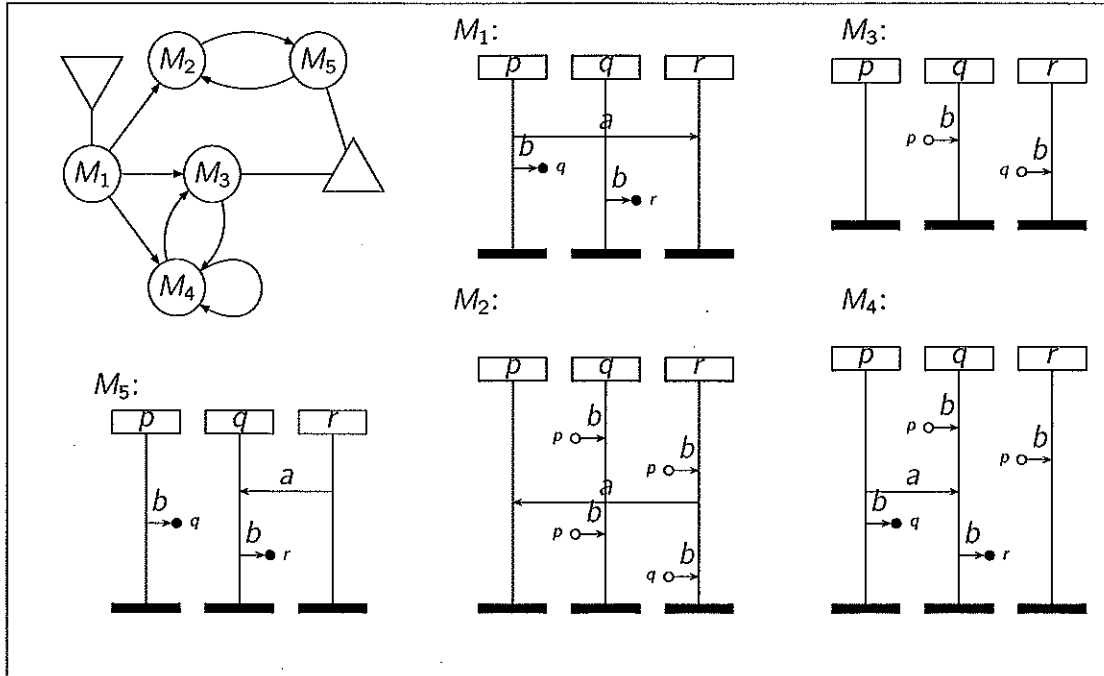
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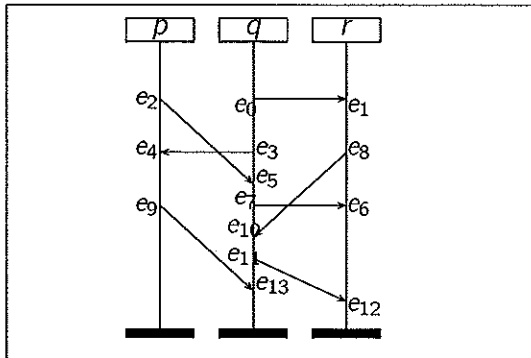
Exercise 2 (Safeness and \exists/\forall boundedness):

(4+3+3 points)

a) Determine if the following CMSG is safe. Justify your answer.



b) Determine for the following MSC if it is existentially (\exists -) or universally (\forall -) bounded. In case it is \exists/\forall -bounded, determine the smallest B such that the MSC is \exists/\forall - B -bounded and argue why it cannot be \exists/\forall - $(B - 1)$ -bounded.

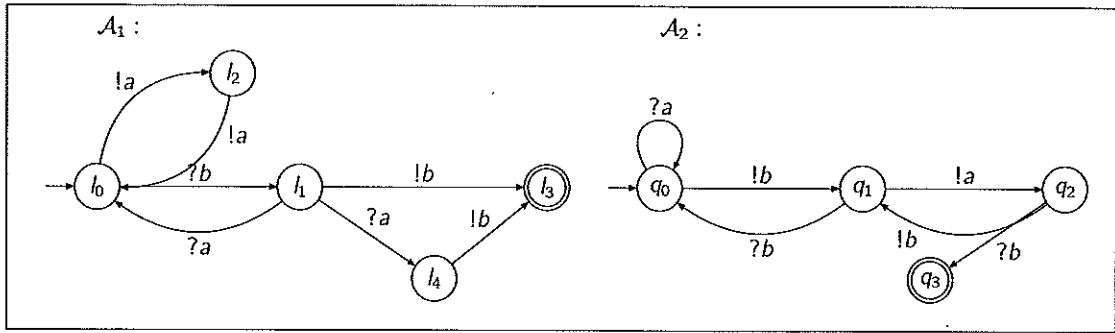


c) Let the following CFM \mathcal{A} , described by \mathcal{A}_1 and \mathcal{A}_2 , be given. Is the CFM \mathcal{A} \exists/\forall - B -bounded? (if the answer is yes find the smallest such B)



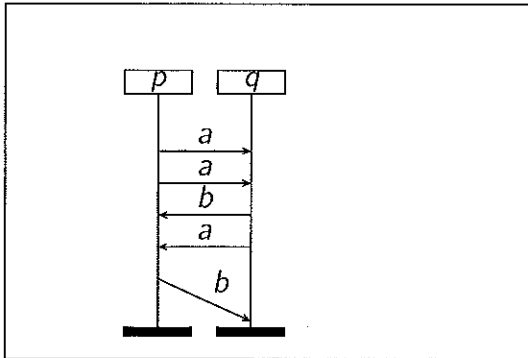
Name: _____

Matriculation Number: _____



Solution: _____

- a) The CMSG \mathcal{G} is not safe the MSCs that ist generated when concatenating $M_1M_2M_5M_2M_5$ has two unmatched receive messages.
- b) M is $\exists - 1$ -bounded, as every message can be received before the next one for the same channel is sent.
 M is $\forall - 2$ -bounded, as the q can only sent two of its three messages to r e_0 and e_7 then e_1 has to happen as e_8 has to be executed since $e_{10} <_p e_{11}$.
- c) The DFA \mathcal{G} is $\exists - 1$ -bounded, as the corresponding MSC is $\exists - 1$ -bounded.

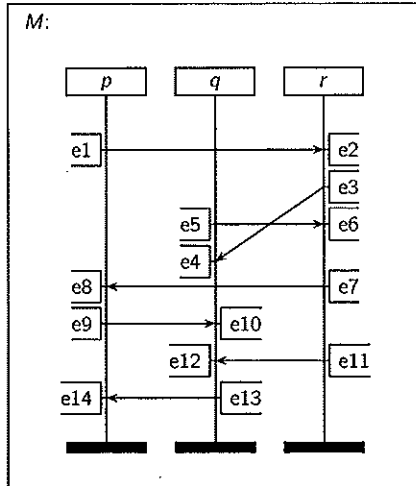


The \mathcal{G} is not \forall -bounded, as \mathcal{A}_1 can loop between location l_0 and l_2 and \mathcal{A}_2 must not receive any messages.

Exercise 3 (PDL):

(10 points)

a) Consider the following MSC M defined over the set of processes $\mathcal{P} = \{p, q, r\}$.



Determine whether the MSC M satisfies the following PDL formulas or not. If your answer is 'yes', provide at least one event that satisfies the corresponding formula.

- 1) $\exists((proc + msg)^*; \{?(p, q, \cdot)\})[proc]^{-1}((proc + msg)^*)(r, q, \cdot)$
- 2) $\exists(\{!p\}; (proc + \{[msg]^{-1}\}; \{!q \vee ?p\})^*)?p$
- 3) $\exists(msg)[proc]^{-1}(msg)[proc; proc]^{-1}false$

Note: for $p_1, p_2 \in \mathcal{P}$, $?(p_1, p_2, \cdot)$ abbreviates $\bigvee_{a \in \mathcal{C}}?(p_1, p_2, a)$ where \mathcal{C} and \mathcal{P} are the sets of message contents and processes in the MSC M respectively. Moreover, we define $?p_1 = \bigvee_{p' \in \mathcal{P} \setminus \{p_1\}, a \in \mathcal{C}}?(p_1, p', a)$. Similarly we define $!p_1$.

b) Write down the PDL formulas that correspond to the informal descriptions about the MSC M :

- 1) Once process p receives a message from process r , it will not receive any message any further.
- 2) Every message that process r receives from process q is immediately passed from process r to process p .

Solution: _____



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a) The satisfaction PDL formulas by MSC M is given as:

1) No. Only one event e_{14} is labelled with $?(p, q, \cdot)$. As e_{14} is the only maximal event of the MSC M , every other event has a path that eventually reaches e_{14} . From e_{14} , we reach e_9 by performing $[proc]^{-1}$ and going one step back along the process p . From the event e_9 , by doing $proc$ or msg , there is no way to reach to event e_6 that is labelled with $?(r, q, \cdot)$. Hence, no event satisfies this formula.

2) Yes, both e_1 and e_9 satisfy the formula.

Both e_1 and e_9 are sent-events at process p . By performing $proc$ from e_1 and e_9 , we reach e_8 and e_{14} respectively which are receive-events at process p . e_8 and e_{14} satisfy $\{!q\vee?p\}$ and $?p$. Hence, the formula is satisfied by e_1 and e_9 .

3) Yes, e_5 satisfies the formula. We present the following path that shows the satisfaction of the formula by e_5 .

$e_5 \xrightarrow{msg} e_6 \xrightarrow{[proc]^{-1}} e_3 \xrightarrow{msg} e_4 \xrightarrow{[proc]^{-1}} e_5 \xrightarrow{[proc]^{-1}} false$.

b) 1) $\forall (?(p, r, \cdot) \rightarrow [(proc; \{-?p\})^*; proc]false)$.

2) $\forall \bigwedge_{a \in \mathcal{C}} (?(r, q, a) \rightarrow [proc]!(r, p, a))$. or
 $\bigwedge_{a \in \mathcal{C}} \forall (?(r, q, a) \rightarrow [proc]!(r, p, a))$.

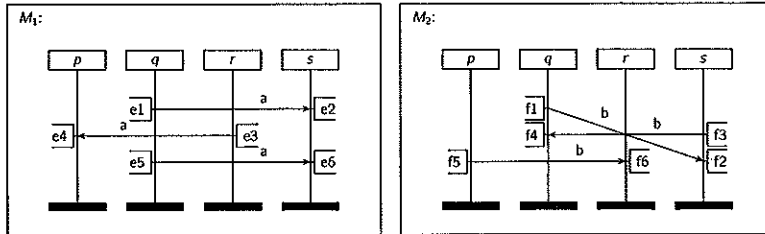
Note: for $p_1, p_2 \in \mathcal{P}$, $?(p_1, p_2, \cdot)$ abbreviates $\bigvee_{a \in \mathcal{C}} ?(p_1, p_2, a)$ where \mathcal{C} and \mathcal{P} are the sets of message contents and processes in the MSC M respectively. Moreover, we define $?p_1 = \bigvee_{p' \in \mathcal{P} \setminus \{p_1\}, a \in \mathcal{C}} ?(p_1, p', a)$.



Exercise 4 (Realizability):

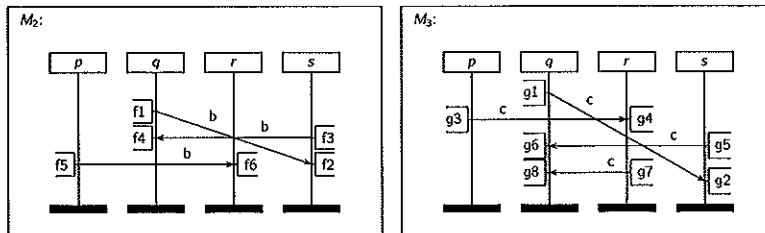
(10 points)

a) Consider the following MSCs M_1 and M_2 defined over the set of processes $\mathcal{P} = \{p, q, r, s\}$.



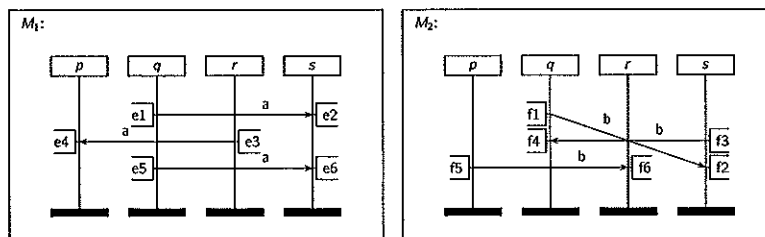
Prove that $L_1 = Lin(M_1) \cup Lin(M_2)$ is not closed under \models .

b) Consider the following MSCs M_2 and M_3 defined over the set of processes $\mathcal{P} = \{p, q, r, s\}$.



Prove that $L_2 = Lin(M_2) \cup Lin(M_3)$ is not closed under \models^{df} .

c) Consider the following MSCs M_1 and M_2 defined over the set of processes $\mathcal{P} = \{p, q, r, s\}$.



Modify either M_1 or M_2 by adding only one pair of send and receive events such that $Lin(M_1) \cup Lin(M_2)$ is closed under \models .

Solution: _____

a) Let $w = e_3 e_4 f_1 f_3 f_2 f_4$ be a well-formed word, where each $l(e_i), l(f_i) \in Act$. We have projections of w on each process in $\mathcal{P} = \{p, q, r, s\}$ as:



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- $w_{l_p} = e_4$
- $w_{l_q} = f_1 f_4$
- $w_{l_r} = e_3$
- $w_{l_s} = f_3 f_2$

For each process $j \in \mathcal{P} = \{p, q, r, s\}$, we find a word $v \in L_1$ such that $v_{l_j} = w_{l_j}$.

- For process p , we have $v = e_1 e_2 e_3 e_4 e_5 e_6$ and $v_{l_p} = e_4 = w_{l_p} = e_4$.
- For process q , we have, $v = f_1 f_3 f_2 f_4 f_5 f_6$ and $v_{l_q} = f_1 f_4 = w_{l_q} = f_1 f_4$.
- For process r , we have $v = e_1 e_2 e_3 e_4 e_5 e_6$ and $v_{l_r} = e_3 = w_{l_r} = e_3$.
- For process s , we have $v = f_1 f_3 f_2 f_4 f_5 f_6$ and $v_{l_s} = f_3 f_2 = w_{l_s} = f_3 f_2$.

This shows that $L_1 \models w$ but $w \notin \text{pref}(L_1)$. Hence L_1 is not closed under \models .

b) Let $w = f_1 g_5 g_2$ be a proper word, where each $l(f_i), l(g_i) \in \text{Act}$. We have projections of w on each process in $\mathcal{P} = \{p, q, r, s\}$ as:

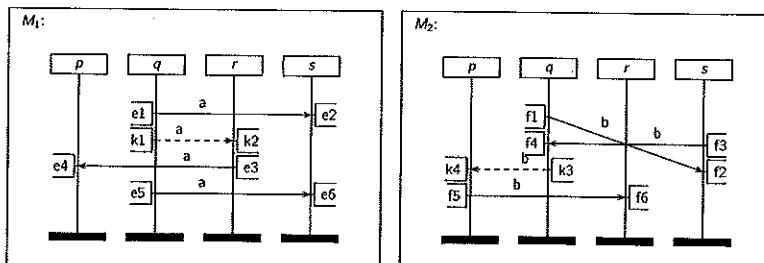
- $w_{l_p} = \epsilon$
- $w_{l_q} = f_1$
- $w_{l_r} = \epsilon$
- $w_{l_s} = g_5 g_2$

For each process $j \in \mathcal{P} = \{p, q, r, s\}$, we find a word $v \in L_2$ such that w_{l_j} is a prefix of v_{l_j} .

- For process p , we have $v = f_1 f_3 f_2 f_4 f_5 f_6$ and $w_{l_p} = \epsilon$ is a prefix of $v_{l_p} = f_5$.
- For process q , we have $v = f_1 f_3 f_2 f_4 f_5 f_6$ and $w_{l_q} = f_1$ is a prefix of $v_{l_q} = f_1 f_4$.
- For process r , we have $v = f_1 f_3 f_2 f_4 f_5 f_6$ and $w_{l_r} = \epsilon$ is a prefix of $v_{l_r} = f_6$.
- For process s , we have $v = g_1 g_5 g_2 g_6 g_3 g_4 g_7 g_8$ and $w_{l_s} = g_5 g_2$ is a prefix of $v_{l_s} = g_5 g_2$.

This shows that $L_2 \models^{df} w$ but $w \notin \text{pref}(L_2)$. Hence L_2 is not closed under \models^{df} .

c) Let $L_3 = \text{Lin}(M_1) \cup \text{Lin}(M_2)$. We only need to make M_1 or M_2 weakly connected; and that can be done by adding just one pair of events in M_1 or M_2 . The language L_3 will then become closed under \models , and thus realizable. Following could be the two possibly ways to modify MSCs.



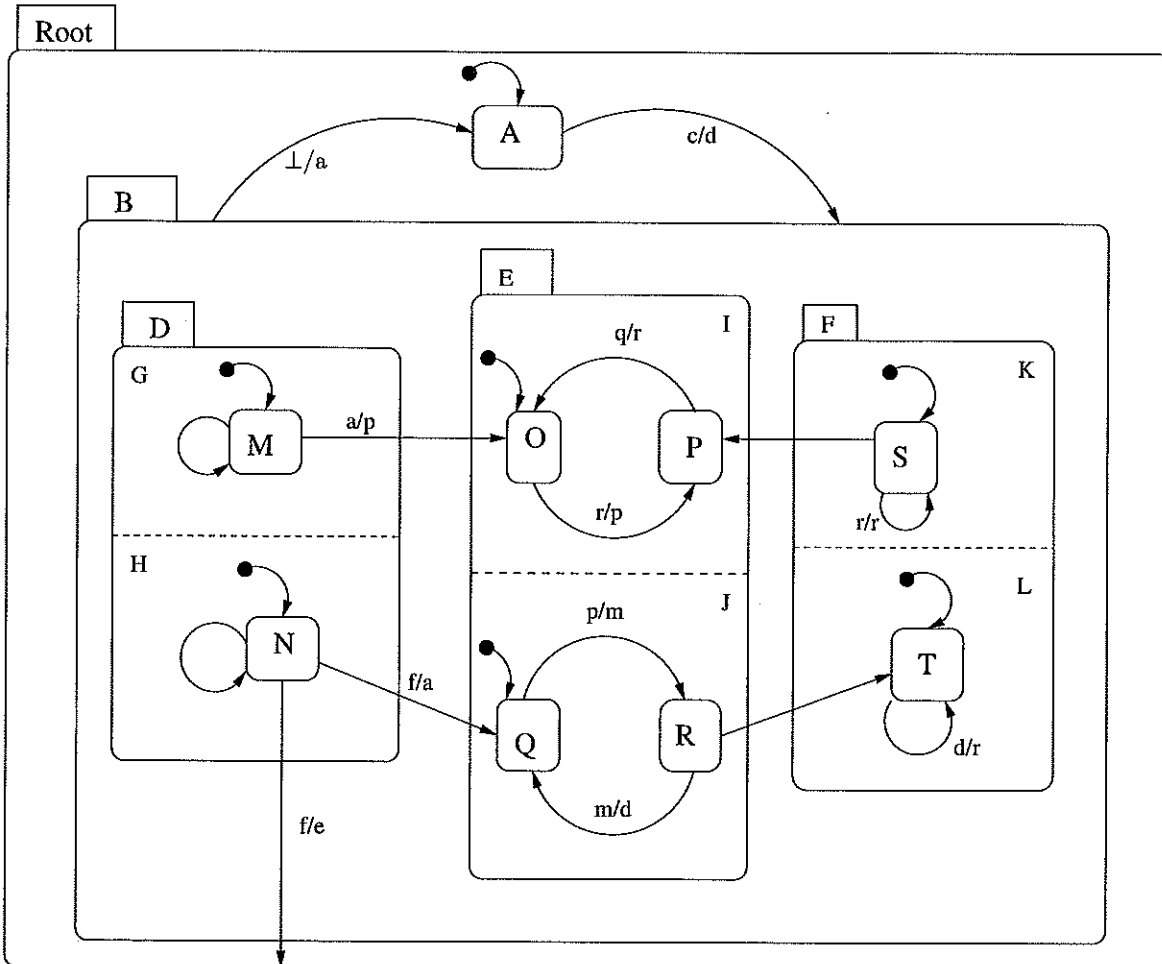
Now we are not able to find even a single well-formed word $w \in \text{Act}^*$ such that $L_3 \models w$ and $w \notin L_3$. Hence, L_3 is closed under \models .



Exercise 5 (Statechart):

(10 points)

Let the following statechart $\mathbb{S} = (N, E, Edges)$ be given:



Note: In this assignment an edge label of the form e/e' of Statechart \mathbb{S} means that \mathbb{S} is consuming event e and executing an action that is sending the event e' to \mathbb{S} (i.e., to itself).

- a) Give the type of the nodes A , B , D and N .
- b) Construct the tree that represents the node hierarchy of statechart \mathbb{S} .
- c) Determine the priority between:
 - 1) moving from N to Q and moving from N to $Root$, and
 - 2) moving from M to M and moving from M to O
 provided both the edges are enabled in each of the above cases.
- d) Determine the scope of the edges:
 - 1) $\{R\} \rightarrow \{T\}$



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2) $\{Q\} \rightarrow \{R\}$

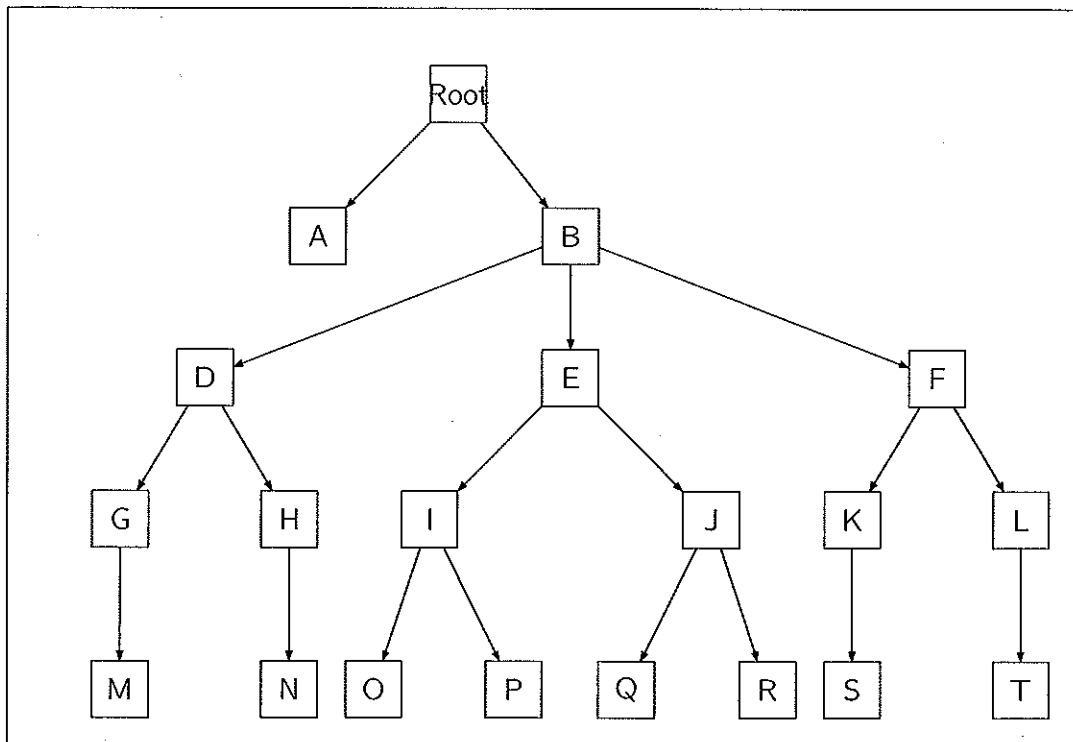
e) Consider the configuration $C = \{Root, B, E, O, Q\}$ in the statechart \mathcal{S} .

- 1) Provide the maximal set of events I that can be consumed in the configuration C .
- 2) Provide all possible steps in configuration C .

Solution: _____

a) $type(A) = BASIC$, $type(B) = OR$, $type(D) = AND$ and $type(N) = BASIC$.

b) The node hierarchy for \mathcal{S} is as:



c) Priority of edges

- $scope(\{N\} \rightarrow \{Q\}) = B$, $scope(\{N\} \rightarrow \{Root\}) = Root$. Node B is an ancestor of node $Root$, therefore edge $\{N\} \rightarrow \{Q\}$ has a higher priority.
- $scope(\{M\} \rightarrow \{M\}) = G$, $scope(\{M\} \rightarrow \{O\}) = B$. Node G is an ancestor of node $Root$, therefore edge $\{M\} \rightarrow \{M\}$ has a higher priority.

d) Scope of an edge is the most nested OR-node that is unaffected by executing the edge.

1) $scope(\{R\} \rightarrow \{T\}) = B$



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2) $scope(\{Q\} \rightarrow \{R\}) = J$

e) Consider the configuration $C = \{Root, B, E, O, Q\}$ in the statechart S .

1) The maximal set of events $I = \{r, p\}$

2) The set of all possible steps is $Steps = \{O \xrightarrow{r/p} P, Q \xrightarrow{p/m} R\}$. This set is consistent as both the edges can be executed concurrently.