## Modeling and Verification of Probabilistic Systems

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Lehrstuhl für Informatik 2 Software Modeling and Verification Group

http://moves.rwth-aachen.de/teaching/ws-1819/movep18/

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# Overview

Introduction

2 Preliminaries

3 Verifying regular safety properties

- 4  $\omega$ -regular properties
- 5 Verifying DBA objectives
- 6 Verifying  $\omega$ -regular properties
  - **O** Summary

 $\Pr(\Diamond G)$  $Pr(s \models \Box \Diamond G)$  $P_r(s \models Q \square G)$ W-regular properties DOF A ODH

# Summary of previous lectures

## **Reachability probabilities**

Can be obtained as a unique solution of a linear equation system.

## Reachability probabilities are pivotal

- 1. Repeated reachability
  - $\blacktriangleright$  = Reachability of the BSCCs containing a goal state
- 2. Persistence
  - Reachability of the BSCCs only containing goal states

⊲□ G

# Aim of this lecture

Reachability probabilities = key to determine the probability of any  $\omega$ -regular property. (This includes all linear temporal logic formulas.)

## Major steps for Markov chain $\ensuremath{\mathcal{D}}$

- 1. Consider first a simple class of properties: regular safety properties.
- 2. All traces refuting such property P are recognized by a deterministic finite-state automaton A.



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## Major steps for Markov chain $\ensuremath{\mathcal{D}}$

- 1. Consider first a simple class of properties: regular safety properties.
- 2. All traces refuting such property P are recognized by a deterministic finite-state automaton A.
- 3. Probability of P = reachability probability in a product of D and A.
- 4. What are  $\omega$ -regular properties?
- 5. All traces satisfying such property P are recognized by a deterministic Rabin automaton A.

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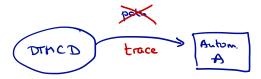
## 7) Summary

# Paths and traces

#### Paths

A *path* in DTMC  $\mathcal{D}$  is an infinite sequence of states  $s_0 s_1 s_2 \dots$  with  $\mathbf{P}(s_i, s_{i+1}) > 0$  for all *i*.

Let  $Paths(\mathcal{D})$  denote the set of paths in  $\mathcal{D}$ , and  $Paths^*(\mathcal{D})$  the set of finite prefixes thereof.



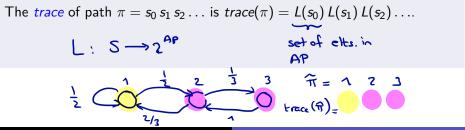
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# Paths and traces

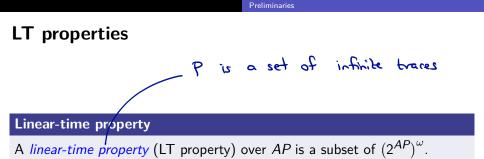
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#### Traces

The *trace* of path  $\pi = s_0 s_1 s_2 \dots$  is  $trace(\pi) = L(s_0) L(s_1) L(s_2) \dots$ The trace of finite path  $\hat{\pi} = s_0 s_1 \dots s_n$  is  $trace(\hat{\pi}) = L(s_0) L(s_1) \dots L(s_n)$ . The *set of traces* of a set  $\Pi$  of paths:  $trace(\Pi) = \{ trace(\pi) \mid \pi \in \Pi \}$ .



# LT properties

## Linear-time property

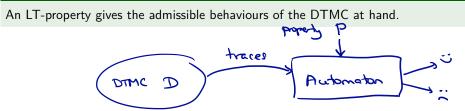
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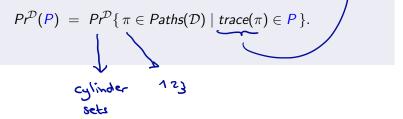
## Intuition



# Probability of LT properties

Probability of LT properties

The *probability* for DTMC  $\mathcal{D}$  to exhibit a trace in property *P* (over AP) is:



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The *probability* for DTMC D to exhibit a trace in property *P* (over *AP*) is:

$$\mathsf{Pr}^{\mathcal{D}}(\mathsf{P}) \;=\; \mathsf{Pr}^{\mathcal{D}}\{\,\pi\in\mathsf{Paths}(\mathcal{D})\mid \mathit{trace}(\pi)\in\mathsf{P}\,\}.$$

For state s in  $\mathcal{D}$ , let  $Pr(s \models P) = Pr_s \{ \pi \in Paths(s) \mid trace(\pi) \in P \}.$ 

# Probability of LT properties Probability of LT properties The probability for DTMC $\mathcal{D}$ to exhibit a trace in property P (over AP) is: $Pr^{\mathcal{D}}(P) = Pr^{\mathcal{D}}\{\pi \in Paths(\mathcal{D}) \mid trace(\pi) \in P\}.$ For state s in $\mathcal{D}$ , let $Pr(s \models P) = Pr_s\{\pi \in Paths(s) \mid trace(\pi) \in P\}.$

We do not address measurability of P yet. We will later identify a rich set P of LT-properties—those that include all LTL formulas—for which the set of paths  $\{ \pi \in Paths(D) \mid trace(\pi) \in P \}$  is measurable.

# **Safety properties**

# Safety properties set of infinite traces

## Safety property

LT property  $P_{safe}$  over AP is a <u>safety property</u> if for all  $\sigma \in (2^{AP})^{\omega} \setminus P_{safe}$ there exists a finite prefix  $\hat{\sigma}$  of  $\sigma$  such that:

$$P_{safe} \cap \underbrace{\left\{\sigma' \in (2^{AP})^{\omega} \mid \hat{\sigma} \text{ is a prefix of } \sigma'\right\}}_{\text{all possible extensions of } \hat{\sigma}} = \varnothing.$$
no extension of  $\hat{\sigma}$  is a trace in  $P_{safe}$ 

$$\overline{\pi} = bad \quad \text{prefix}$$

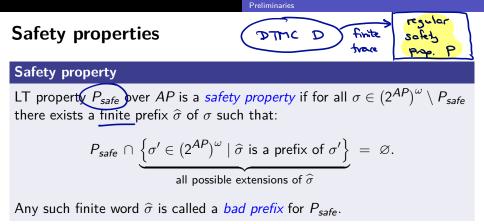
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Any such finite word  $\hat{\sigma}$  is called a *bad prefix* for  $P_{safe}$ .



#### Regular safety property

A safety property is *regular* if its set of bad prefixes constitutes a regular language (over the alphabet  $2^{AP}$ ).

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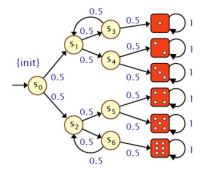
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#### Regular safety property

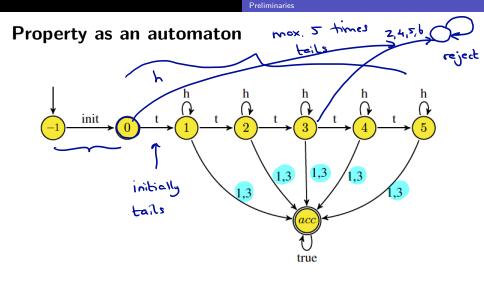
A safety property is *regular* if its set of bad prefixes constitutes a regular language (over the alphabet  $2^{AP}$ ). Thus, the set of all bad prefixes of a regular safety property can be represented by a finite-state automaton.

# Property of Knuth's die



## Property of Knuth's die

After initial tails, yield 1 or 3 but with maximally five time tails.



After initial tails, yield 1 or 3 but with at most five times tails in total

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Let  $\mathcal{A} = (Q, 2^{AP}, \delta, q_0, F)$  be a deterministic finite-state automaton (DFA) for the bad prefixes of regular safety property  $P_{safe}$ :

$$\frac{P_{safe}}{P_{safe}} = \begin{cases} A_0 A_1 A_2 \dots \in (2^{AP})^{\omega} & \forall n \ge 0. A_0 A_1 \dots A_n \notin \mathcal{L}(\mathcal{A}) \end{cases}.$$

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Let  $\delta$  be total, i.e.,  $\delta(q, A)$  is defined for each  $A \subseteq AP$  and state  $q \in Q$ .



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$$\frac{Pr^{\mathcal{P}}(P_{safe})}{1 - \sum_{s \in S} \iota_{init}(s) \cdot Pr(s \models \mathcal{A})} \text{ where }$$

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$$(Pr^{\mathcal{D}}(P_{safe})) = 1 - \sum_{s \in S} \iota_{init}(s) \cdot Pr(s \models \mathcal{A}) \text{ where}$$

$$Pr(s \models A) = Pr_s^{\mathcal{D}} \{ \pi \in Paths(s) \mid trace(\pi) \notin P_{safe} \}.$$

These probabilities can be obtained by considering a product of DTMC  ${\cal D}$  with DFA  ${\cal A}.$ 

Joost-Pieter Katoen

$$Pr^{\mathcal{D}}(P_{safe}) = 1 - \sum_{s \in S} \iota_{\text{init}}(s) \cdot Pr(s \models \mathcal{A})$$
 where

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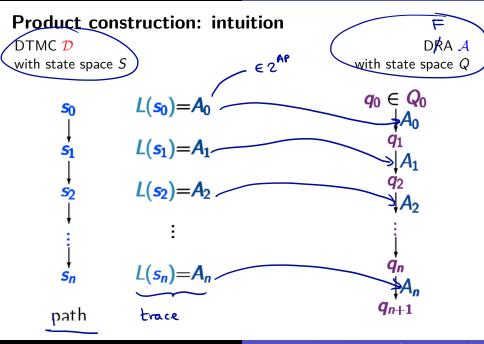
### Remark

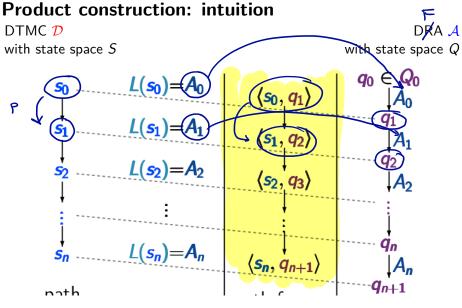
The value  $Pr(s \models A)$  can be written as the (possibly infinite) sum:

$$Pr(s \models A) = \sum_{\widehat{\pi}} \mathbf{P}(\widehat{\pi})$$

where  $\hat{\pi}$  ranges over all finite path prefixes  $s_0 s_1 \dots s_n$  with  $s_0 = s$  and:

- 1.  $trace(s_0 s_1 \dots s_n) = L(s_0) L(s_1) \dots L(s_n) \in \mathcal{L}(\mathcal{A})$ , and
- 2. the length of  $\hat{\pi}$  is minimal, i.e.,  $trace(s_0 s_1 \dots s_i) \notin \mathcal{L}(\mathcal{A})$  for all  $0 \leq i < n$ .





product  $\mathcal{D} \otimes \mathcal{A}$ 

## **Product Markov chain**

Let  $\mathcal{D} = (S, \mathbf{P}, \iota_{\text{init}}, AP, L)$  be a DTMC and  $\mathcal{A} = (Q, 2^{AP}, \delta, q_0, F)$  be a DFA. The *product*  $\mathcal{D} \otimes \mathcal{A}$  is the DTMC:

$$\mathcal{D} \otimes \mathcal{A} = (\mathbf{S} \times \mathbf{Q}, \mathbf{P}', \iota'_{\text{init}}, \{ accept \} \mathcal{L}')$$

where  $L'(\langle s, q \rangle) = \{ accept \}$  if  $q \in F$  and  $L'(\langle s, q \rangle) = \emptyset$  otherwise,  $L': S \times P \longrightarrow P \notin F$ 

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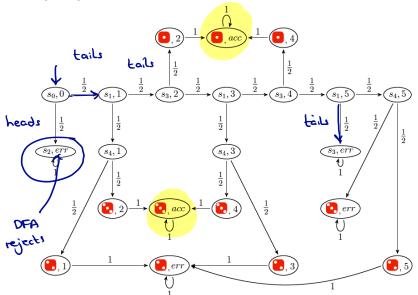
$$\iota'_{\mathrm{init}}(\langle s,q \rangle) = \begin{cases} \iota_{\mathrm{init}}(s) & \text{ if } q = \delta(q_0, L(s)) \\ 0 & \text{ otherwise.} \end{cases}$$

The transition probabilities in  $\mathcal{D} \otimes \mathcal{A}$  are given by:

$$\mathbf{P}'(\langle s, q \rangle, \langle s', q' \rangle) = \begin{cases} \mathbf{P}(s, s') & \text{if } q' = \delta(q, L(s')) \\ 0 & \text{otherwise.} \end{cases}$$

Verifying regular safety properties

## Example product: Knuth-Yao's die



# Product Markov chain

### Some observations

- ▶ For each path  $\pi = s_0 s_1 s_2 \dots$  in DTMC  $\mathcal{D}$  there exists a unique run  $q_0 q_1 q_2 \dots$  in DFA  $\mathcal{A}$  for  $trace(\pi) = L(s_0) L(s_1) L(s_2) \dots$  and  $\pi^+ = \langle s_0, q_1 \rangle \langle s_1, q_2 \rangle \langle s_2, q_3 \rangle \dots$  is a path in  $\mathcal{D} \otimes \mathcal{A}$ .
- The DFA A does not affect the probabilities, i.e., for each measurable set Π of paths in D and state s:

$$Pr_{s}^{\mathcal{D}}(\Pi) = Pr_{\langle s,\delta(q_{0},L(s))\rangle}^{\mathcal{D}\otimes\mathcal{A}} \underbrace{\{\pi^{+} \mid \pi \in \Pi\}}_{\Pi^{+}}$$

For Π = { π ∈ Paths<sup>D</sup>(s) | pref(trace(π)) ∩ L(A) ≠ ∅ }, the set Π<sup>+</sup> is given by:

$$\mathsf{\Pi}^+ \,=\, \{\, \pi^+ \in \mathsf{Paths}^{\mathcal{D}\otimes\mathcal{A}}(\langle s, \delta(q_0, \mathsf{L}(s))\rangle) \,\mid\, \pi^+ \models \Diamond \mathsf{accept}\, \}.$$

Theorem for analysing regular safety properties

Let 
$$P_{safe}$$
 be a regular safety property  $A$  a DFA for the set of bad prefixes  
of  $P_{safe}$ ,  $D$  a DTMC, and  $s$  a state in  $D$ . Then:  
 $Pr^{\mathcal{D}}(s \models P_{safe}) = Pr^{\mathcal{D} \otimes \mathcal{A}}(\langle s, q_s \rangle \not\models \Diamond accept)$   
 $D$  storts in  $s$  in the product  $D \otimes A$   
and satisfies  $P_{safe}$   
 $P$  all bad prefixes of  $P_{safe} = regular$  larguage  
 $= larguage accepted$   
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#### Theorem for analysing regular safety properties

Let  $P_{safe}$  be a regular safety property, A a DFA for the set of bad prefixes of  $P_{safe}$ , D a DTMC, and s a state in D. Then:

$$Pr^{\mathcal{D}}(s \models P_{safe}) = Pr^{\mathcal{D} \otimes \mathcal{A}}(\langle s, q_s \rangle \not\models \Diamond accept)$$
$$= 1 - Pr^{\mathcal{D} \otimes \mathcal{A}}(\langle s, q_s \rangle \models \Diamond accept)$$
$$= \delta(q_0, L(s)).$$



where  $q_s$ 

Theorem for analysing regular safety properties

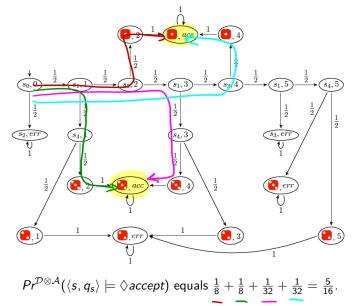
Let  $P_{safe}$  be a regular safety property,  $\mathcal{A}$  DFA for the set of bad prefixes of  $P_{safe}$ ,  $\mathcal{D}$  a DTMC, and s a state in  $\mathcal{D}$ . Then:  $Pr^{\mathcal{D}}(s \models P_{safe}) = Pr^{\mathcal{D} \otimes \mathcal{A}}(\langle s, q_s \rangle \not\models \Diamond accept)$  $= 1 - Pr^{\mathcal{D} \otimes \mathcal{A}}(\langle s, q_s \rangle \models \Diamond accept)$ 

where 
$$q_s = \delta(q_0, L(s))$$
.

#### Remarks

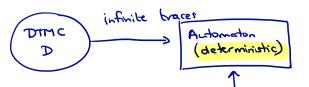
- 1. For finite DTMCs,  $Pr^{\mathcal{D}}(s \models P_{safe})$  can thus be computed by determining reachability probabilities of *accept* states in  $\mathcal{D} \otimes \mathcal{A}$ . This amounts to solving a linear equation system.
- 2. For qualitative regular safety properties, i.e.,  $Pr^{\mathcal{D}}(s \models P_{safe}) > 0$  and  $Pr^{\mathcal{D}}(s \models P_{safe}) = 1$ , a graph analysis of  $\mathcal{D} \otimes \mathcal{A}$  suffices.

### Determining the property's probability



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 $P_r(D \models P)$ 

Modeling and Verification of Probabilistic Systems

### Infinite repetition of languages

Let  $\boldsymbol{\Sigma}$  be a finite alphabet.

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Let  $\Sigma$  be a finite alphabet. For language  $\mathcal{L} \subseteq \Sigma^*$  let  $\mathcal{L}^{\omega}$  be the set of words in  $\Sigma^* \cup \Sigma^{\omega}$  that arise from the infinite concatenation of (arbitrary) words in  $\Sigma$ ,

abe, abb, acceb e E\*

acabaab aaob. ( aaob)

Z = {a,b,c}

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#### $\omega$ -regular expression

An  $\omega$ -regular expression G over the  $\Sigma$  has the form:  $G = E_1.F_1^{\omega} + \ldots + E_n.F_n^{\omega}$ where  $n \ge 1$  and  $E_1, \ldots, E_n, F_1, \ldots, F_n$  are regular expressions over  $\Sigma$  such that  $\varepsilon \notin \mathcal{L}(F_i)$ , for all  $1 \le i \le n$ .  $E_1 \cdot F_1^{\omega} + E_2 \cdot F_2^{\omega} + \cdots + E_n \cdot F_n^{\omega}$ regular expressions for  $\varepsilon$  and  $\varepsilon$  and

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The semantics of G is defined by  $\mathcal{L}_{\omega}(G) = \mathcal{L}(E_1).\mathcal{L}(F_1)^{\omega} \cup \ldots \cup \mathcal{L}(E_n).\mathcal{L}(F_n)^{\omega}$ where  $\mathcal{L}(E) \subseteq \Sigma^*$  denotes the language (of finite words) induced by the regular expression E.

#### 

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#### Example

Examples for  $\omega$ -regular expressions over the alphabet  $\Sigma = \{A, B, C\}$  are  $\underbrace{(A+B)^*A(AAB+C)^{\omega}}_{n=1} \text{ or } A(B+C)^*A^{\omega} + B(A+C)^{\omega}.$   $F_1 = (A+B)^* \cdot A$   $F_1 = AAB+C$ 

Modeling and Verification of Probabilistic Systems

#### $\omega$ -regular property

<u>LT property</u> *P* over *AP* is called  $\omega$ -regular if  $P = \mathcal{L}_{\omega}(G)$  for some  $\omega$ -regular expression G over the alphabet  $2^{AP}$ .

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• always *a*, i.e.,  $(\{a\} + \{a, b\})^{\omega}$ .

10]+20,6]

 $\mathbf{F}' \cdot \mathbf{F}'$ 

5

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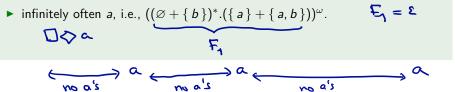
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- infinitely often a, i.e.,  $((\emptyset + \{b\})^* . (\{a\} + \{a, b\}))^{\omega}$ .
- ▶ from some moment on, always *a*, i.e.,  $(2^{AP})^* \cdot (\{a\} + \{a, b\})^{\omega}$ .

Olla

#### $\omega$ -regular property

LT property *P* over *AP* is called  $\omega$ -regular if  $P = \mathcal{L}_{\omega}(G)$  for some  $\omega$ -regular expression G over the alphabet  $2^{AP}$ .

#### Example

Any regular safety property  $P_{safe}$  is an  $\omega$ -regular property. This follows from the fact that the complement language  $(2^{AP})^{\omega} \setminus P_{safe} = \underbrace{BadPref(P_{safe})}_{\text{regular}} \cdot \underbrace{(2^{AP})^{\omega}}_{\text{regular}}$ 

is an  $\omega$ -regular language, and  $\omega$ -regular languages are closed under complement.

#### $\omega$ -regular property

LT property *P* over *AP* is called  $\omega$ -regular if  $P = \mathcal{L}_{\omega}(G)$  for some  $\omega$ -regular expression G over the alphabet  $2^{AP}$ .

### $\omega$ -regular property

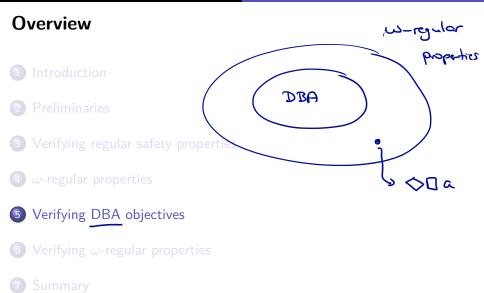
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#### Example

Starvation freedom in the sense of "whenever process  $\mathcal P$  is waiting then it will enter its critical section eventually" is an  $\omega$ -regular property as it can be described by

$$\left((\neg \textit{wait})^*.\textit{wait}.\mathsf{true}^*.\textit{crit}
ight)^\omega \ + \ \left((\neg \textit{wait})^*.\textit{wait}.\mathsf{true}^*.\textit{crit}
ight)^*.(\neg \textit{wait})^\omega$$

Intuitively, the first summand stands for the case where  $\mathcal{P}$  requests and enters its critical section infinitely often, while the second summand stands for the case where  $\mathcal{P}$  is in its waiting phase only finitely many times.



### Deterministic Büchi automata

### Deterministic Büchi automata

### Deterministic Büchi Automaton (DBA)

A deterministic Büchi automaton (DBA)  $\mathcal{A} = (Q, \Sigma, \delta, q_0, F)$  with

- Q is a finite set of states with initial state  $q_0 \in Q_0$ ,  $\gamma$
- Σ is an alphabet,
- $\delta: Q \times \Sigma \to Q$  is a transition function,

•  $F \subseteq Q$  is a set of *accept* (or: final) states.

A *run* for  $\sigma = A_0 A_1 A_2 \ldots \in \Sigma^{\omega}$  denotes an infinite sequence  $q_0 q_1 q_2 \ldots$  of states in  $\mathcal{A}$  such that  $q_0 \in Q_0$  and  $q_i \xrightarrow{A_i} q_{i+1}$  for  $i \ge 0$ .

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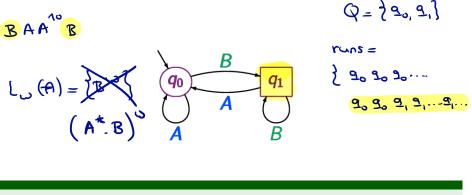
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Run  $q_0 q_1 q_2 \dots$  is accepting if  $q_i \in F$  for infinitely many indices  $i \in \mathbb{N}$ . The infinite *language* of  $\mathcal{A}$  is

 $\mathcal{L}_{\omega}(\mathcal{A}) = \{ \sigma \in \Sigma^{\omega} \mid \text{there exists an accepting run for } \sigma \text{ in } \mathcal{A} \}.$ 

Verifying DBA objectives

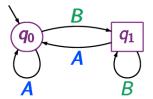
### Deterministic Büchi automata for LT properties



DBA over 
$$\{A, B\}$$
 with  $F = \{q_1\}$  and initial state  $q_0$   
=  $\Sigma$ 

Verifying DBA objectives

### Deterministic Büchi automata for LT properties

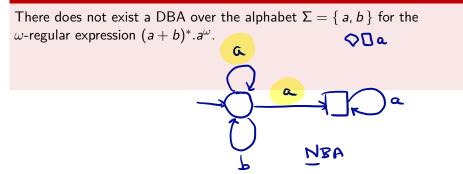


DBA over { A, B } with  $F = \{q_1\}$  and initial state  $q_0$  accepting the LT property "infinitely often B".

### Some facts about DBA

#### **Expressiveness of DBA**

For any DBA  $\mathcal{A}$ , the language  $\mathcal{L}_{\omega}(\mathcal{A})$  is  $\omega$ -regular.



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There does not exist a DBA over the alphabet  $\Sigma = \{a, b\}$  for the  $\omega$ -regular expression  $(a + b)^* . a^{\omega}$ .

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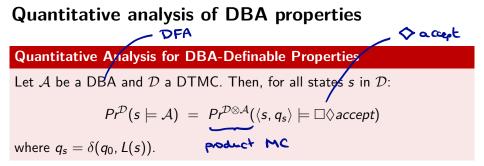
The class of DBA-recognizable languages is a proper subclass of the class of  $\omega$ -regular languages and is not closed under complementation.

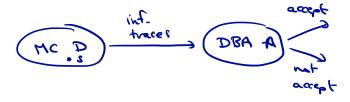
An  $\omega$ -language is recognizable by a DBA iff it is the limit language of a regular language. (Details: see lecture Applications of Automata Theory.)

let L E E\* for alphabet E we Z is in the Limit of L if and any if  $|pref(w) \cap L| = 00$ Thus: for arbitrary n, there is a UEL such that [u]>n with u & pref (w) L = L (A) for some DBA A lemna if and only if L is the <u>Limit</u> of some regular lay. Proof: let A be a DBA and A' the corresponding DFA. Claim thy (A) = limit of h (A'). WE ZW is accepted by DBA A iff some final state in A is visited infinitely often. This holds iff to many prefixes of w are accepted by A'. Here,  $h_{\omega}(A) = limit of <math>h(A')$  $\boxtimes$ 

### Quantitative analysis of DBA properties

Verifying DBA objectives





## Quantitative analysis of DBA properties

### **Quantitative Analysis for DBA-Definable Properties**

Let  $\mathcal{A}$  be a DBA and  $\mathcal{D}$  a DTMC. Then, for all states s in  $\mathcal{D}$ :

$$Pr^{\mathcal{D}}(s \models \mathcal{A}) = Pr^{\mathcal{D}\otimes\mathcal{A}}(s, q_s) \models \Box \Diamond accept)$$
  
where  $q_s = \delta(q_0, L(s))$ .

#### Algorithm

Recall that for finite DTMCs, the probability of  $\Box \Diamond accept$  can be obtained in polynomial time by first determining the BSCCs of  $\mathcal{D} \otimes \mathcal{A}$ .

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.

≥ 1 accept state.

#### Algorithm

Recall that for finite DTMCs, the probability of  $\Box \Diamond accept$  can be obtained in polynomial time by first determining the BSCCs of  $\mathcal{D} \otimes \mathcal{A}$ . For each BSCC *B* that contains a state  $\langle s, q \rangle$  with  $q \in F$ , determine the probability of eventually reaching *B*. Its sum is the required probability. Thus this amounts to solve a linear equation system for each accepting BSCC in  $\mathcal{D}$ .

## Overview

- Introduction
- 2 Preliminaries
- 3 Verifying regular safety properties
- $\Phi$   $\omega$ -regular properties

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- 5 Verifying DBA objectives
- 6 Verifying  $\omega$ -regular properties
  - 7 Summary

## **Beyond DBA properties**

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#### Remarks

- Since DBAs do not have the full power of ω-regular languages, this approach is not capable of handling arbitrary ω-regular properties.
- To overcome this deficiency, Büchi automata will be replaced by an alternative automaton model for which their deterministic counterparts are as expressive as ω-regular languages.
- Such automata have the same components as DBA (finite set of states, and so on) except for the acceptance sets. We consider *deterministic Rabin automata*.

alternative Muller/ Street

# **Beyond DBA properties**

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- Such automata have the same components as DBA (finite set of states, and so on) except for the acceptance sets. We consider *deterministic Rabin automata*. There are alternatives, e.g., Muller automata.
- Determinism is important to stay within the realm of Markov chains; a product of an MC with a deterministic automaton yields a MC.

Michael Robin

- \$ F = 2 × 2

## Deterministic Rabin automata

#### Deterministic Rabin automaton

A deterministic Rabin automaton (DRA)  $\mathcal{A} = (Q, \Sigma, \delta, q_0, \mathcal{F})$  with

- ▶ Q,  $q_0 \in Q_0$ ,  $\Sigma$  is an alphabet, and  $\delta: Q imes \Sigma o Q$  as before
- ▶  $\mathcal{F} = \{ (L_i, K_i) \mid 0 < i \leq k \}$  with  $L_i, K_i \subseteq Q$ , is a set of *accept pairs*

A *run* for  $\sigma = A_0 A_1 A_2 \ldots \in \Sigma^{\omega}$  denotes an infinite sequence  $q_0 q_1 q_2 \ldots$  of states in  $\mathcal{A}$  such that  $q_0 \in Q_0$  and  $q_i \xrightarrow{A_i} q_{i+1}$  for  $i \ge 0$ .

Run  $q_0 q_1 q_2 \dots$  is *accepting* if for some pair  $(L_i, K_i)$ , the states in  $L_i$  are visited finitely often and the states in  $K_i$  infinitely often. That is, an accepting run should satisfy

## When does a DRA accept an infinite word?

#### Acceptance condition

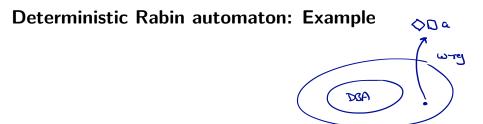
A run of a word in  $\Sigma^{\omega}$  on a DRA is accepting if and only if: for some  $(L_i, K_i) \in \mathcal{F}$ , the states in  $L_i$  are visited finitely often and (some of) the states in  $K_i$  are visited infinitely often

Stated in terms of an LTL formula:

$$\bigvee_{0 < i \leq k} (\Diamond \Box \neg L_i \land \Box \Diamond K_i)$$

A deterministic Büchi automaton is a DRA with acceptance condition  $\{(\emptyset, F)\}$ .

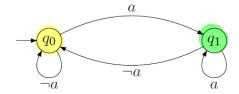
Verifying  $\omega$ -regular properties



### Deterministic Rabin automaton: Example

#### Acceptance condition

A run of a word in  $\Sigma^{\omega}$  on a DRA is accepting iff  $\bigvee_{0 < i \leq k} (\Diamond \Box \neg L_i \land \Box \Diamond K_i)$ .

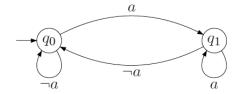


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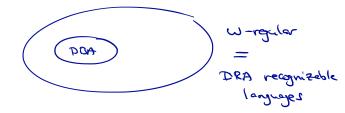
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Recall that there does not exist a deterministic Büchi automaton for  $\Diamond \Box a$ .

Joost-Pieter Katoen

#### DRA are $\omega$ -regular

A language on infinite words is  $\omega$ -regular iff there exists a DRA that generates it.



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A language on infinite words is  $\omega$ -regular iff there exists a DRA that generates it.

- ► DRA are thus equally expressive as nondeterministic Büchi automata.
- They are more expressive than deterministic Büchi automata.
- ► Any nondeterministic Büchi automata of *n* states can be converted to a DRA of size 2<sup>O(n log n)</sup>. (Details omitted.)

#### Product of a Markov chain and a DRA

The product of DTMC  ${\cal D}$  and DRA  ${\cal A}$  is defined as the product of a Markov chain and a DFA, except that the labeling is defined differently.

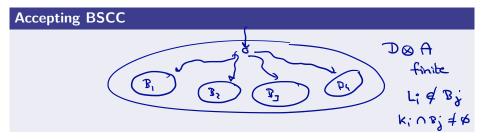
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gely then by E L'((S, 9))

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### Accepting BSCC

A BSCC T in  $\mathcal{D} \otimes \mathcal{A}$  is *accepting* iff for some index  $i \in \{1, ..., k\}$  we have:

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Let  $\mathcal{D}$  be a finite DTMC, s a state in  $\mathcal{D}$ ,  $\mathcal{A}$  a DRA, and let U be the union of all accepting BSCCs in  $\mathcal{D} \otimes \mathcal{A}$ .



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$$\mathsf{Pr}^{\mathcal{D}}(s\models\mathcal{A}) = \mathsf{Pr}^{\mathcal{D}\otimes\mathcal{A}}(\langle s,q_s
angle\models\Diamond oldsymbol{U}) \quad ext{where} \quad q_s=\delta(q_0,L(s)).$$

#### Proof

#### On the blackboard (if time permits).

Joost-Pieter Katoen

## Verifying DRA objectives

# Verifying DRA objectives

#### DRA probabilities = reachability probabilities

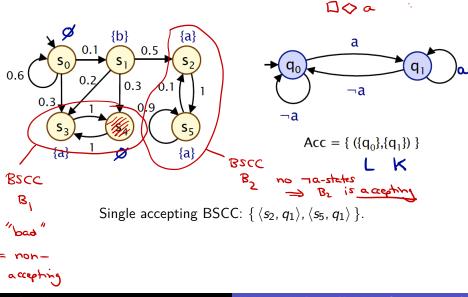
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$$Pr^{\mathcal{D}}(s \models \mathcal{A}) = Pr^{\mathcal{D} \otimes \mathcal{A}}(\langle s, q_s \rangle \models \Diamond U) \text{ where } q_s = \delta(q_0, L(s)).$$

Probabilities for satisfying  $\omega$ -regular properties are obtained by computing the reachability probabilities for accepting BSCCs in  $\mathcal{D} \otimes \mathcal{A}$ . Again, a graph analysis and solving systems of linear equations suffice. The time complexity is polynomial in the size of  $\mathcal{D}$  and  $\mathcal{A}$ .

Verifying  $\omega$ -regular properties

## Example: verifying a DTMC versus a DRA

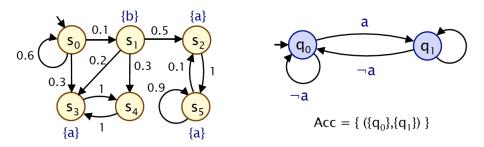


Joost-Pieter Katoen

Verifying  $\omega$ -regular properties

# Example: verifying a DTMC versus a DRA

Ø∏a



Single accepting BSCC: 
$$\{ \langle s_2, q_1 \rangle, \langle s_5, q_1 \rangle \}$$
.  
Reachability probability is  $\frac{1}{2} \cdot \frac{1}{10} \cdot \sum_{k=0}^{\infty} \left(\frac{3}{5}\right)^k = \frac{1}{8}$ .

Measurability theorem for  $\omega$ -regular properties

[Vardi 1985]

For any DTMC  ${\mathcal D}$  and DRA  ${\mathcal A}$  the set

$$\{\pi \in \mathsf{Paths}(\mathcal{D}) \mid \mathsf{trace}(\pi) \in \mathcal{L}_\omega(\mathcal{A})\}$$

is measurable.

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Let DRA  $\mathcal{A}$  with accept sets {  $(L_1, K_1), \ldots, (L_m, K_m)$  }. Let  $\varphi_i = \Diamond \Box \neg L_i \land \Box \Diamond K_i$  and  $\Pi_i$  the set of paths satisfying  $\varphi_i$ .

Measurability theorem for  $\omega$ -regular properties

[Vardi 1985]

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Joost-Pieter Katoen

### Linear temporal logic

## Linear temporal logic

### Linear Temporal Logic: Syntax

[Pnueli 1977]

LTL formulas over the set AP obey the grammar:

$$\varphi ::= \mathbf{a} \mid \neg \varphi \mid \varphi_1 \land \varphi_2 \mid \bigcirc \varphi \mid \varphi_1 \, \mathsf{U} \, \varphi_2$$

where  $a \in AP$  and  $\varphi$ ,  $\varphi_1$ , and  $\varphi_2$  are LTL formulas.

#### Example

On the blackboard.

# LTL semantics

### LTL semantics

The LT-property induced by LTL formula  $\varphi$  over AP is:

$$Words(\varphi) = \left\{ \sigma \in \left(2^{AP}\right)^{\omega} \mid \sigma \models \varphi \right\}, \text{ where } \models \text{ is the smallest relation satisfying}$$

$$\underbrace{\mathsf{set of}}_{\mathsf{traces}} \quad \underbrace{\mathsf{traces}}_{\mathsf{schisfynj}} \quad \Psi$$

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$$\sigma \models \text{ true}$$

$$\sigma \models a \quad \text{iff} \quad a \in A_0 \quad (\text{i.e., } A_0 \models a)$$

$$\sigma \models \varphi_1 \land \varphi_2 \quad \text{iff} \quad \sigma \models \varphi_1 \text{ and } \sigma \models \varphi_2$$

$$\sigma \models \neg \varphi \quad \text{iff} \quad \sigma \not\models \varphi$$

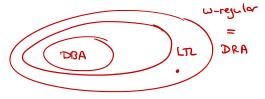
$$\sigma \models \bigcirc \varphi \quad \text{iff} \quad \sigma^1 = A_1 A_2 A_3 \dots \models \varphi$$

$$\sigma \models \varphi_1 \cup \varphi_2 \quad \text{iff} \quad \exists j \ge 0. \ \sigma^j \models \varphi_2 \text{ and } \sigma^i \models \varphi_1, \ 0 \le i < j$$

$$\sigma = A_0 A_1 A_2 \dots \text{ we have } \sigma^i = A_i A_{i+1} A_{i+2} \dots \text{ is the suffix of } \sigma \text{ from index } i \text{ on.}$$

for

## Some facts about LTL



#### LTL is $\omega$ -regular

For any LTL formula  $\varphi$ , the set  $Words(\varphi)$  is an  $\omega$ -regular language.

### LTL are DRA-definable

For any LTL formula  $\varphi$ , there exists a DRA  $\mathcal{A}$  such that  $\mathcal{L}_{\omega} = \mathit{Words}(\varphi)$ 

## Some facts about LTL

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For any LTL formula  $\varphi$ , the set  $Words(\varphi)$  is an  $\omega$ -regular language.

#### LTL are DRA-definable

For any LTL formula  $\varphi$ , there exists a DRA  $\mathcal{A}$  such that  $\mathcal{L}_{\omega} = Words(\varphi)$  where the number of states in  $\mathcal{A}$  lies in  $2^{2^{|\varphi|}}$ .

# Verifying a DTMC against LTL formulas

#### Complexity of LTL model checking

#### [Vardi 1985]

The qualitative model-checking problem for finite DTMCs against LTL formula  $\varphi$  is PSPACE-complete, i.e., verifying whether  $Pr(s \models \varphi) > 0$  or  $Pr(s \models \varphi) = 1$  is PSPACE-complete.

Recall that the LTL model-checking problem for finite transition systems is PSPACE-complete.

# Overview

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- Overifying regular safety properties
- 4  $\omega$ -regular properties
- 5 Verifying DBA objectives
- 6 Verifying  $\omega$ -regular properties

### Summary

# Summary

#### Summary

- Verifying a DTMC D against a DFA A, i.e., determining Pr(D ⊨ A), amounts to computing reachability probabilities of accept states in D ⊗ A.
- For DBA objectives, the probability of infinitely often visiting an accept state in  $\mathcal{D}\otimes \mathcal{A}$ .
- **DBA** are strictly less powerful than  $\omega$ -regular languages.
- Deterministic Rabin automata are as expressive as  $\omega$ -regular languages.
- Verifying DTMC D agains DRA A amounts to computing reachability probabilities of accepting BSCCs in D ⊗ A.

#### Take-home message

Model checking a DTMC against various automata models reduces to computing reachability probabilities in a product.