



Parameter Synthesis in Markov Chains: The Why and How?

Sebastian Junges

Last Lecture Modelling and Verification of Probabilistic Systems

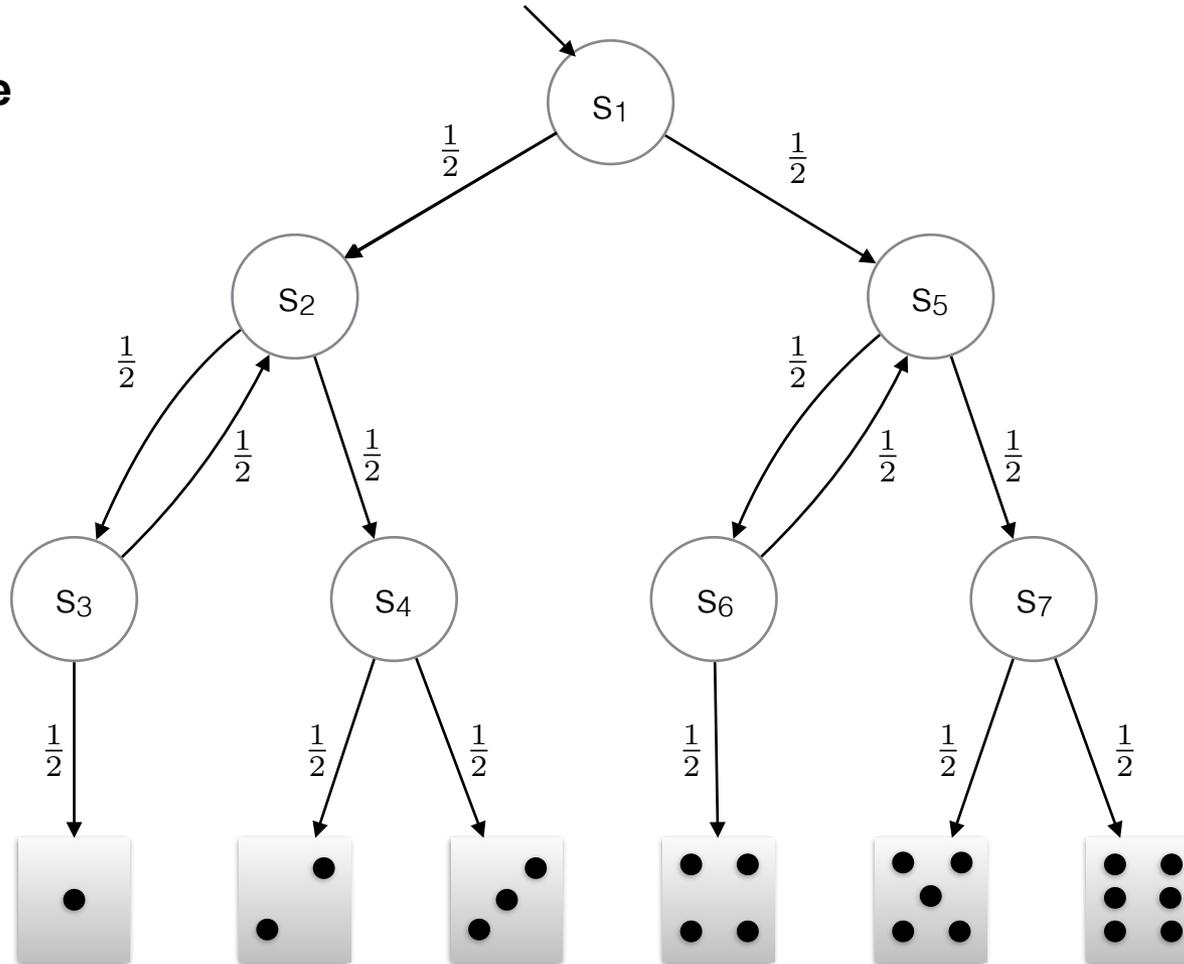
Including work with and by:

Erika Abraham, Christel Baier, Bernd Becker, Harold Brientjes, Florian Corzilius, Murat Cubuktepe, Christian Dehnert, Nils Jansen, Joost-Pieter Katoen, Joachim Klein, Lisa Hutschenreiter, Ufuk Topcu, Tim Quatmann, Matthias Volk, Leonore Winterer, Ralf Wimmer

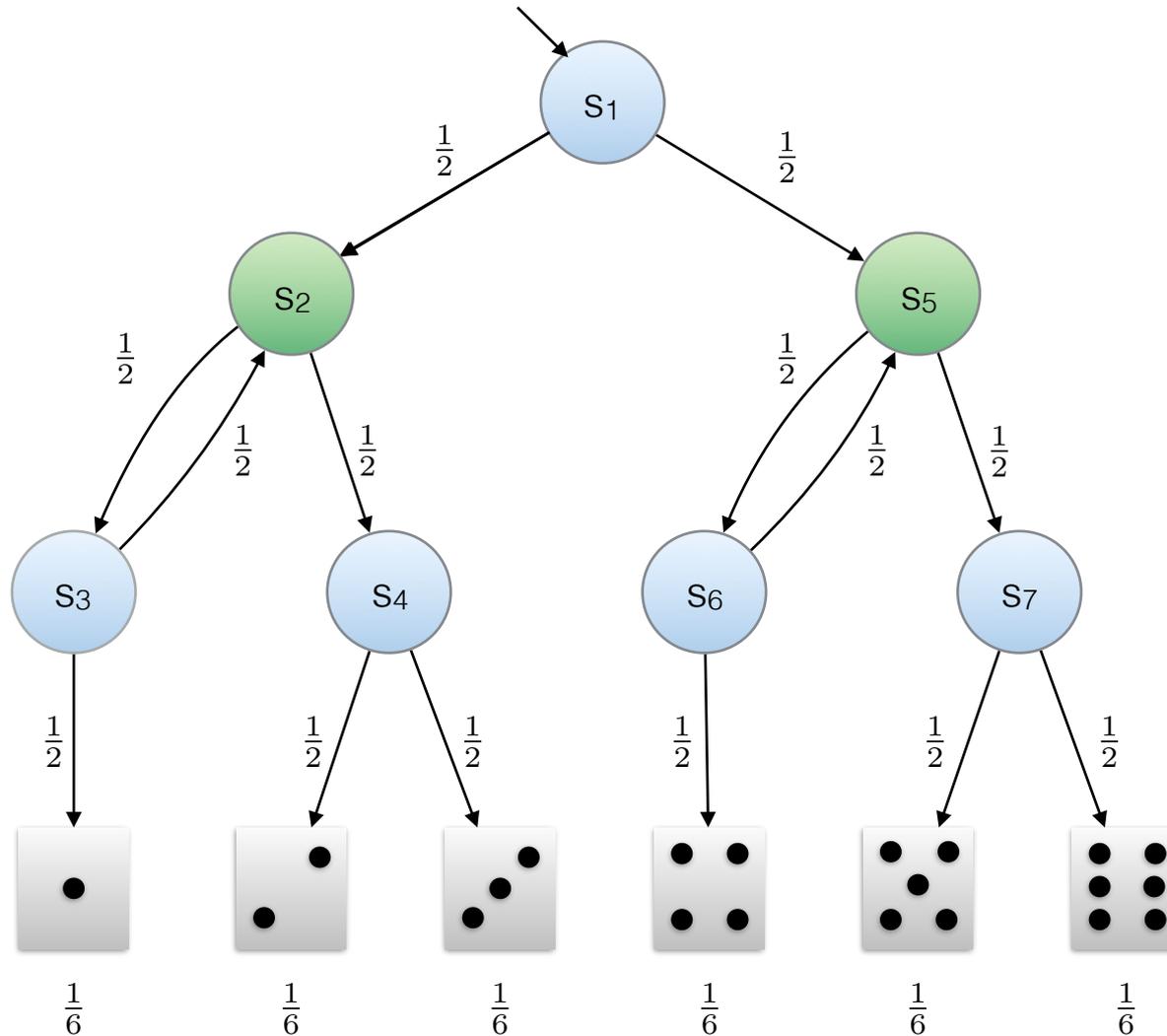


parametric Markov Chains (pMCs)

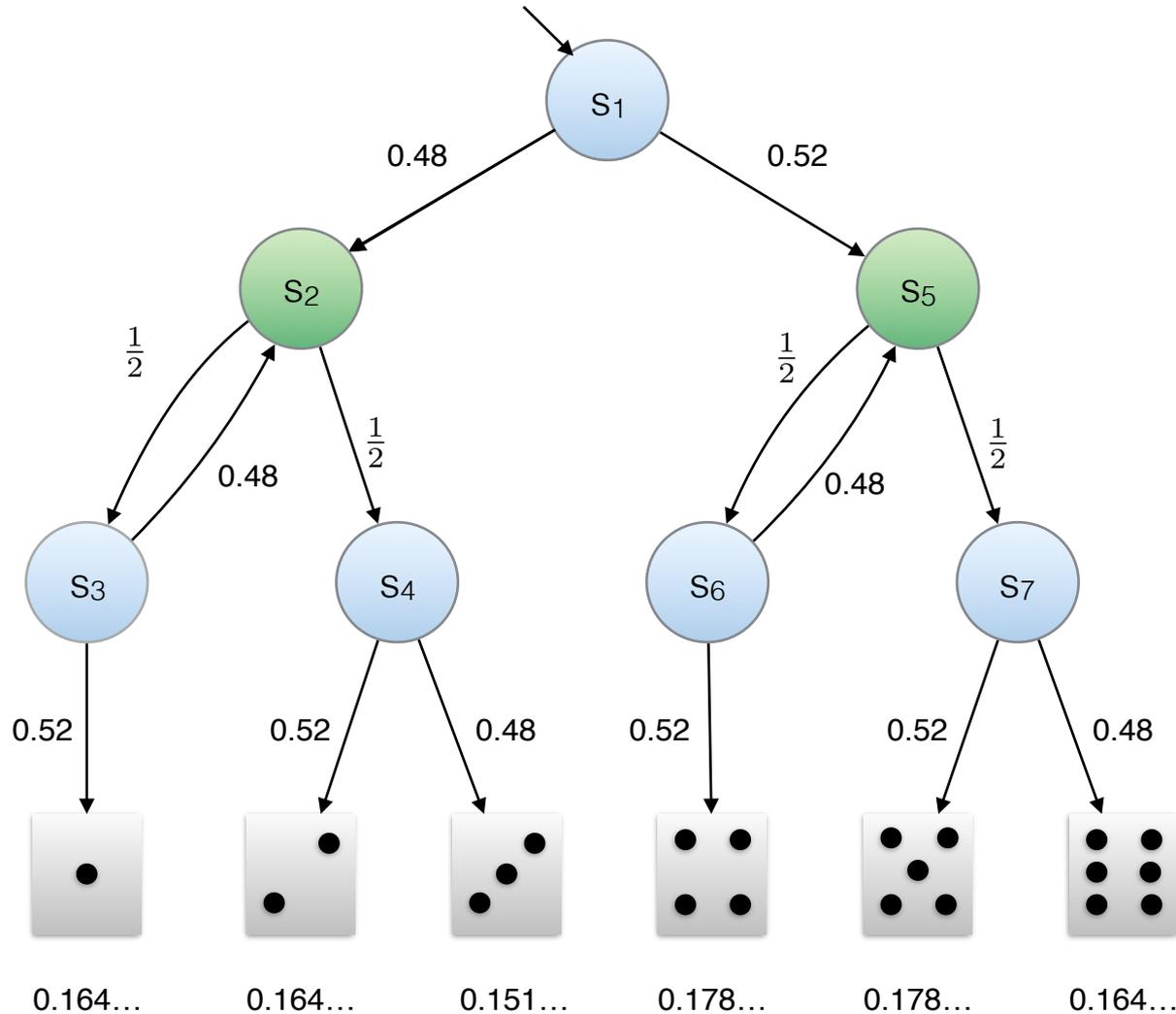
Knuth-Yao Die



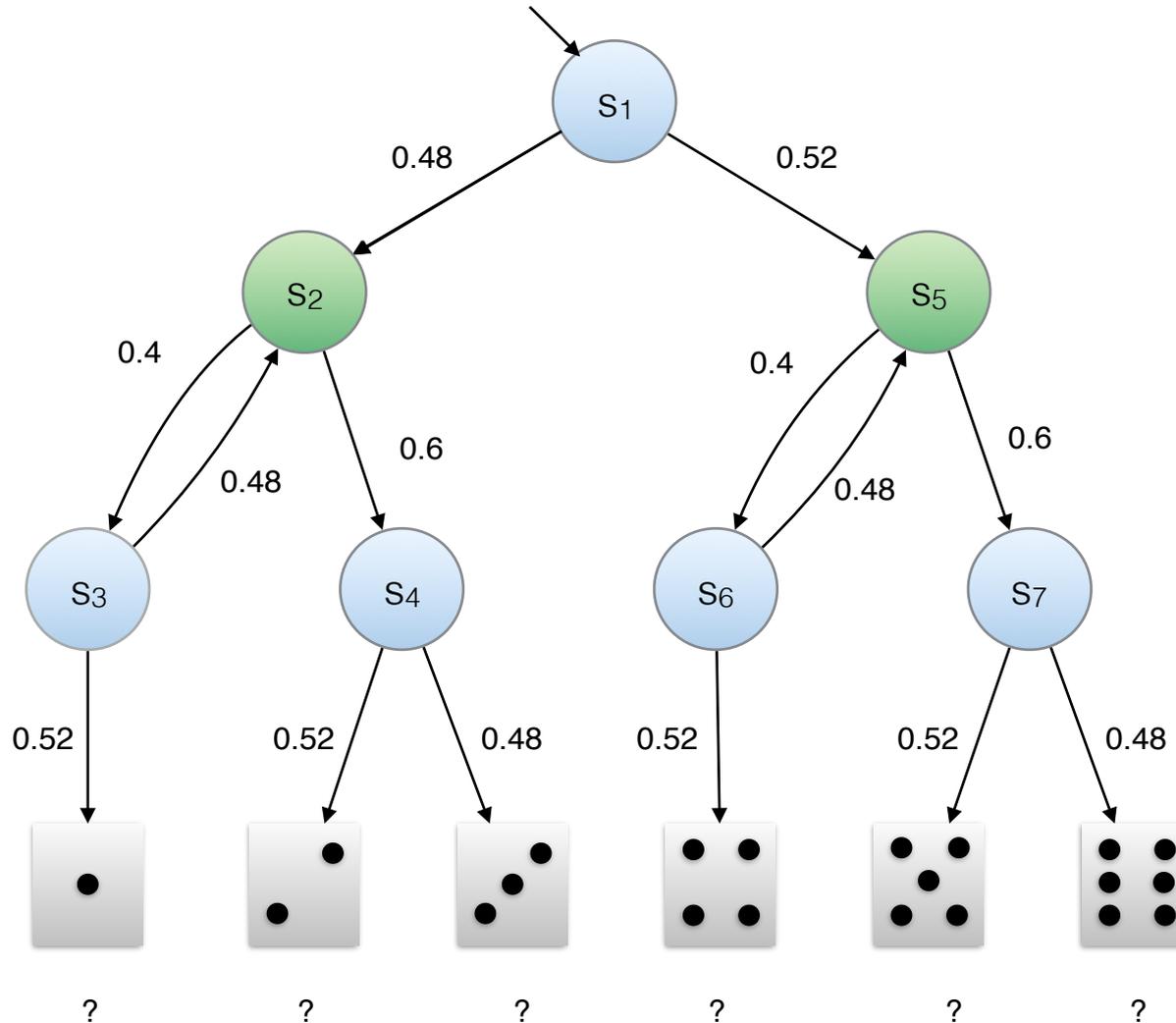
Knuth-Yao Die



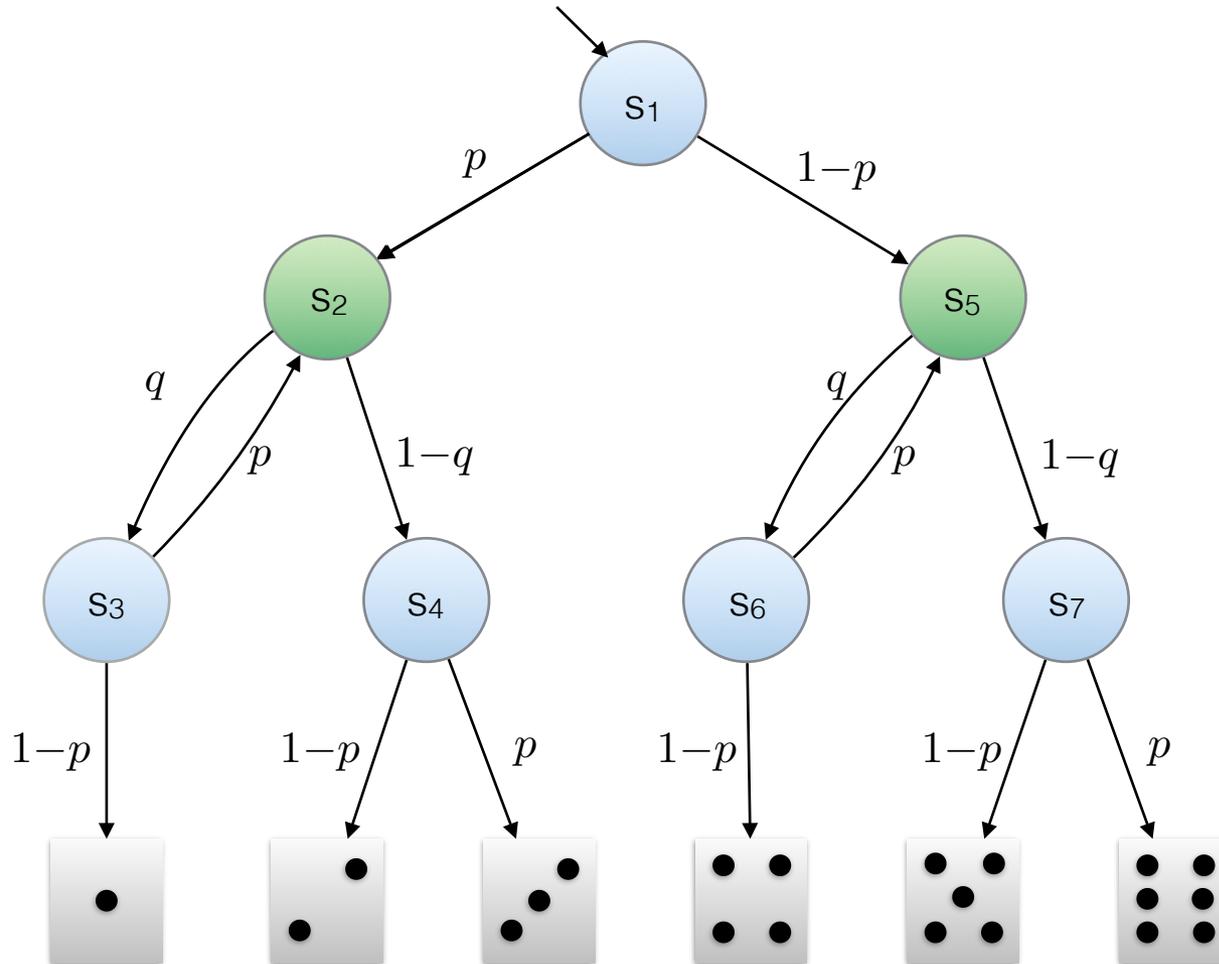
Knuth-Yao Die



Knuth-Yao Die



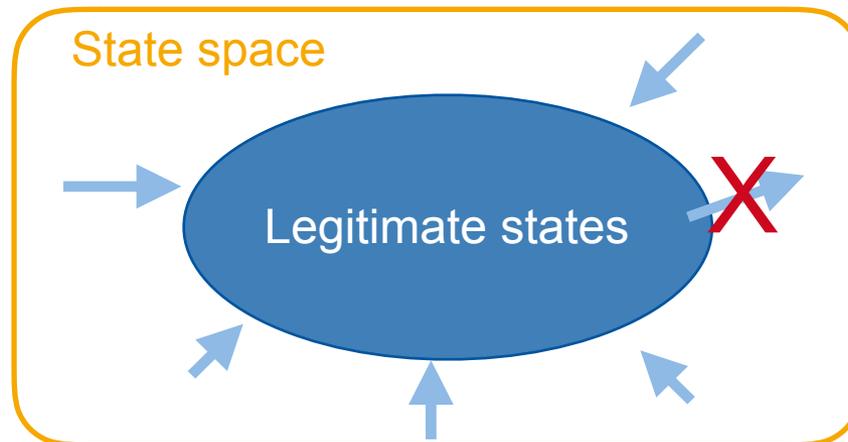
Knuth-Yao Die



Self-stabilizing algorithms

A distributed system is **self-stabilizing** iff it satisfies:

1. **Convergence (recovery)**: Starting from any arbitrary state, it **always reaches a legitimate state** in a finite number of steps, and
2. **Closure**: It **remains in legitimate states** in the absence of faults

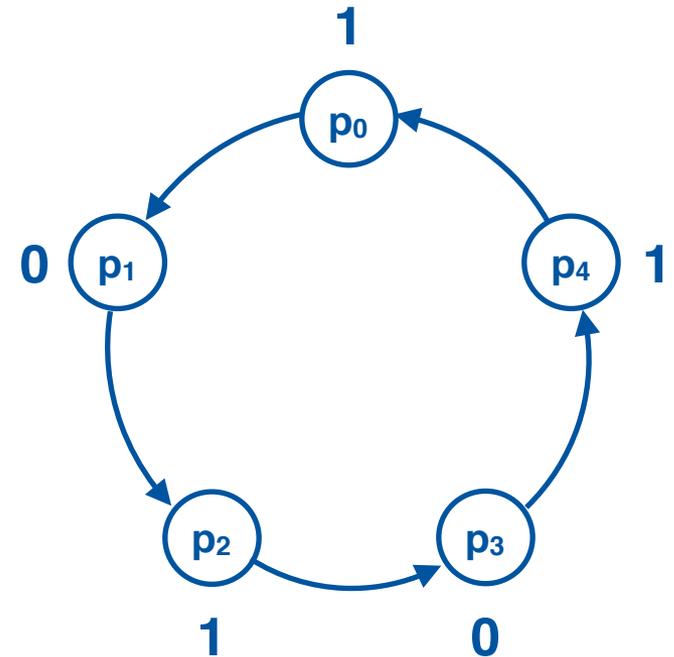


Herman's randomized self-stabilizing algorithm

Token in x_i , if $x_i = x_{i-1}$

$x_i \neq x_{i-1} \rightarrow x_i := x_{i-1}$

$x_i = x_{i-1} \rightarrow \begin{cases} p : & x_i := 0 \\ 1 - p : & x_i := 1 \end{cases}$



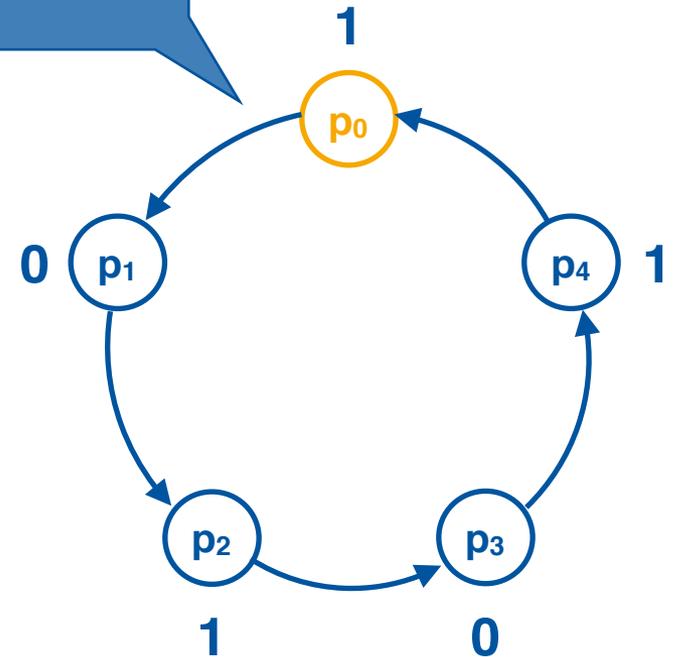
Herman's randomized self-stabilizing algorithm

Token in x_i , if $x_i = x_{i-1}$

$x_i \neq x_{i-1} \rightarrow x_i := x_{i-1}$

$x_i = x_{i-1} \rightarrow \begin{cases} p : & x_i := 0 \\ 1 - p : & x_i := 1 \end{cases}$

Legitimate state:
exactly 1 token

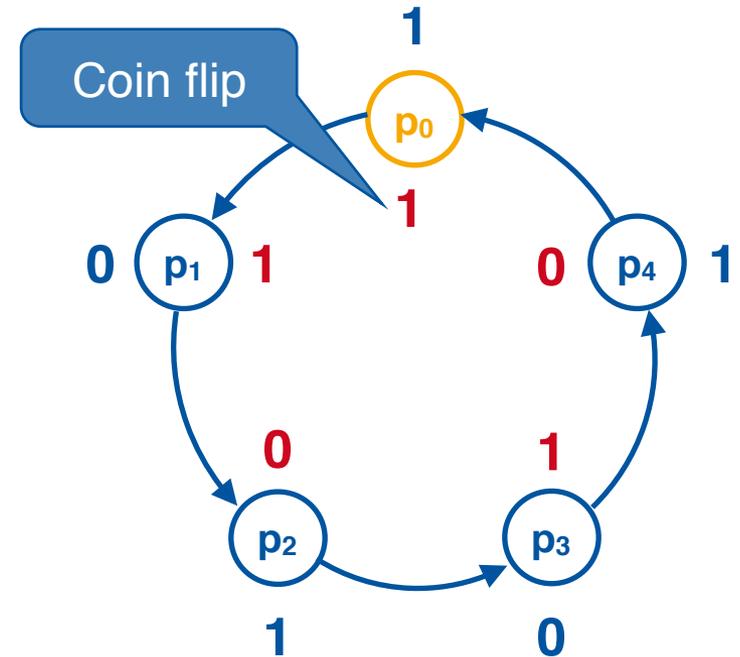


Herman's algorithm

Token in x_i , if $x_i = x_{i-1}$

$x_i \neq x_{i-1} \rightarrow x_i := x_{i-1}$

$x_i = x_{i-1} \rightarrow \begin{cases} p : & x_i := 0 \\ 1 - p : & x_i := 1 \end{cases}$

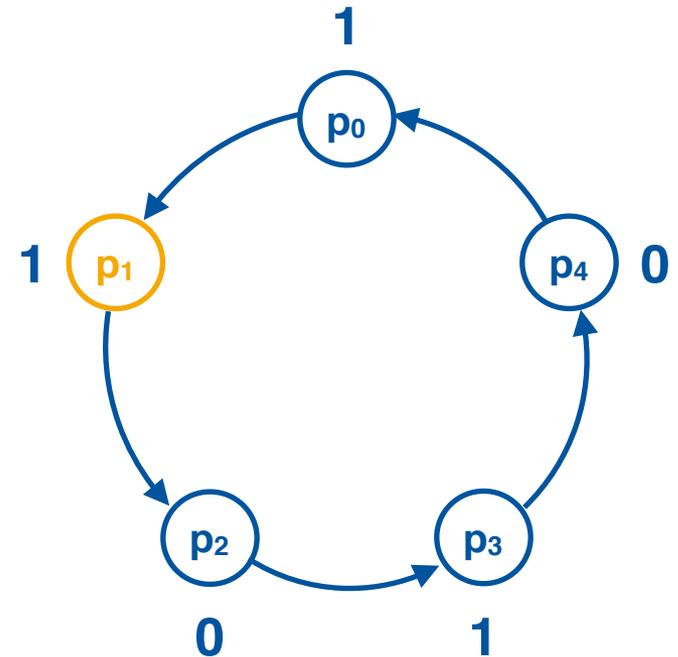


Herman's algorithm

Token in x_i , if $x_i = x_{i-1}$

$x_i \neq x_{i-1} \rightarrow x_i := x_{i-1}$

$x_i = x_{i-1} \rightarrow \begin{cases} p : & x_i := 0 \\ 1 - p : & x_i := 1 \end{cases}$

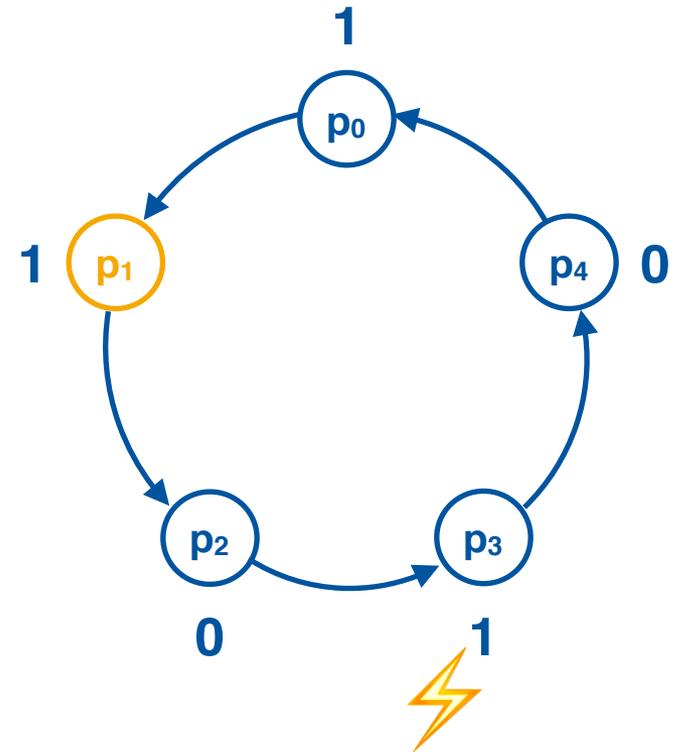


Recovery

Token in x_i , if $x_i = x_{i-1}$

$x_i \neq x_{i-1} \rightarrow x_i := x_{i-1}$

$x_i = x_{i-1} \rightarrow \begin{cases} p : & x_i := 0 \\ 1 - p : & x_i := 1 \end{cases}$

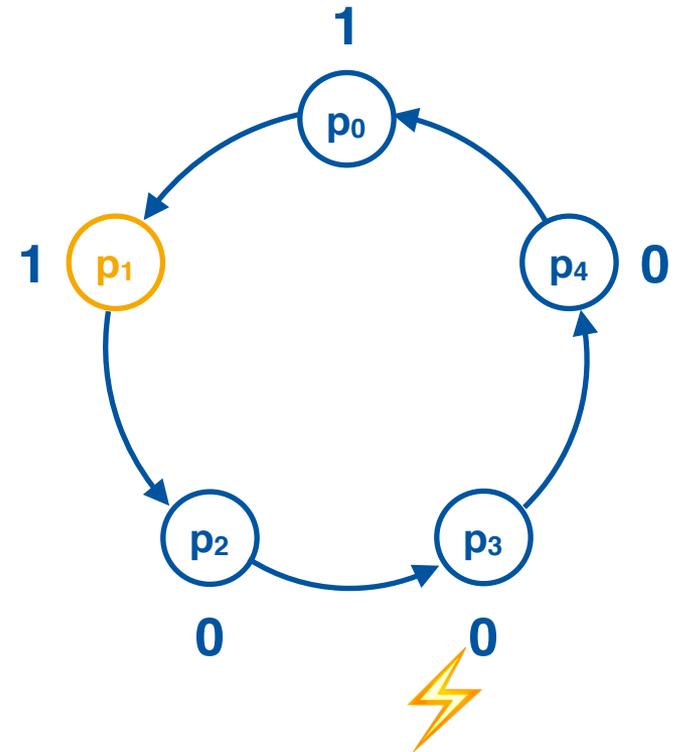


Recovery

Token in x_i , if $x_i = x_{i-1}$

$x_i \neq x_{i-1} \rightarrow x_i := x_{i-1}$

$x_i = x_{i-1} \rightarrow \begin{cases} p : & x_i := 0 \\ 1 - p : & x_i := 1 \end{cases}$



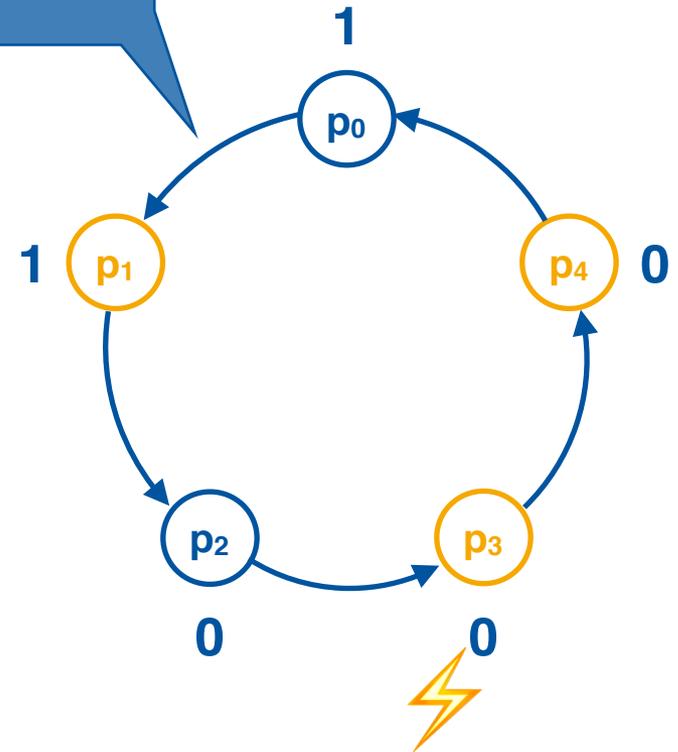
Recovery

Token in x_i , if $x_i = x_{i-1}$

$x_i \neq x_{i-1} \rightarrow x_i := x_{i-1}$

$x_i = x_{i-1} \rightarrow \begin{cases} p : & x_i := 0 \\ 1 - p : & x_i := 1 \end{cases}$

No legitimate state:
3 tokens

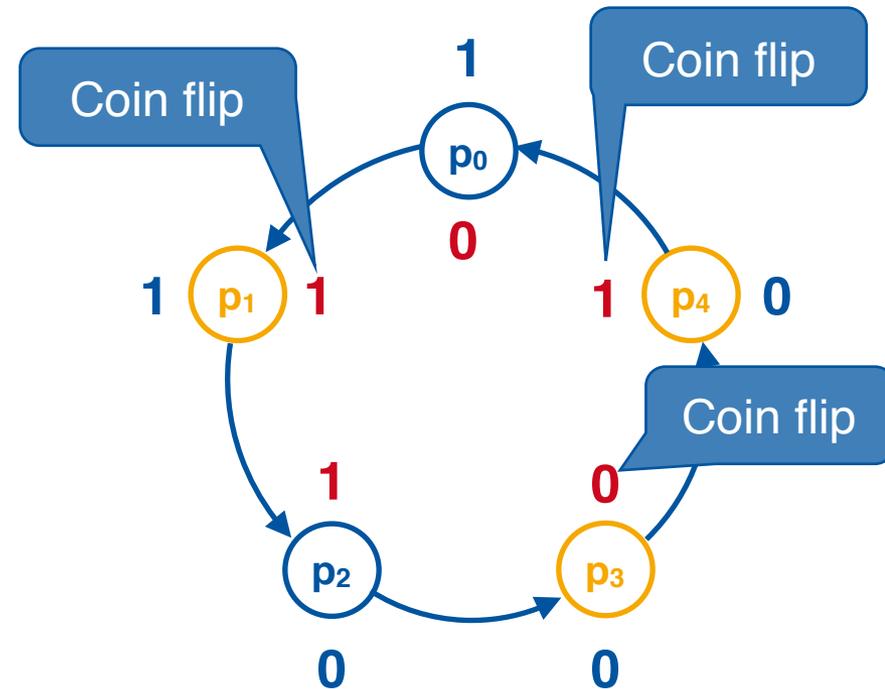


Recovery

Token in x_i , if $x_i = x_{i-1}$

$x_i \neq x_{i-1} \rightarrow x_i := x_{i-1}$

$x_i = x_{i-1} \rightarrow \begin{cases} p : & x_i := 0 \\ 1 - p : & x_i := 1 \end{cases}$

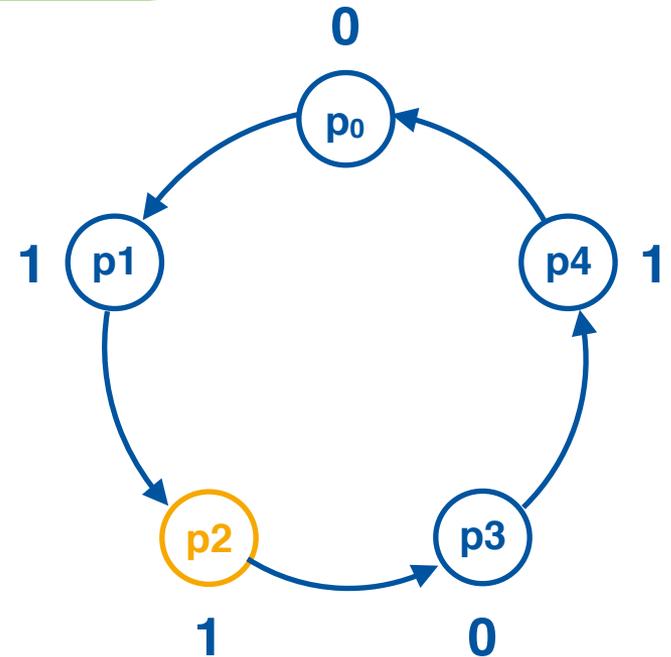


Self-Stabilizing

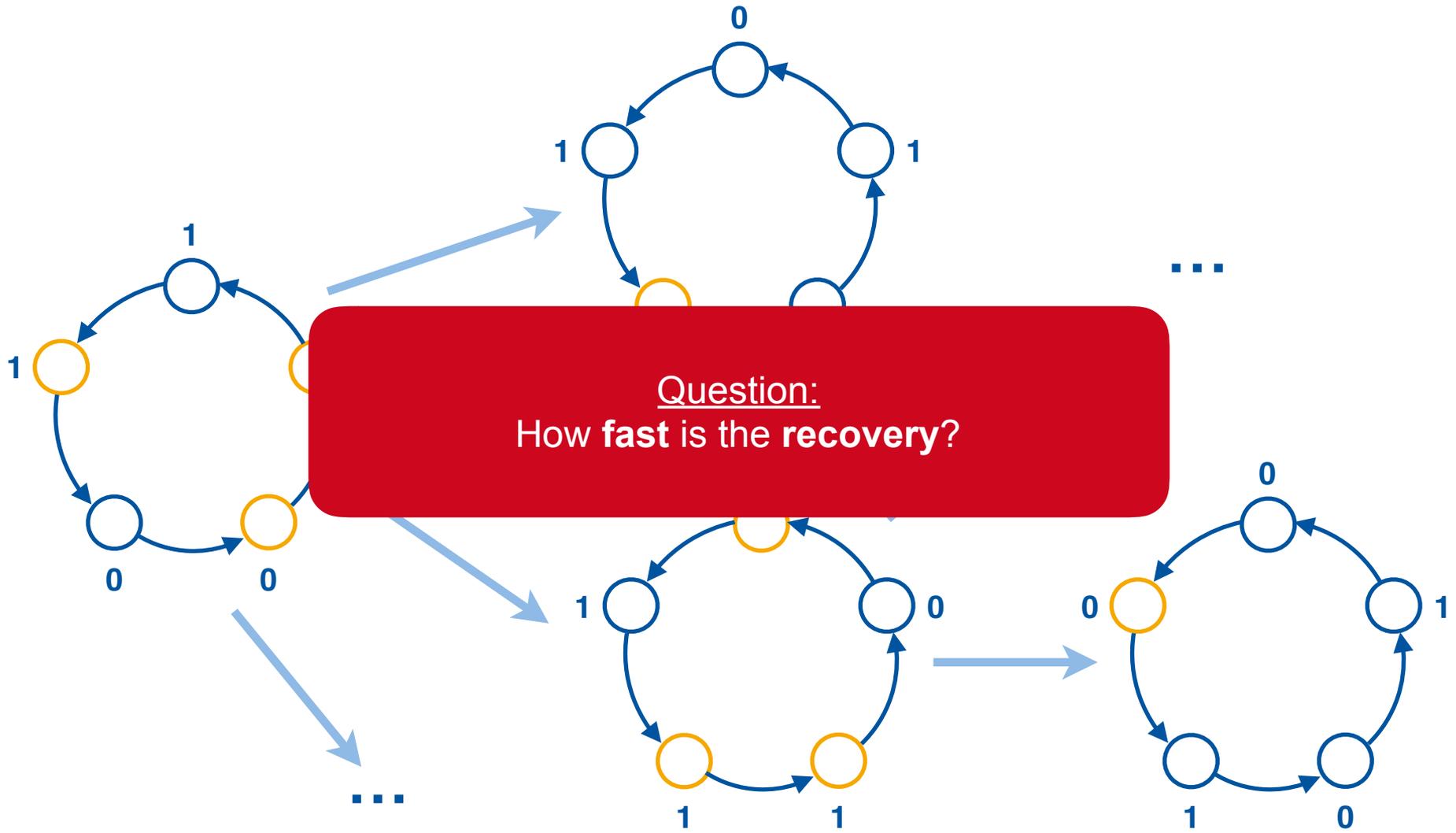
Token in x_i , if $x_i = x_{i-1}$

$x_i \neq x_{i-1} \rightarrow x_i := x_{i-1}$

$x_i = x_{i-1} \rightarrow \begin{cases} p : & x_i := 0 \\ 1 - p : & x_i := 1 \end{cases}$



Recovery

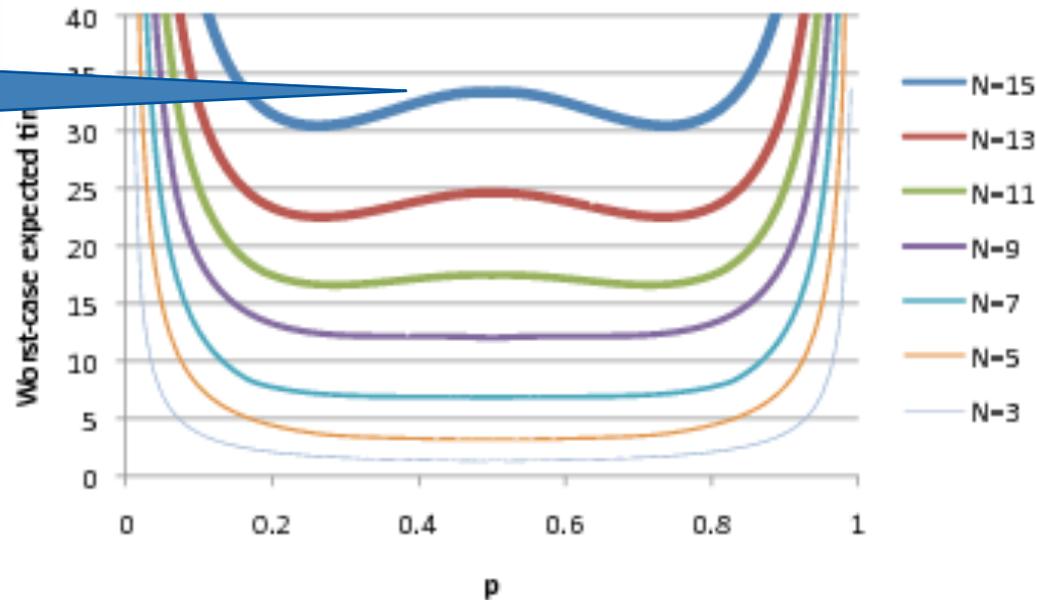


Research questions

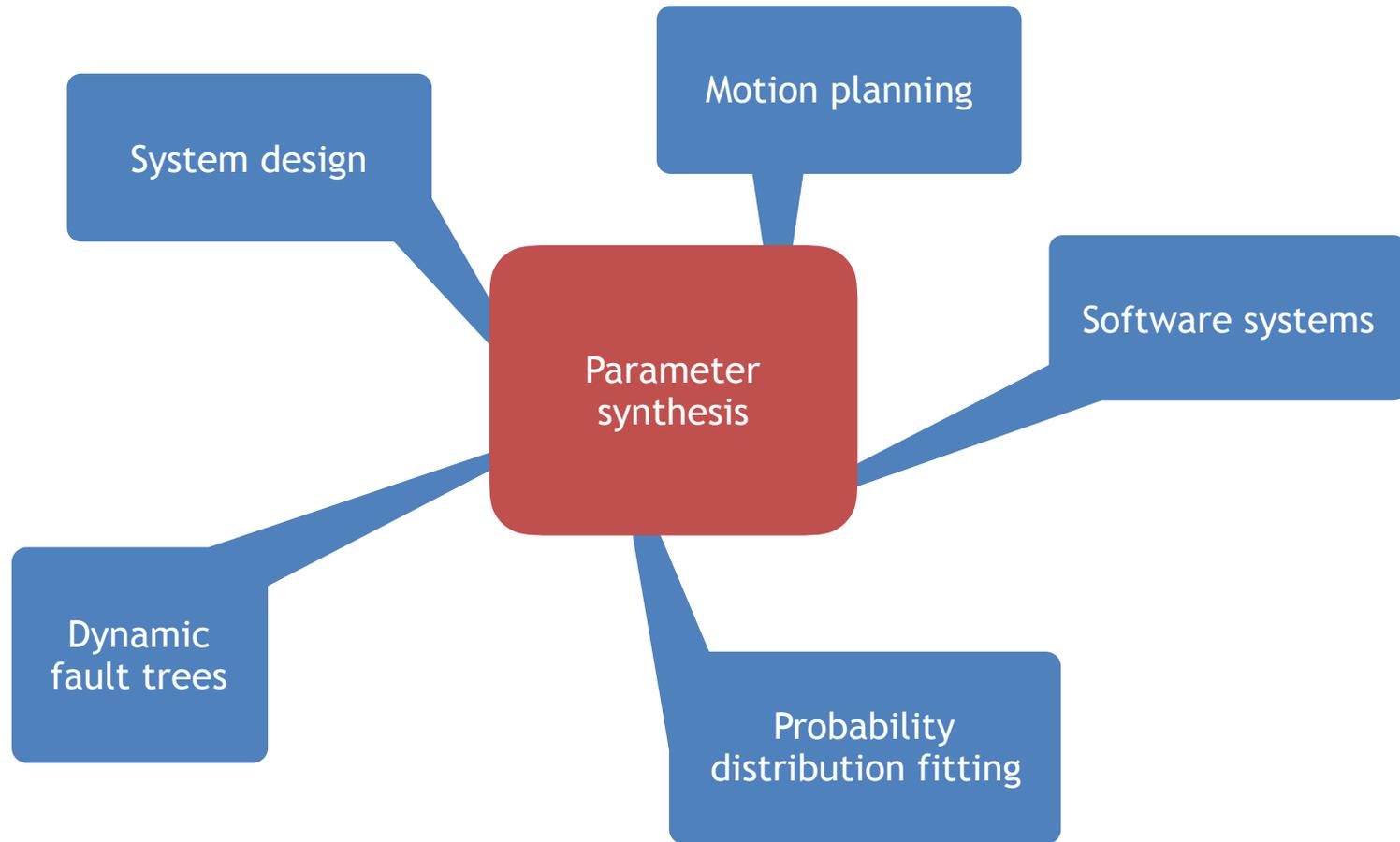
- How fast do these algorithms converge?
 - worst-case recovery time
 - average recovery time
- How does the randomization influence the recovery time?

use pMCs
[Aflaki et al. - 2017]

Fair coin not optimal



Other applications



What is a parametric Markov chain?

A parametric Markov chain is a DTMC over a set of parameters (or variables).

$$\mathcal{D} = (S, \text{Var}, \mathbf{P}, s_{\iota}, \text{AP}, L)$$

S (finite) set of states

s_{ι} initial state

AP, L atomic propositions & labelling

Var finite set of parameters or variables

$\mathbf{P}: S \times S \rightarrow \mathbb{Q}(\text{Var})$ transition probabilities

instantiation: $\text{Var} \rightarrow \mathbb{R}$



Rational
Functions

Whiteboard: Well-defined, Graph-preserving, Simple

What is Parameter Synthesis?

in the context of probabilistic model checking

- parametric Markov chain (i.e. a family of induced Markov chains)
- reachability property

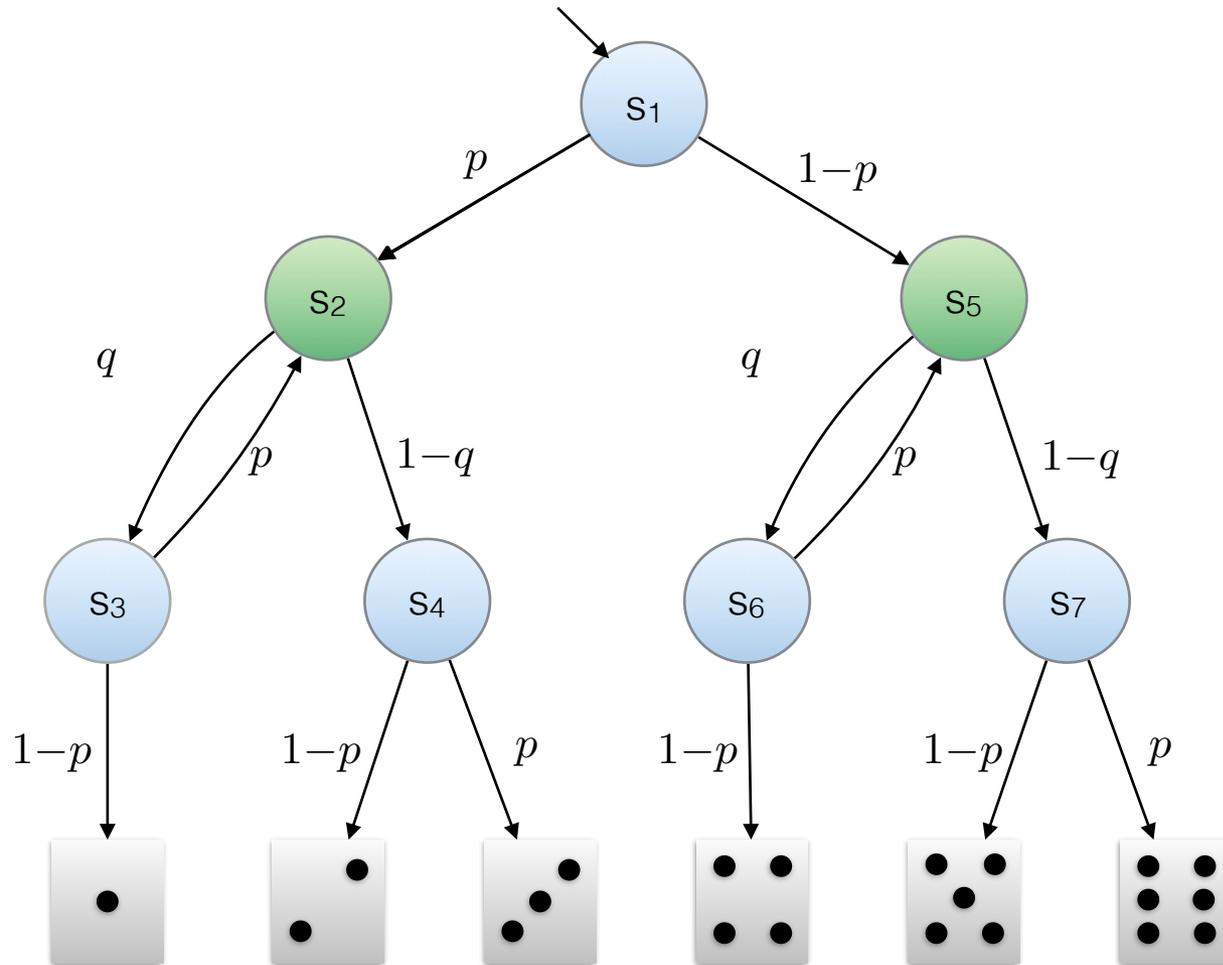
Check the property for every induced Markov chain in the **family**:

Learn something about the **effect** of the parameters

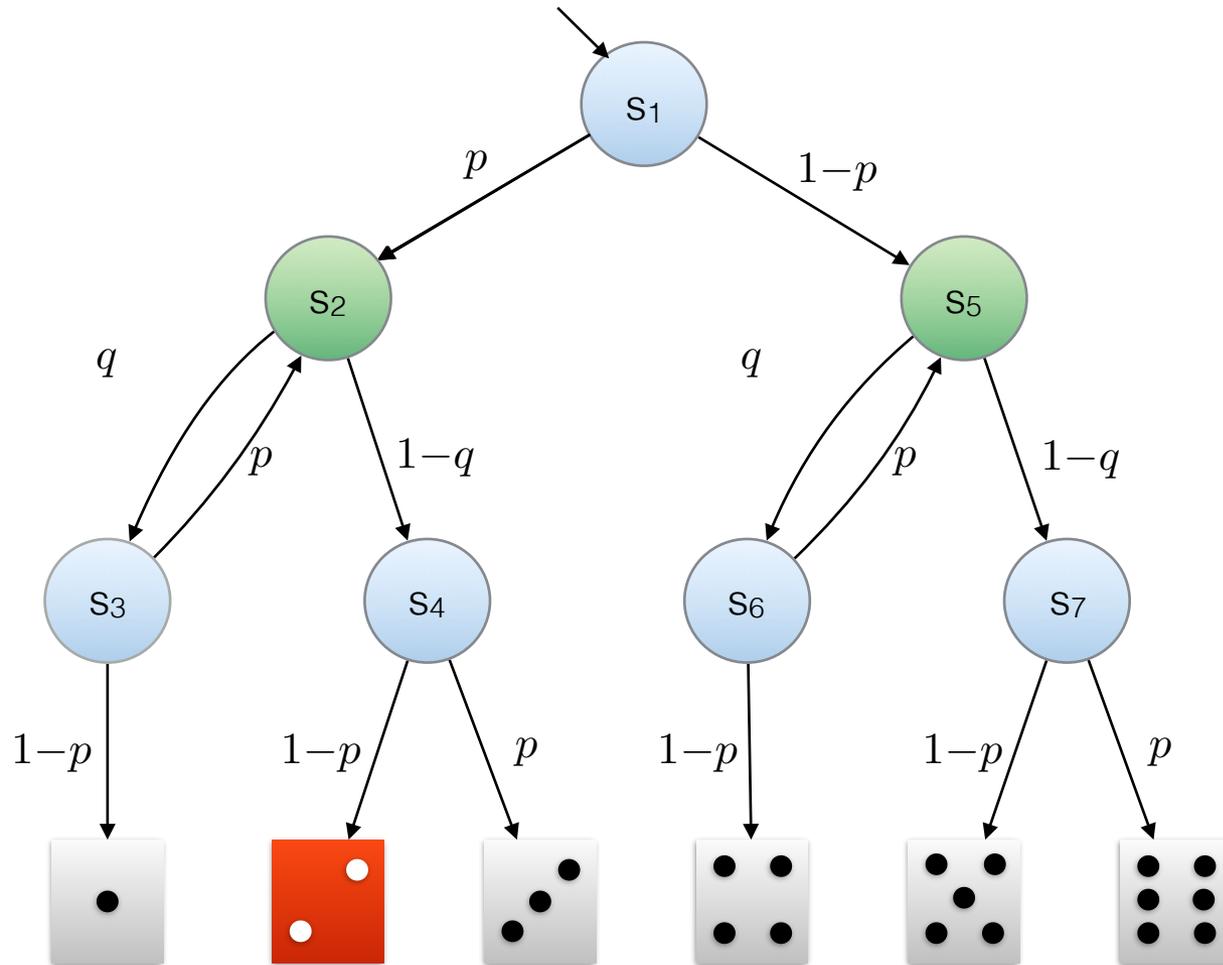
not touched today

- parametric MDPs and robust strategies
- richer properties
- connections to partially observable MDPs (prominent model in AI)

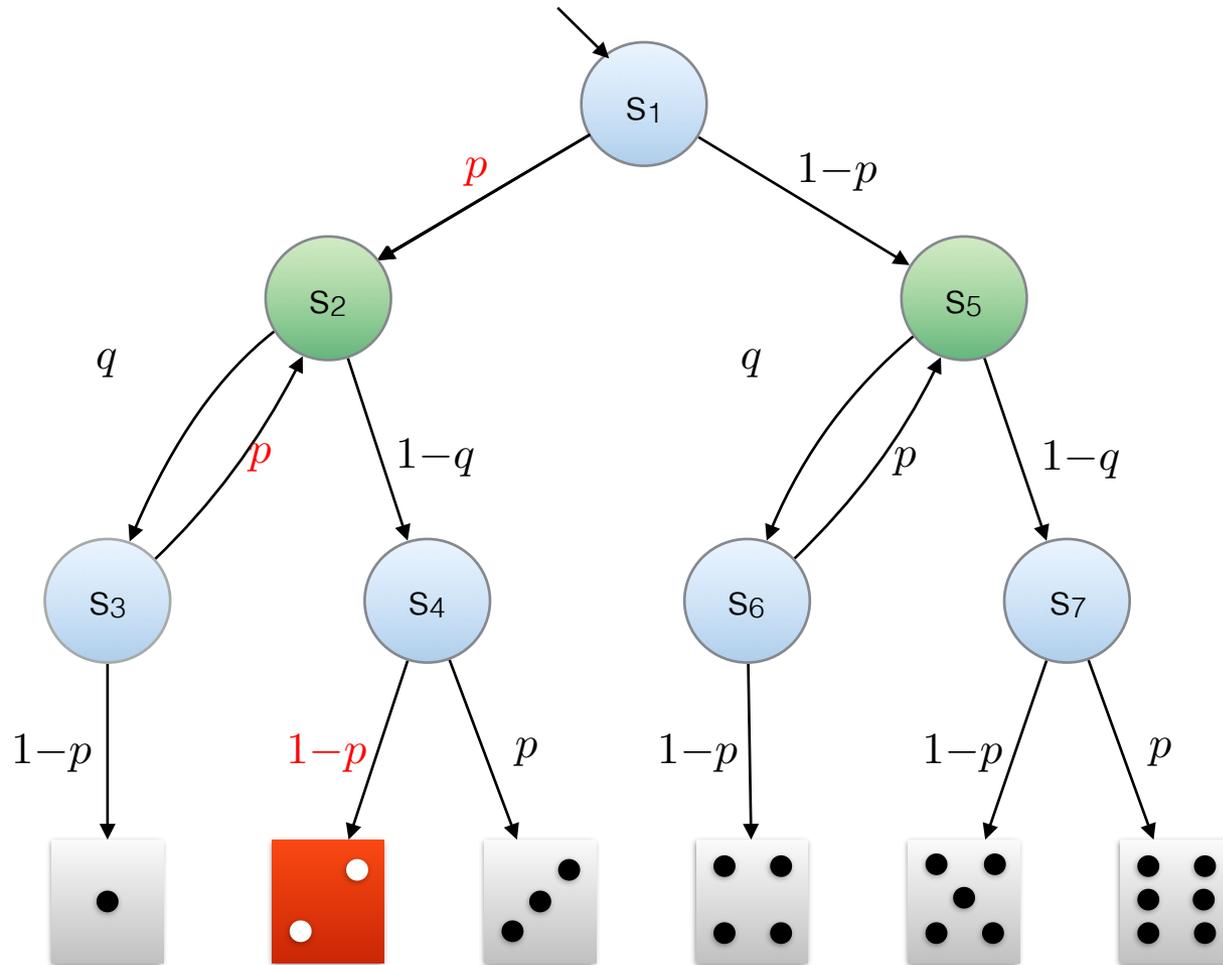
Knuth-Yao Die



Knuth-Yao Die



Knuth-Yao Die



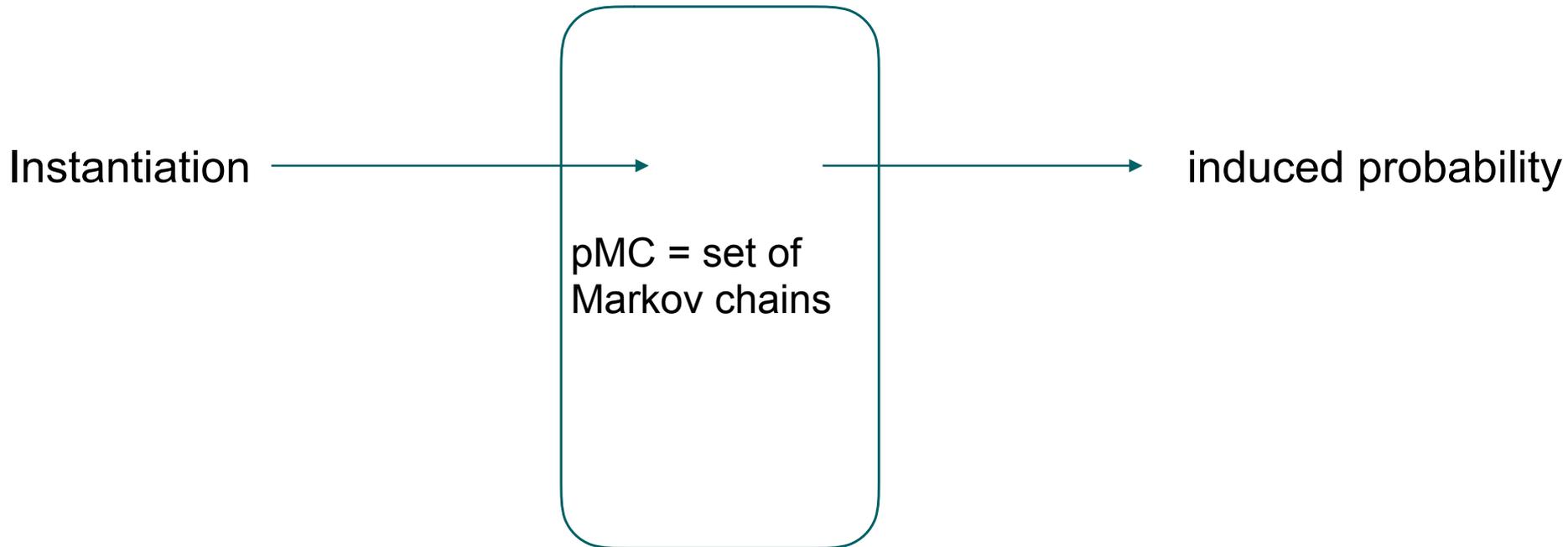
What is the Output of Parameter Synthesis?

So far, three options have been considered in the literature (to the best of our knowledge)

- Option A:
A generalisation of the output of non-parametric Markov Chain model checking
- Option B:
A concise description of parameter values that yield satisfactory performance
- Option C:
One parameter valuation that yields satisfactory performance

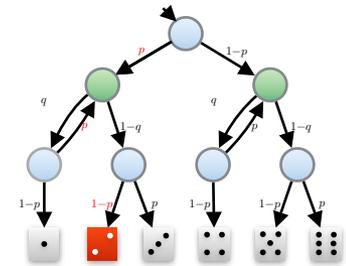
Generalised DTMC “Model Checking”

What is the probability that in a given DTMC T is eventually reached?



State Elimination

- Reachability in MCs = Linear Equation System
states = rows



Analogous to
computing regex from NFAs

State Elimination:

[Daws - 2004]

[Hahn et al - 2011]

Solving Linear Equation Systems while exploiting structure.

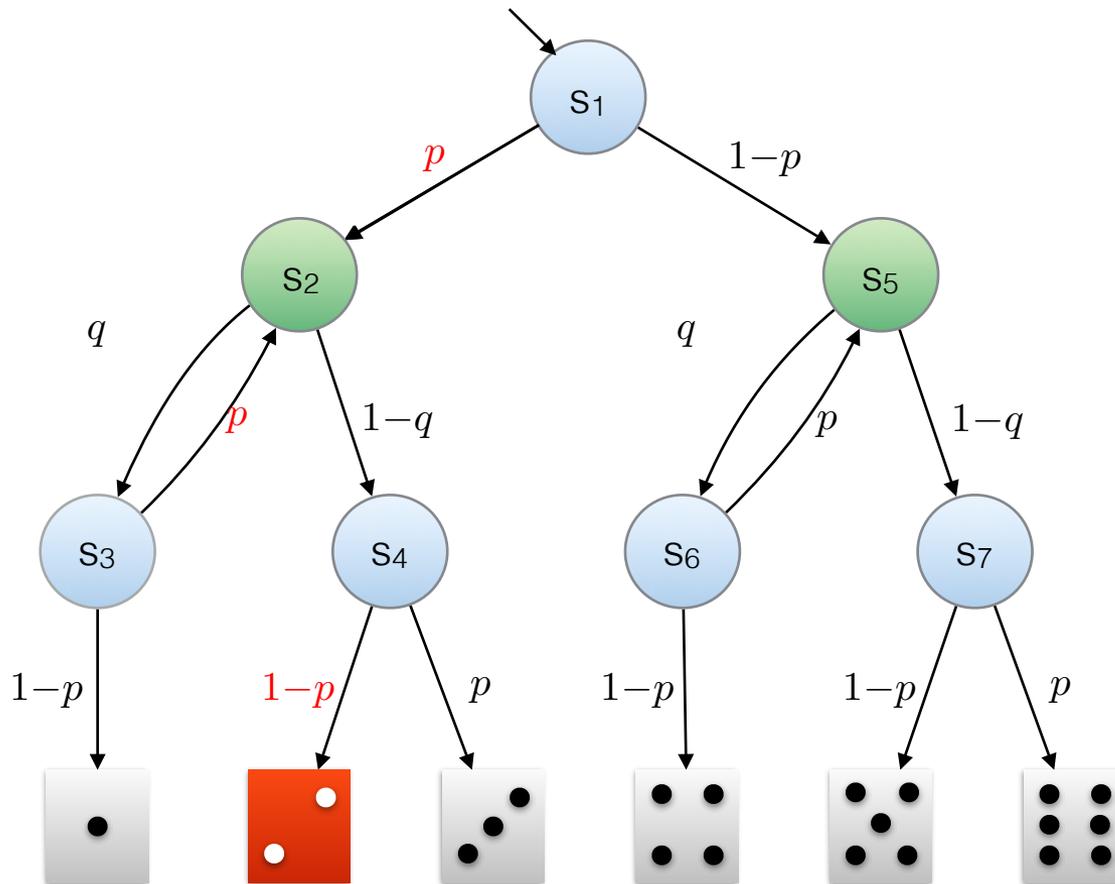
- Several heuristics - forward/backward/degree-based
- SCC-based approaches & efficient data structures

[Jansen et al. - 2014, CAV15]

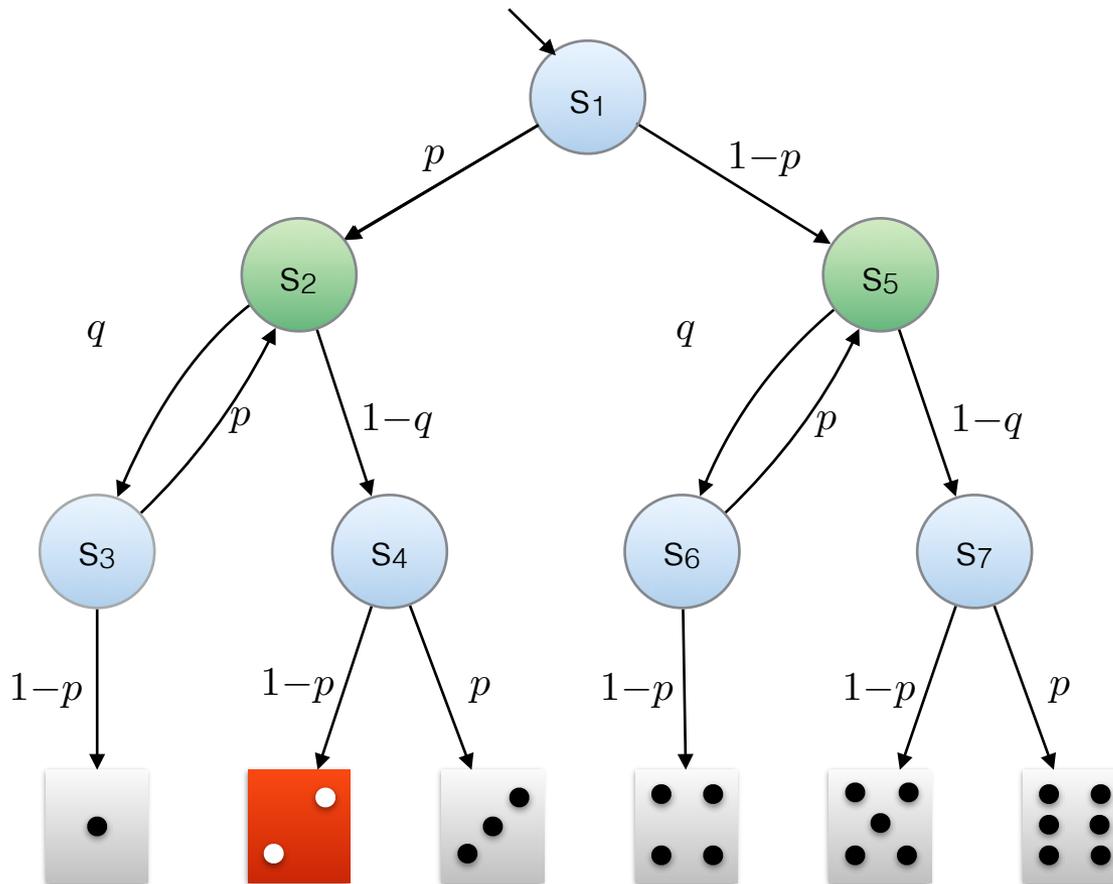
- Borrow from Floyd-Warshall and Fraction-Free Gaussian

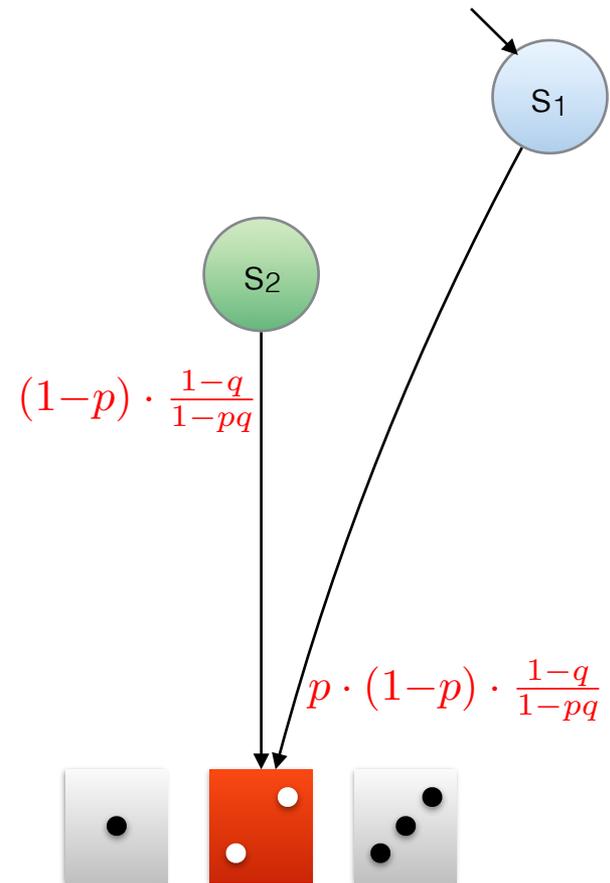
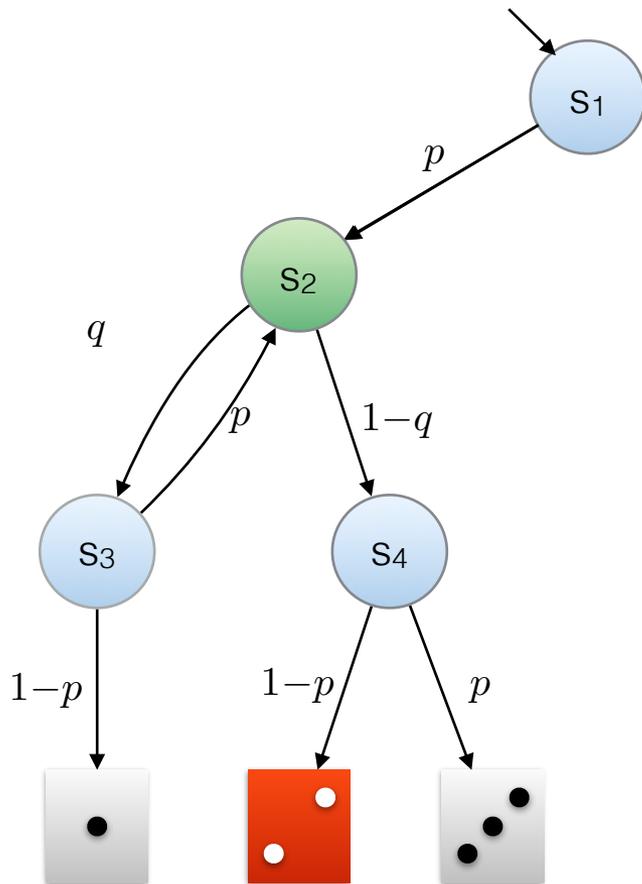
[Accepted - 2019, CAV17]

State Elimination

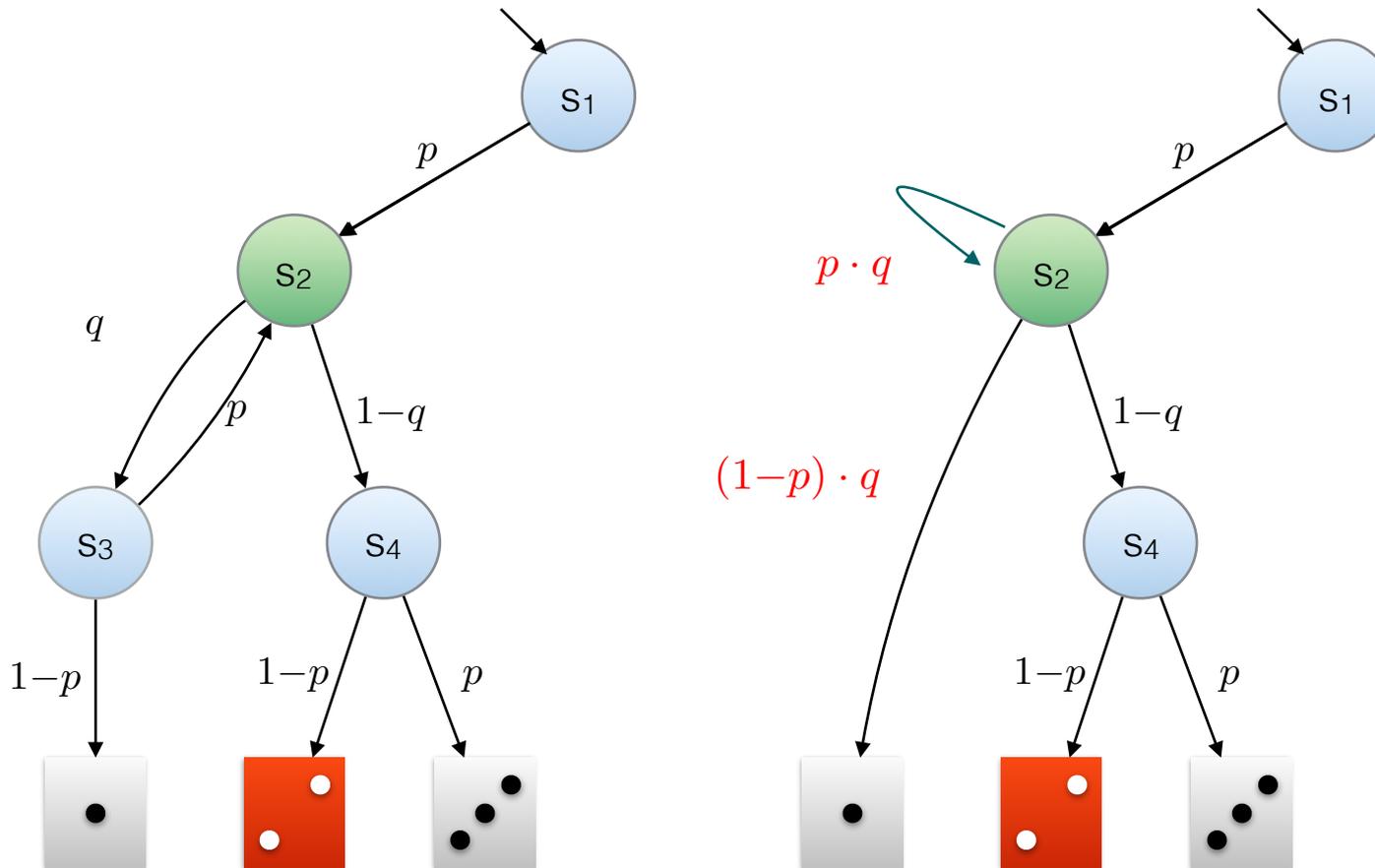


State Elimination

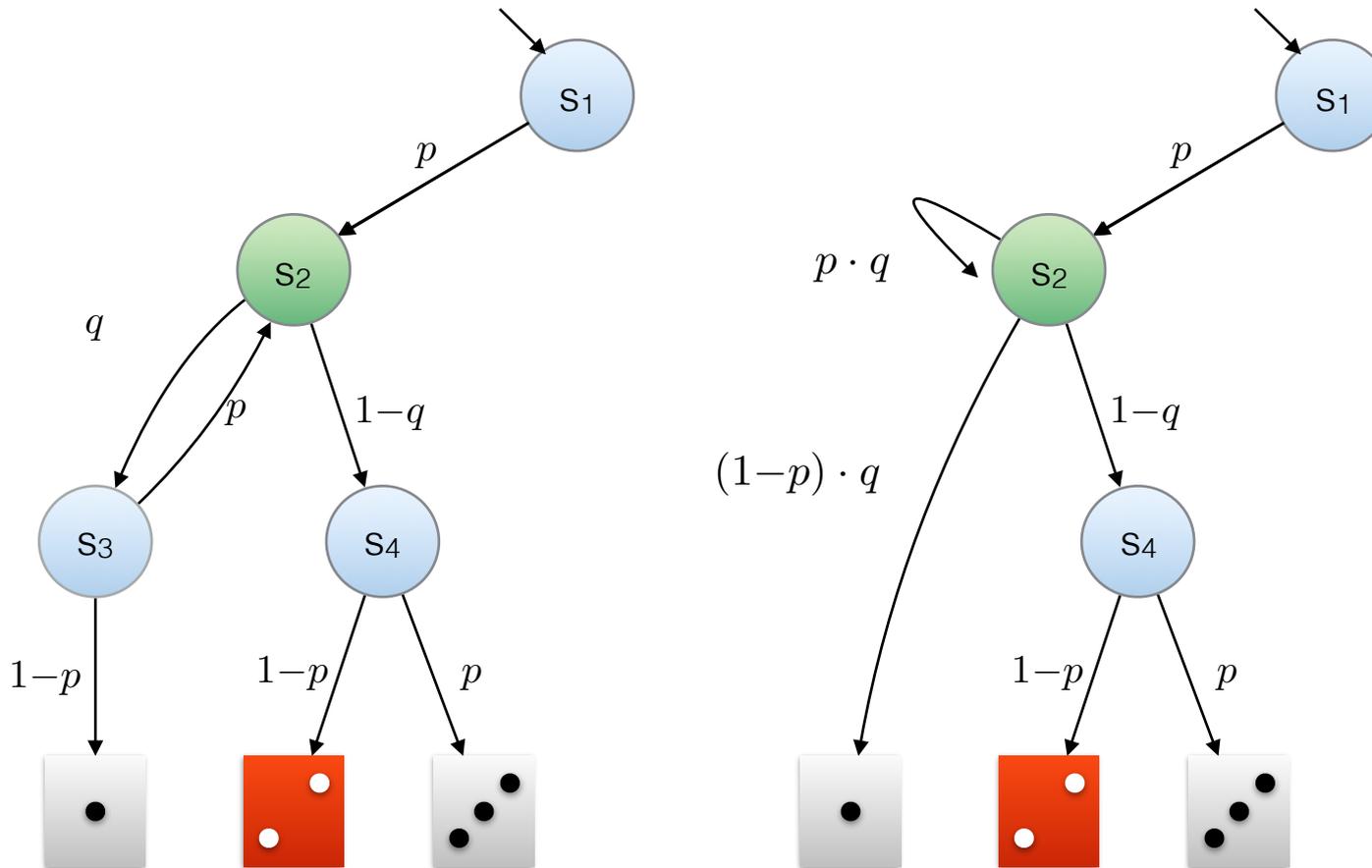




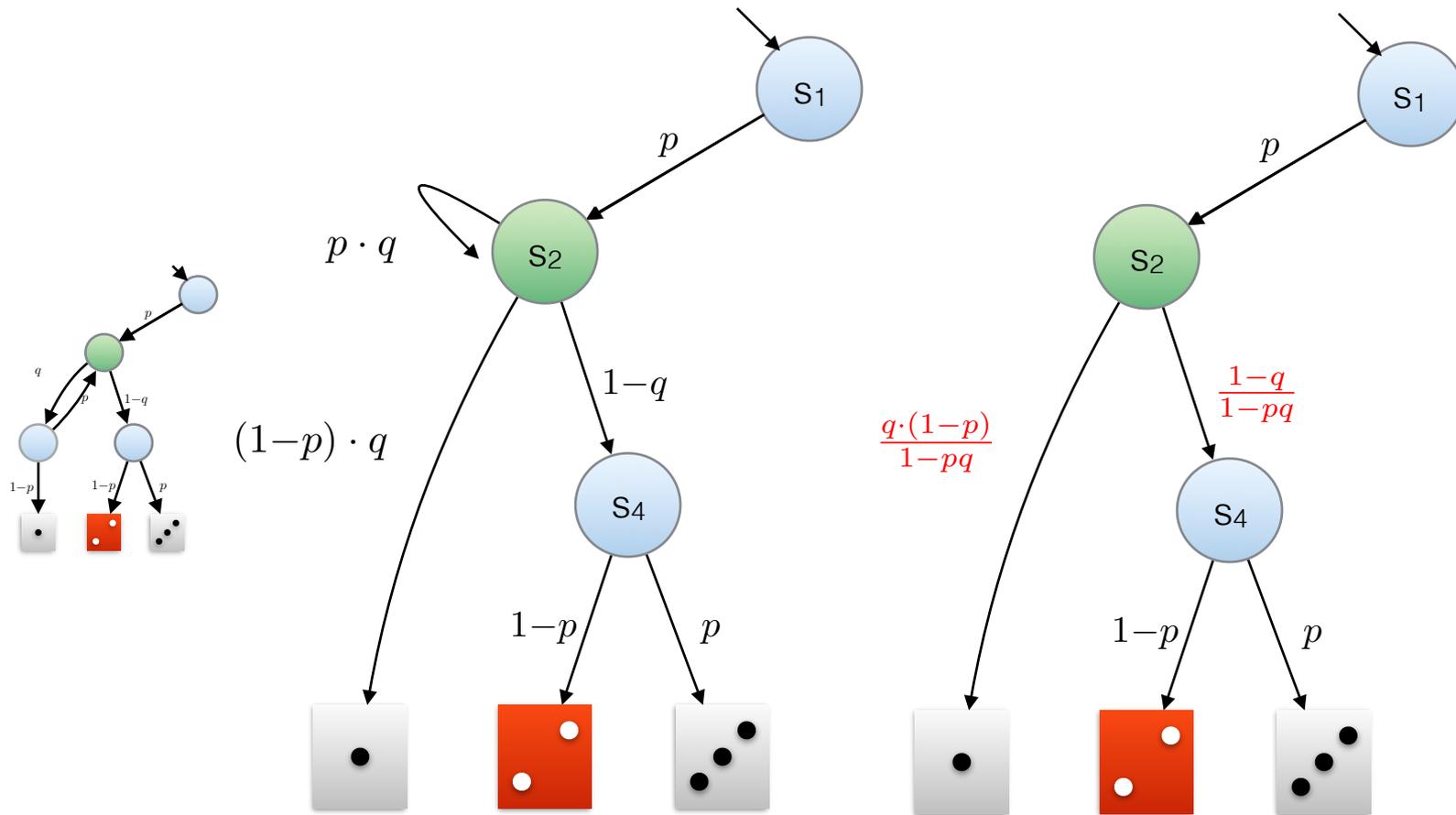
State Elimination



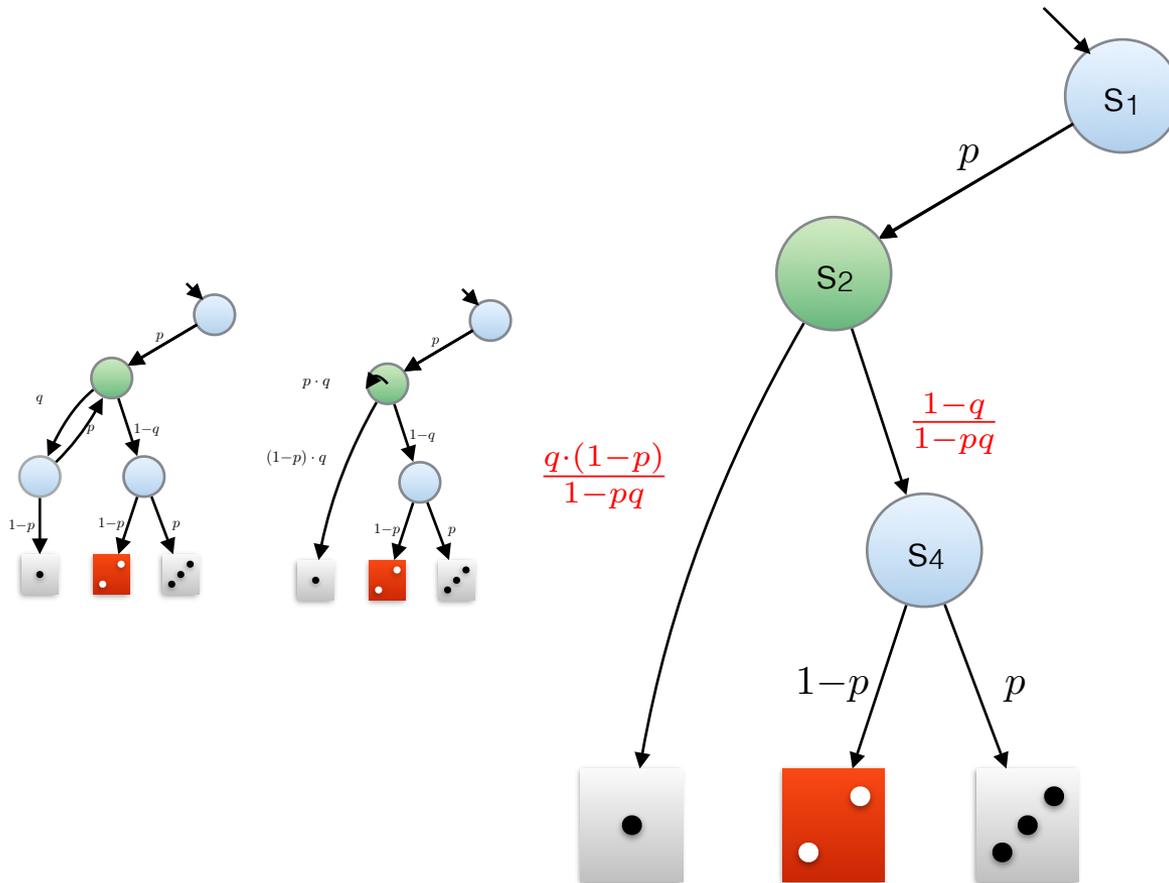
State Elimination



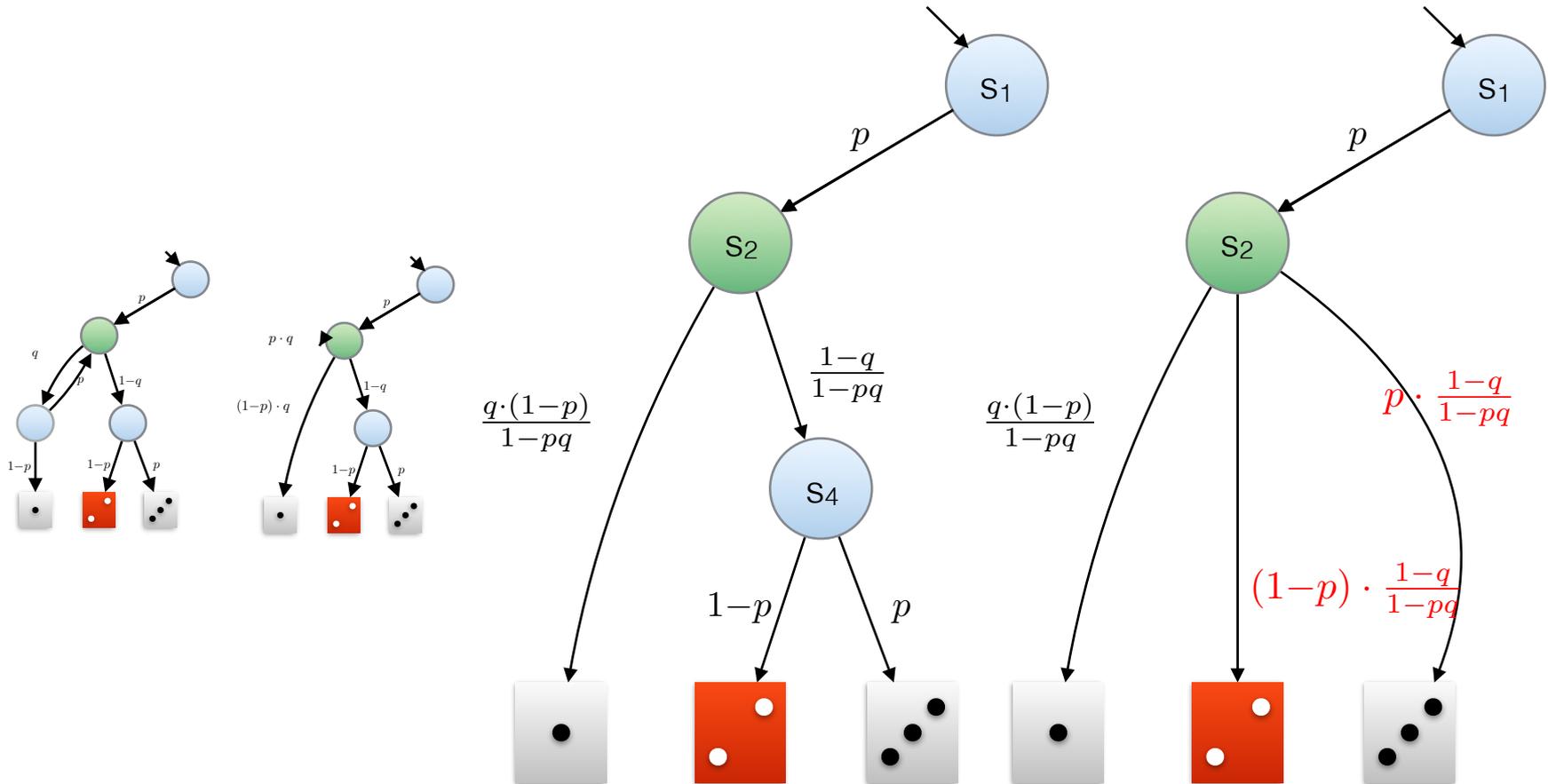
State Elimination



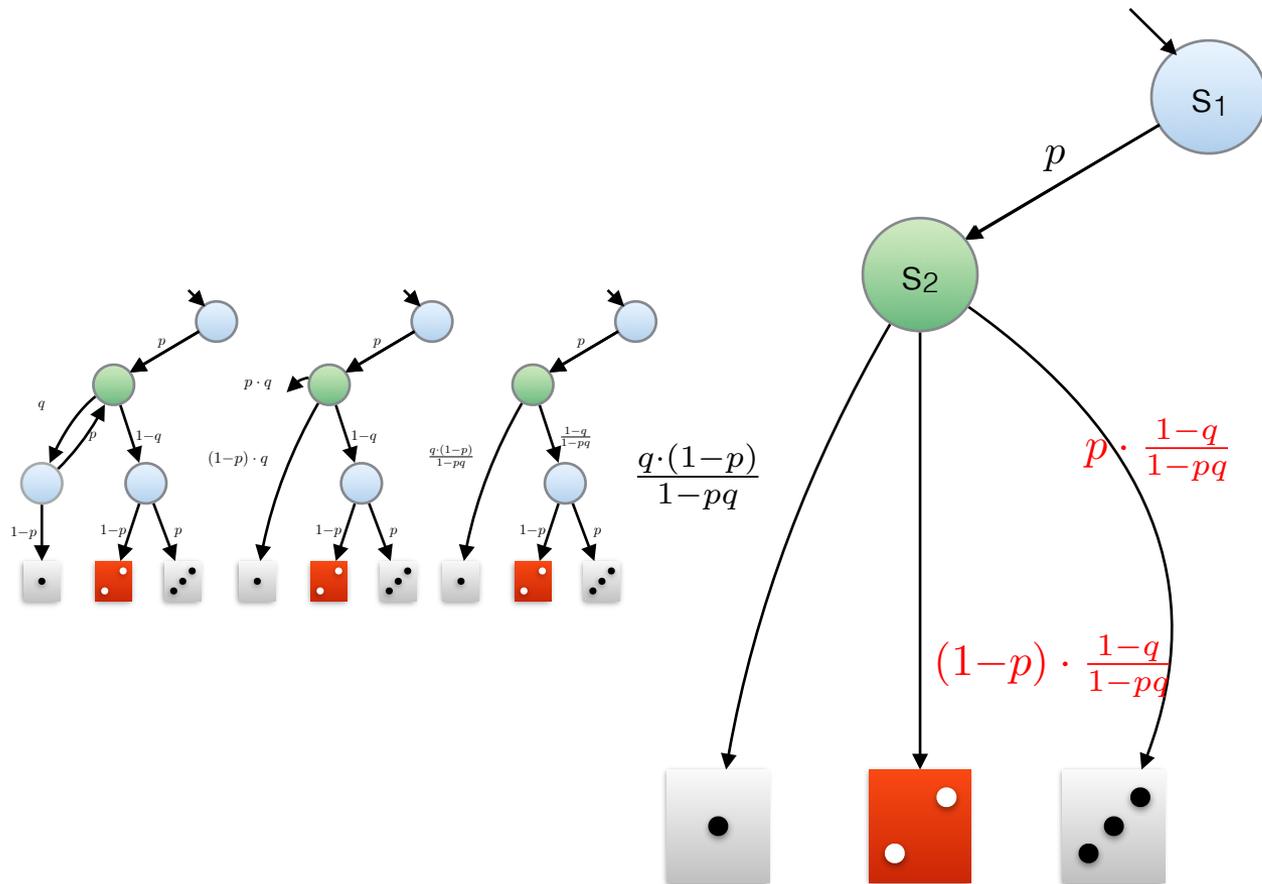
State Elimination



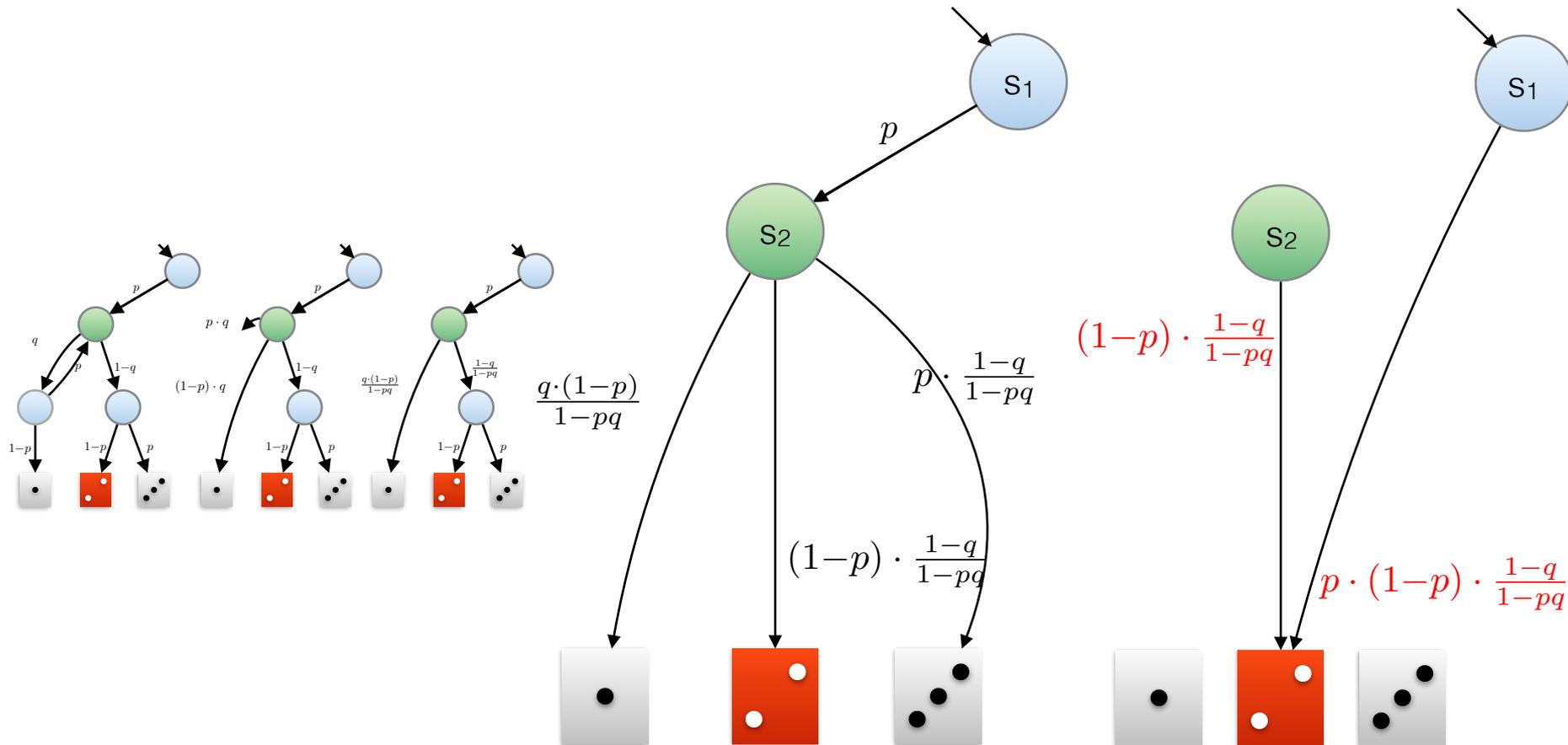
State Elimination



State Elimination



State Elimination



Facts

For a pMC with k parameters, n states and polynomial probabilities of degree d .

- The rational function (actually a polynomial) can be exponential in k (even for acyclic pMCs)
- Hence, computation of the function is exponential in the worst case
- For any fixed k , the computation can be done in polynomial time in n and d .

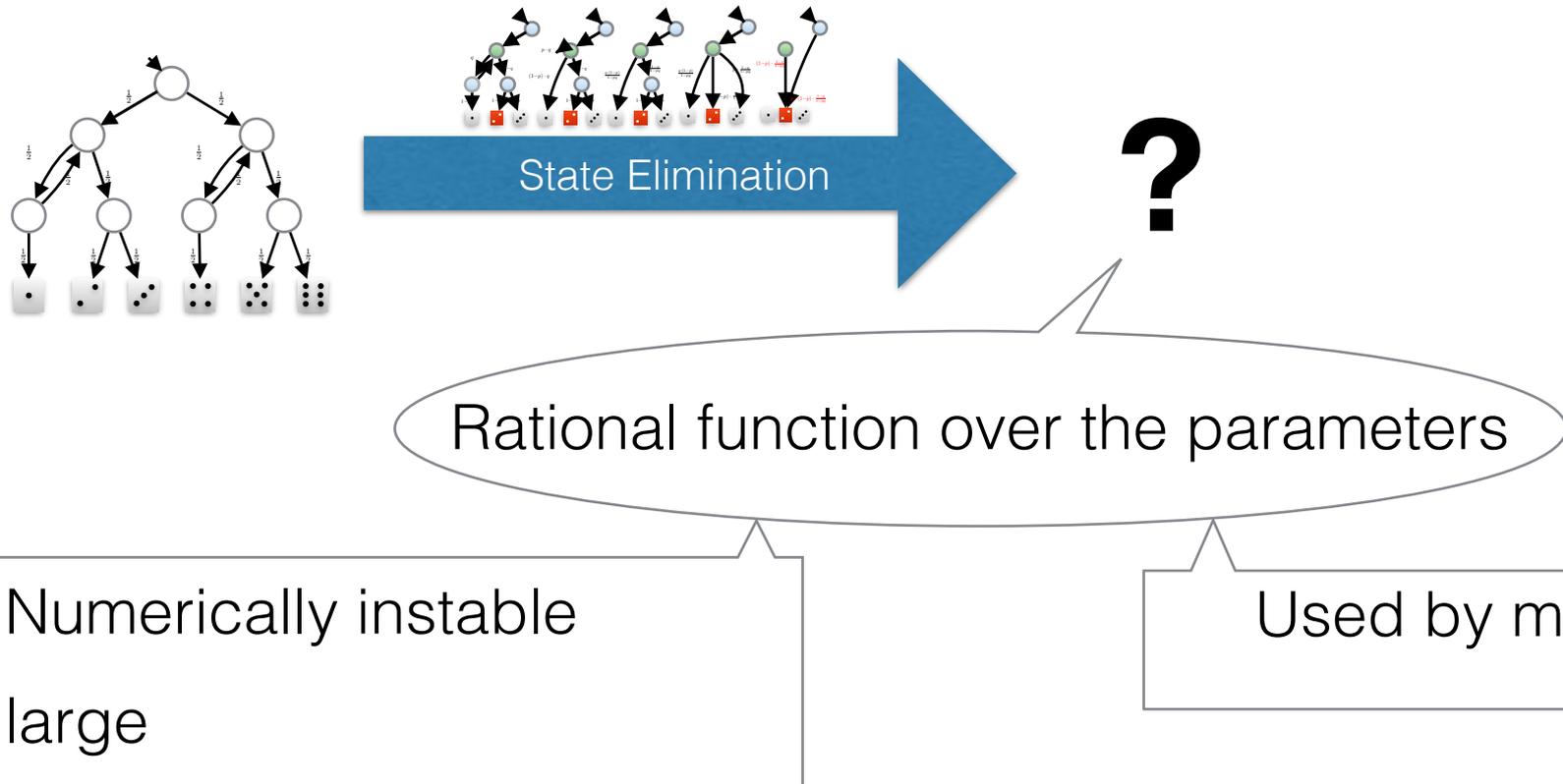
Computing the rational function

Tool support for state elimination

Using Storm

			PRISM		PARAM		PROPheSY			
			instance	//states	//trans	verif.	total	verif.	total	
reachability	brp	(128, 5)	10376	13827	215	218	5	7	2	3
		(256, 5)	20744	27651	1237	1242	32	33	8	10
	crowds	(15, 5)	592060	1754860	TO	TO	18*	48*	1	46
		(20, 5)	2061951	7374951	TO	TO	75*	194*	4	165
	nand	(20, 2)	154942	239832	886	901	44	48	16	22
		(20, 5)	384772	594792	TO	TO	319	328	89	104
exp. reward	egl	(5, 4)	74750	75773	5	11			< 1	5
		(8, 4)	7536638	7602173	543	910	-	-	7	607
	nand	(20, 2)	154942	239832	TO	TO	264	2033	5	12
		(20, 5)	384772	594792	TO	TO	TO	TO	47	64
	zconf	(10000)	10004	20005	TO	TO	TO*	TO*	4	4
		(100000)	100004	200005	TO	TO	TO*	TO*	255	263
conditional	brp	(256, 2)	10757	13827	-	-	-	-	< 1	1
		(256, 5)	20744	27651	-	-	-	-	1	3
	crowds	(15, 5)	592060	1754860					5	50
		(20, 5)	2061951	7374951					14	174

Result of State Elimination

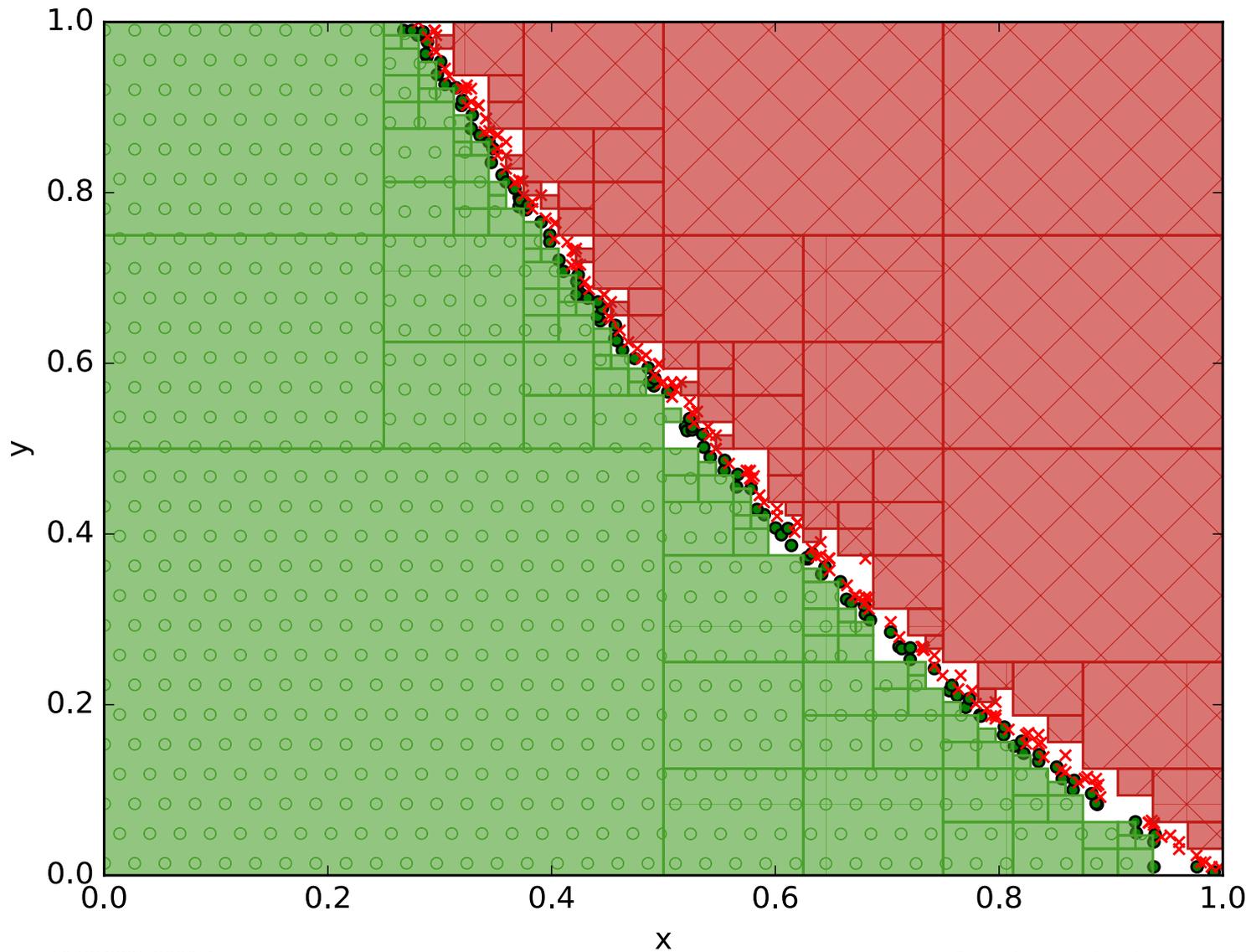


What is the Output of Parameter Synthesis?

So far, three options have been considered in the literature

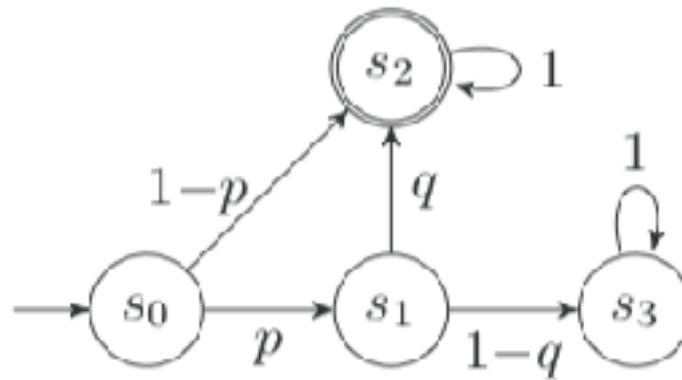
- Option A:
A generalisation of the output of non-parametric Markov Chain model checking
- Option B:
A concise description of parameter values that yield satisfactory performance
- Option C:
One parameter valuation that yields satisfactory performance

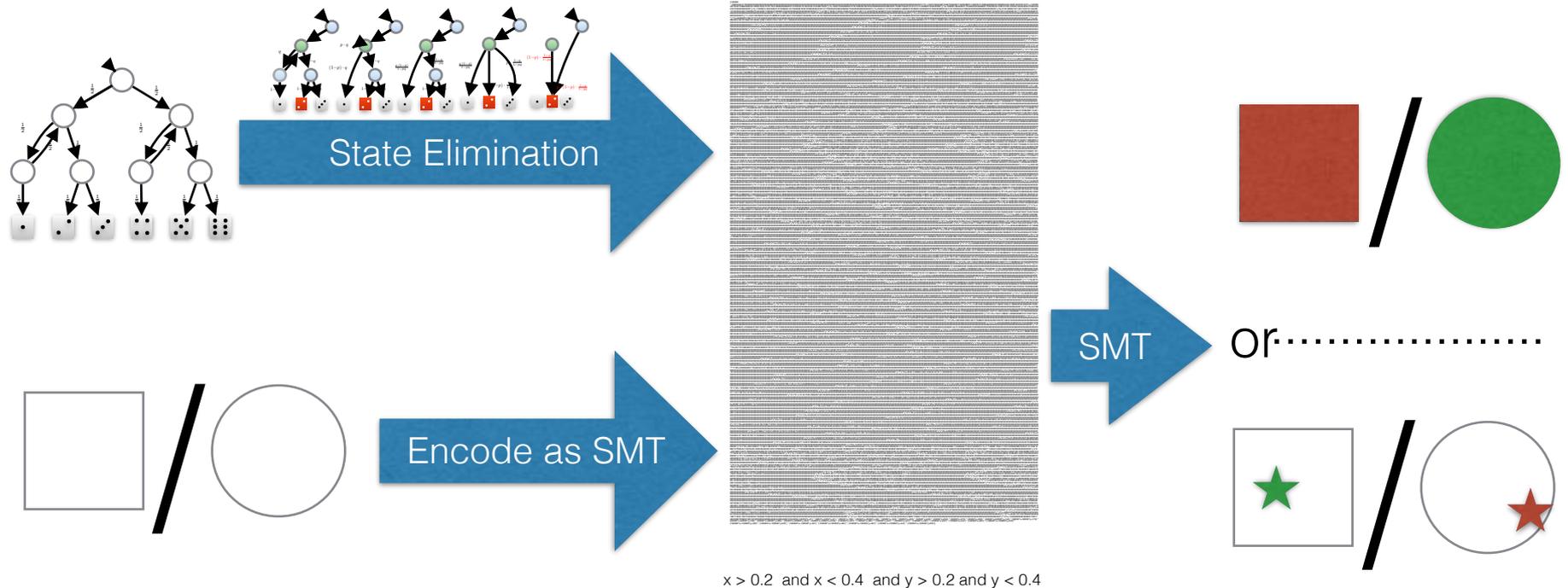
Parameter Space Partitioning



SMT-Encoding

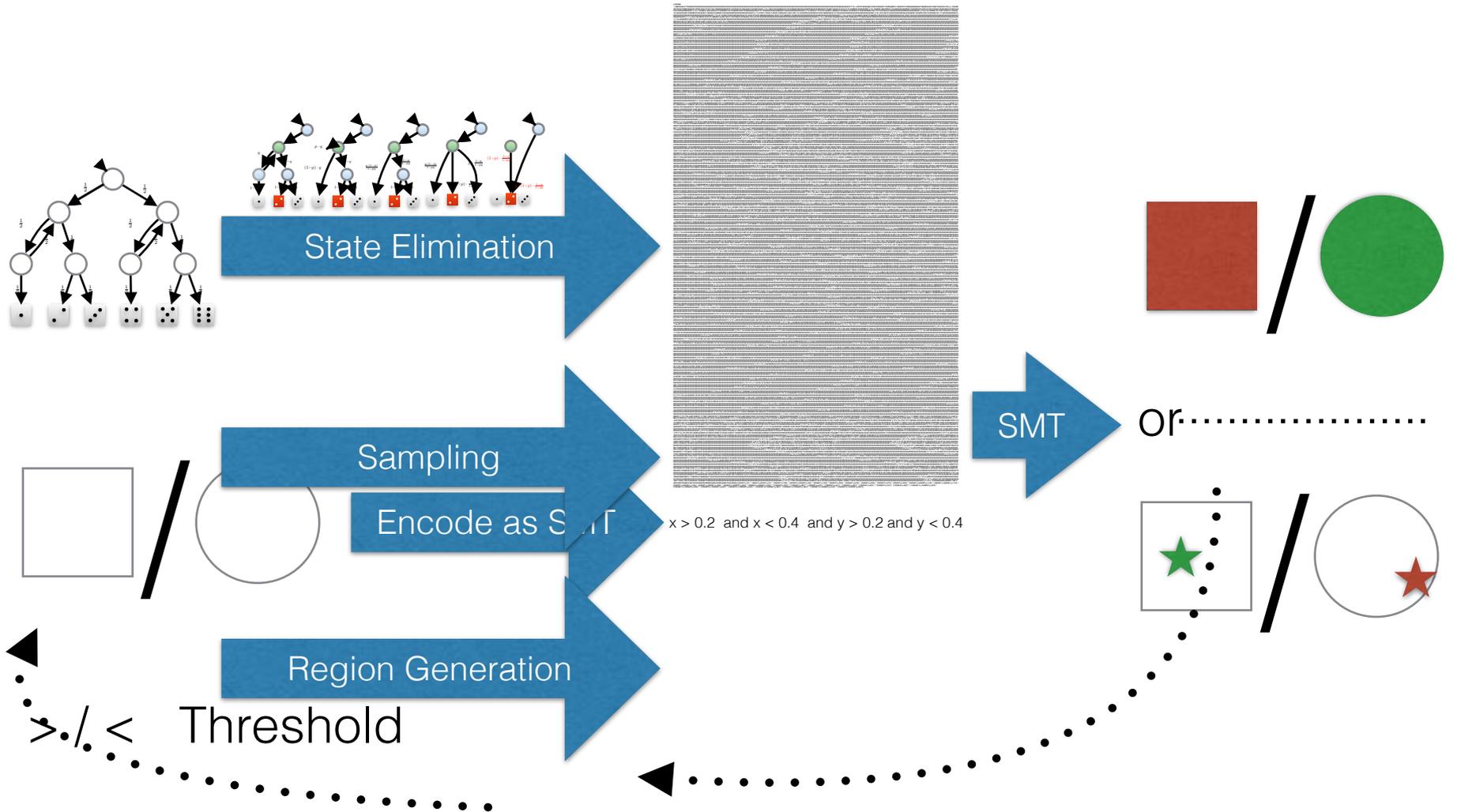
Encoding transition system, satisfiability (region)

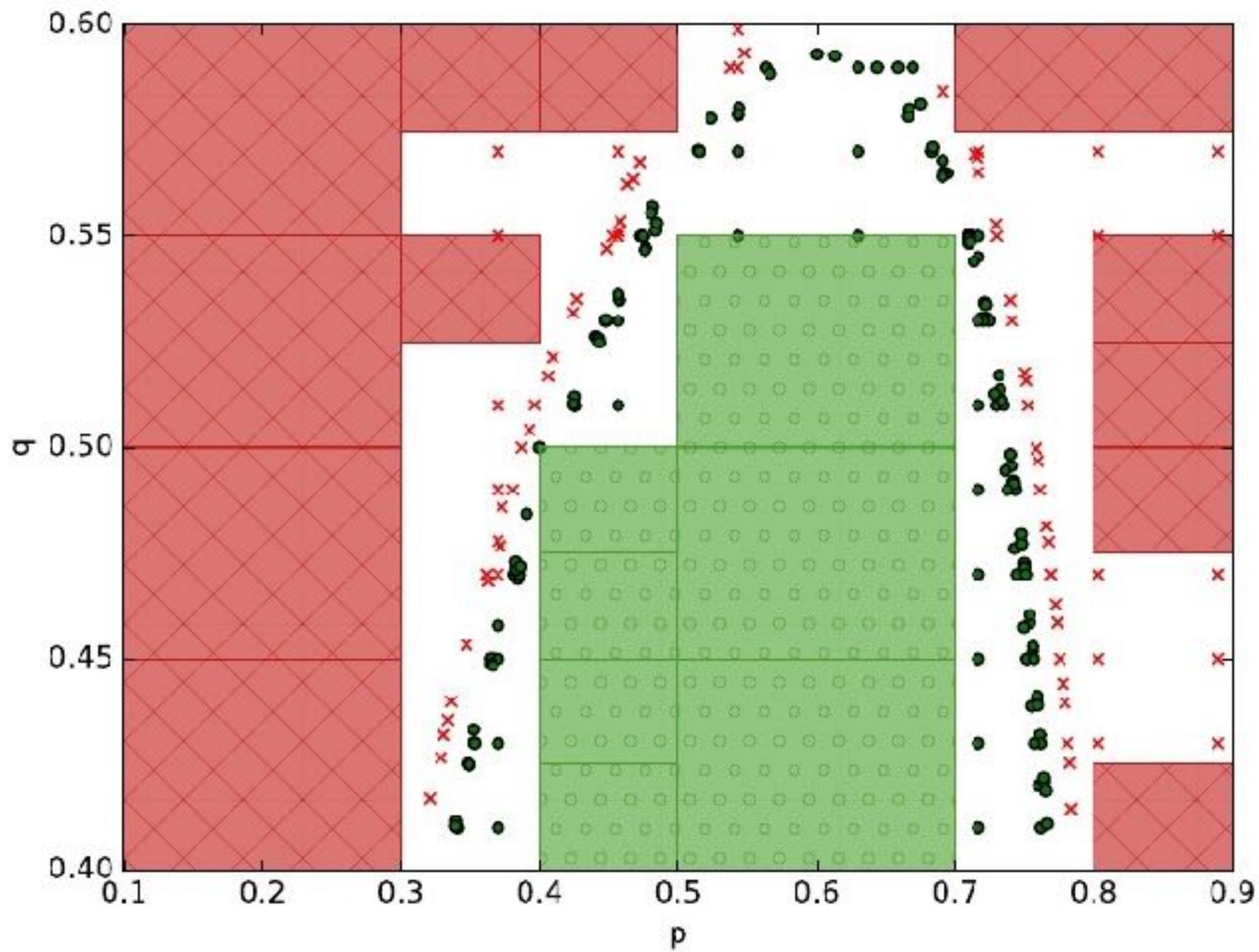


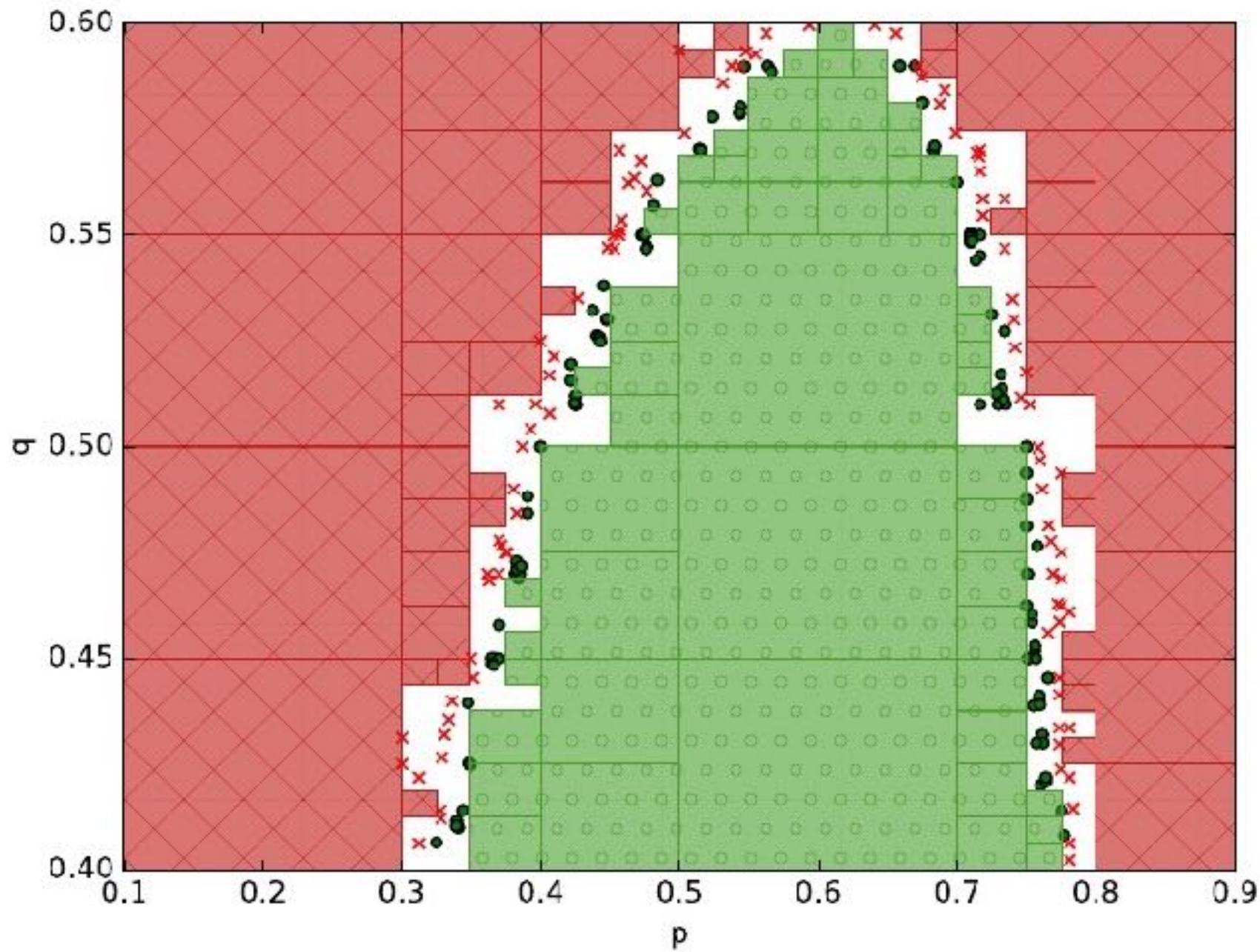


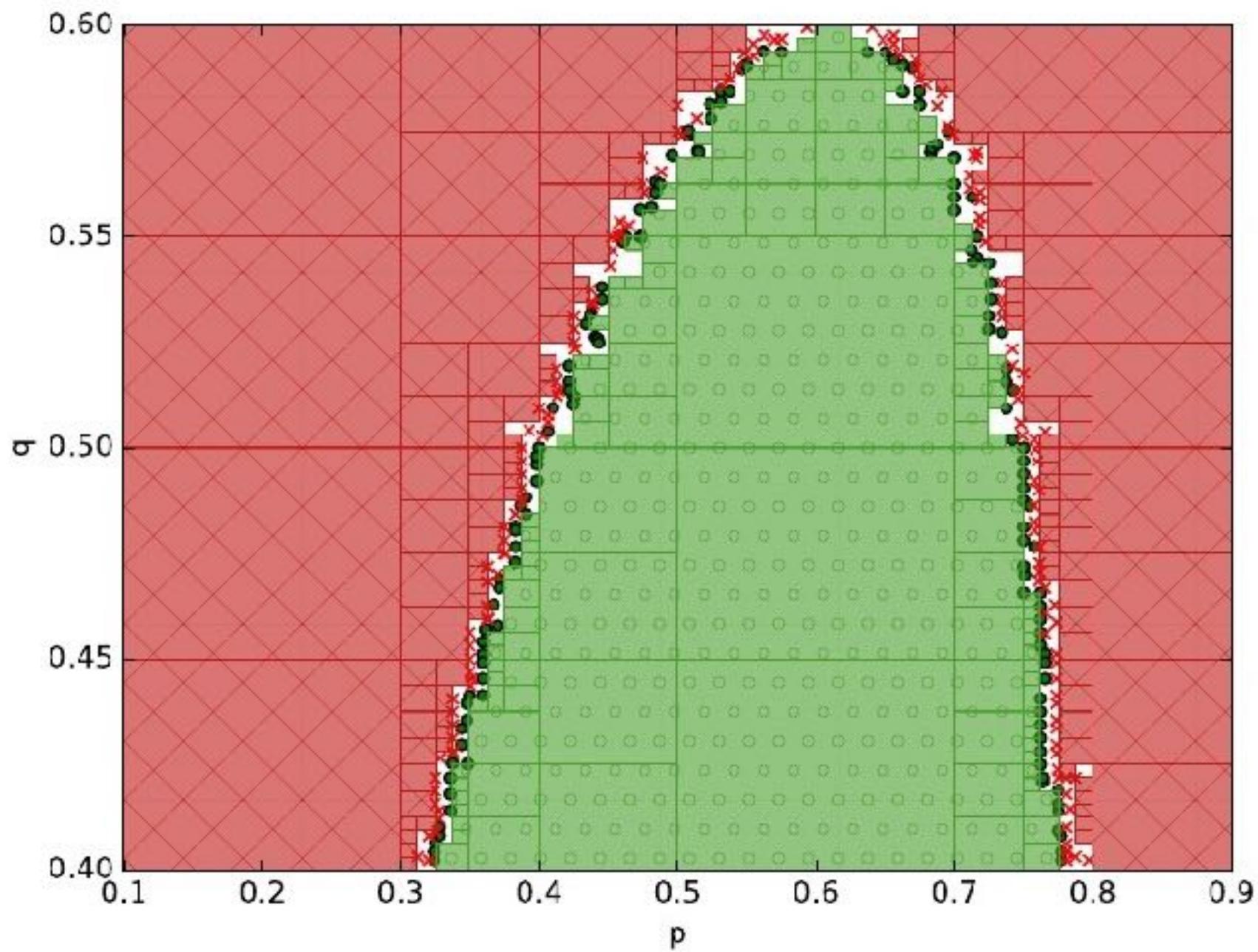
> / < Threshold

Prophecy









Complexity

Does there exist a parameter valuation such that the induced MC induces probability larger than 1/2?

Facts

- Definitely in the existential theory of the reals (ETR), see earlier.

Thus, in PSPACE.

- Via rational function: number of variables == number of parameters

Thus, as ETR is polynomial for fixed variables,
PTIME for fixed number of parameters (graph-preserving)

- With two objectives: NP-hard (graph-preserving)
- NP-hard (non-graph preserving)

Also known to be SQRS-hard (graph-preserving)

Checking Regions w SMT

#4 parameters seems out of reach

Obtaining Rational Function → function is typically huge

Hard to develop heuristics

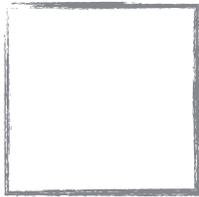
SMT performance unpredictable

Solver does too much work

Rational function is exact everywhere

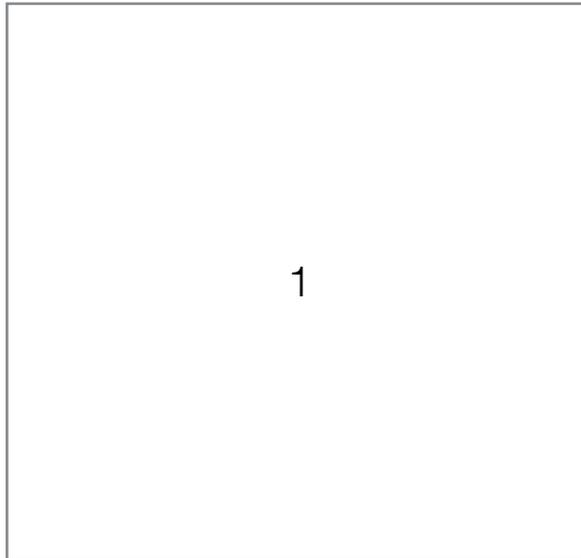
pMC is a 1.5 player game

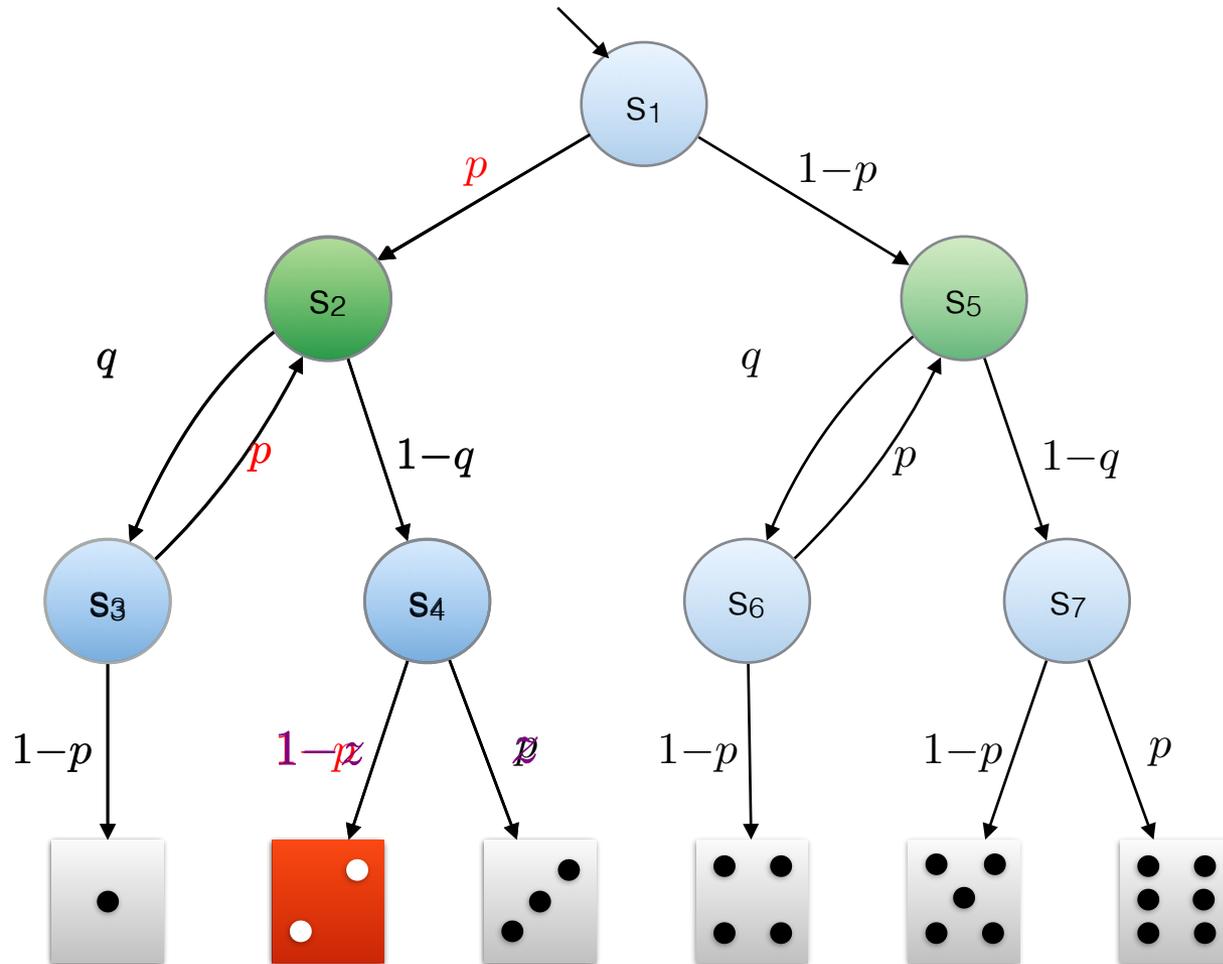
pMC is a set of *instantiated* DTMCs

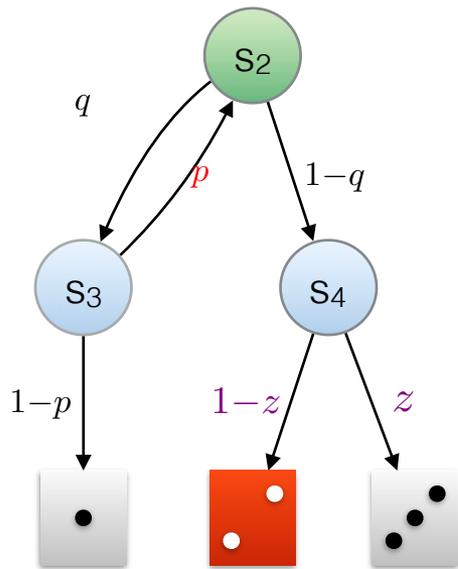


For all points u in the region:

Probability in $\text{DTMC}(u) < \text{Threshold?}$





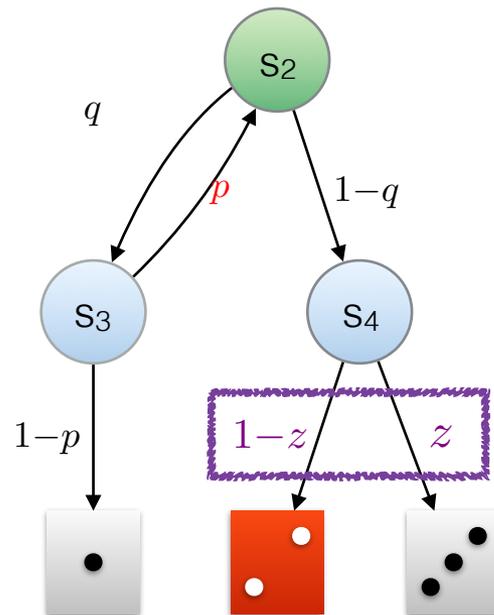


$$P(\diamond \text{red die}) = (1-z) \cdot \frac{1-q}{1-pq}$$

st at 1 state;

at most degree 1

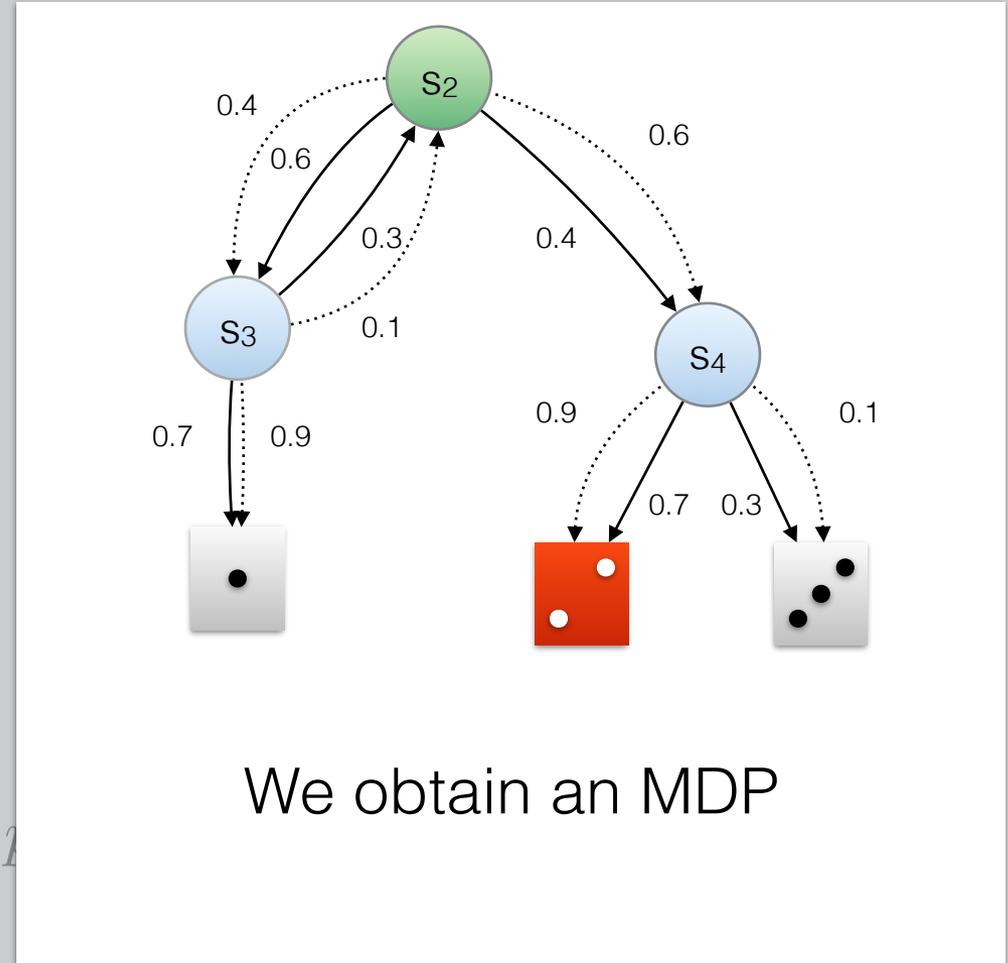
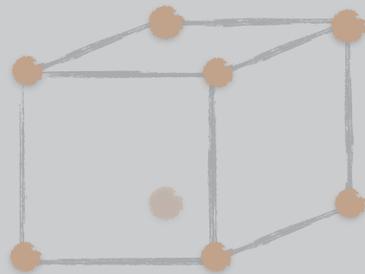
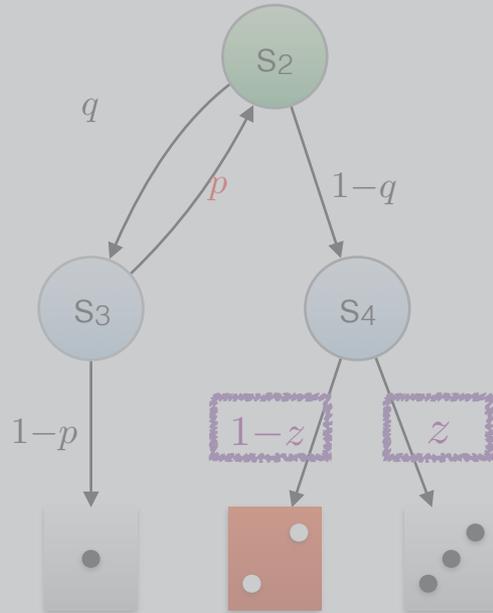
t extremal values

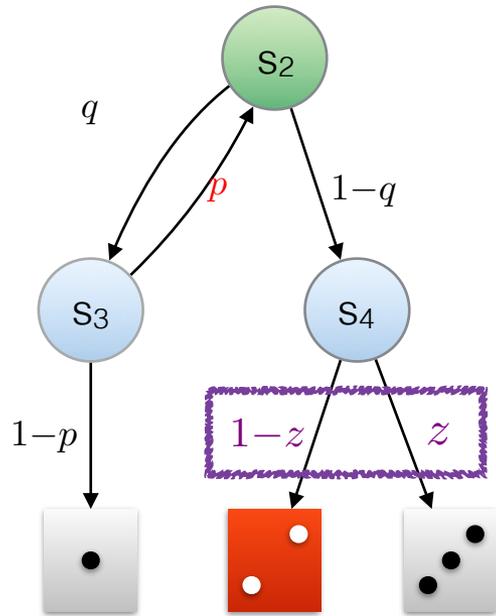


Relaxation

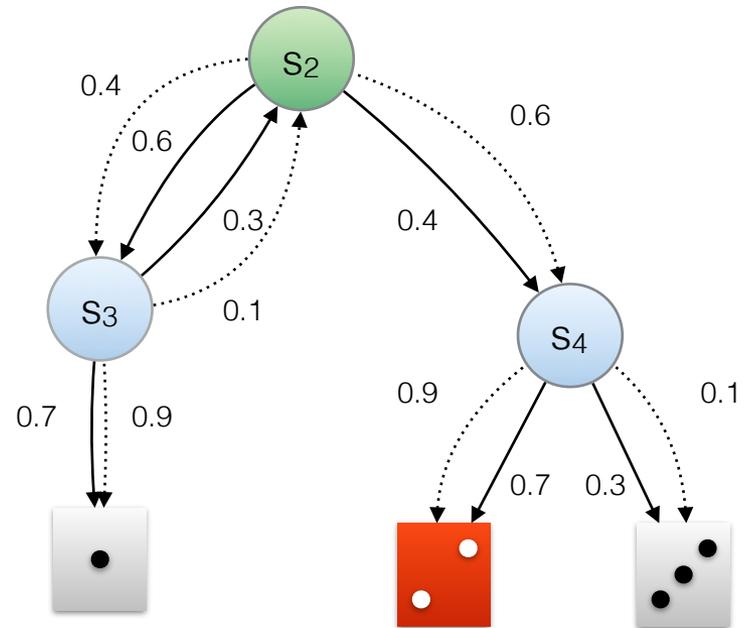


Lifting

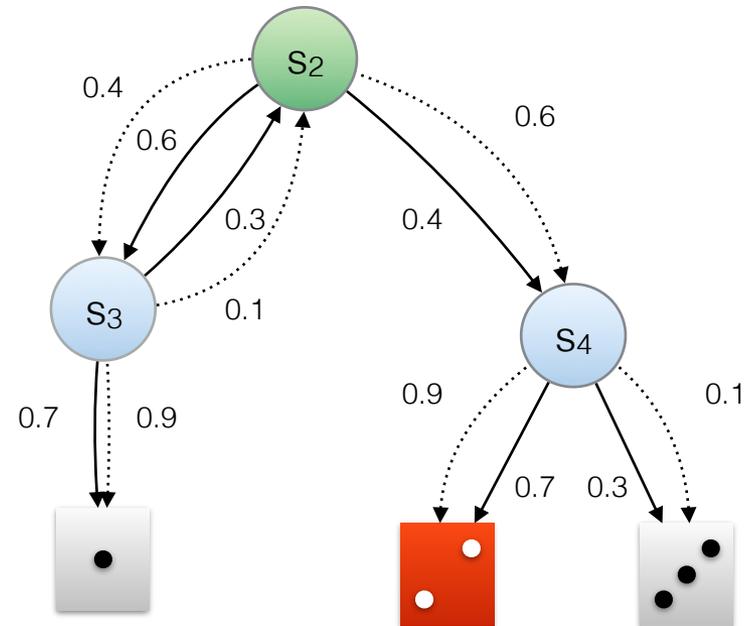




Relaxation



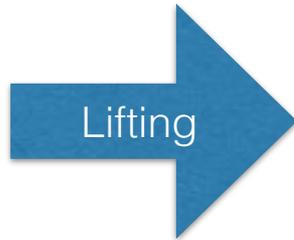
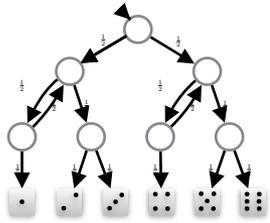
Lifting



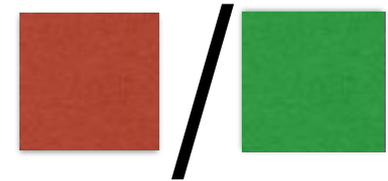
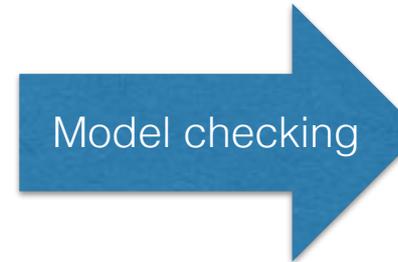
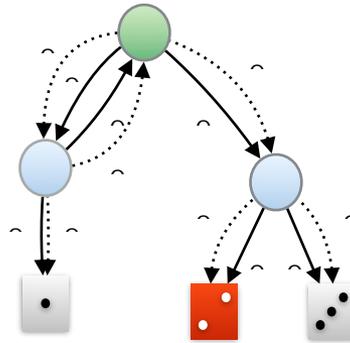
Lifting

Lifting (Relaxation (D)) = Lifting (D)

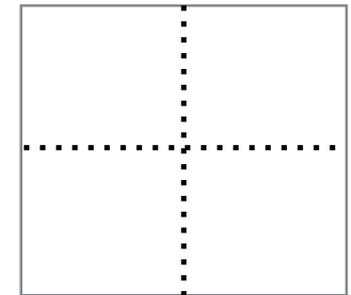
pDTMC

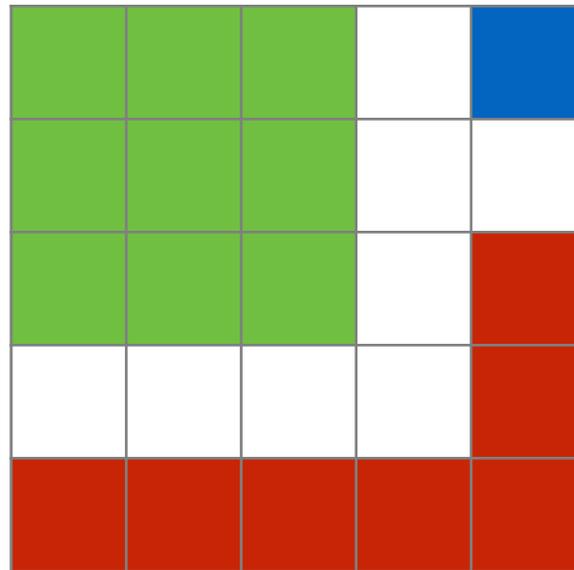


MDP



or.....





	instance	φ	#pars	#states	#trans	#par trans	l	safe	unsafe	neither	unkn	
pMIC	brp	(256,5)	E	2	20744	27651	13814	51	14.9%	79.2%	5.8%	0.2%
		(256,5)	P	4	20744	27651	13814	71	7.5%	51.0%	40.6%	0.8%
	crowds	(10,5)	P	2	104512	246082	51480	44	54.4%	41.1%	4.2%	0.3%
	nand	(10,5)	P	2	35112	52647	25370	21	21.4%	68.5%	6.9%	3.2%
pMIDP	brp	(256,5)	P	2	40721	55143	27800	153	6.6%	90.4%	3.0%	0.0%
	consensus	(4,2)	P	4	22656	75232	29376	357	2.6%	87.0%	10.4%	0.0%
	sav	(6,2,2)	P	4	379	1127	552	2	44.0%	15.4%	35.4%	5.3%
	zeroconf	(2)	P	2	88858	203550	80088	186	16.6%	77.3%	5.6%	0.5%

Parameter Lifting Performance

SMT TO (1h) everywhere

Covering 95%

	benchmark	instance	φ	#pars	#states	#trans	PLA		PRISM	
							#regions	direct	bisim	best
PMC	brp	(256,5)	P	2	19 720	26 627	37	6	14	TO
		(4096,5)	P	2	315 400	425 987	13	233	TO	TO
		(256,5)	E	2	20 744	27 651	195	8	15	TO
		(4096,5)	E	2	331 784	442 371	195	502	417	TO
		(16,5)	E	4	1 304	1 731	1 251 220	2 764	1 597	TO
		(32,5)	E	4	2 600	3 459	1 031 893	TO	2 722	TO
		(256,5)	E	4	20 744	27 651	TO	TO	TO	
	crowds	(10,5)	P	2	104 512	246 082	123	17	6	TO
		(15,7)	P	2	8 364 409	25 108 729	116	1 880	518	TO
		(20,7)	P	2	45 421 597	164 432 797	119	TO	2 935	TO
nand	(10,5)	P	2	35 112	52 647	469	22	30	TO ²	
	(25,5)	P	2	865 592	1 347 047	360	735	2 061	TO	
PMDP	brp	(256,5)	P	2	40 721	55 143	37	35	3 359	TO
		(4096,5)	P	2	647 441	876 903	13	3 424	TO	TO
	consensus	(2,2)	P	2	272	492	119	<1	<1	31 ⁴
		(2,32)	P	2	4 112	7 692	108	113	141	TO ⁴
		(4,2)	P	4	22 656	75 232	6 125	1 866	2 022	TO ⁴
		(4,4)	P	4	43 136	144 352	-	TO	TO	TO ⁴
	sav	(6,2,2)	P	2	379	1 127	162	<1	<1	TO ⁴
		(100,10,10)	P	2	1 307 395	6 474 535	37	1 612	TO	TO
		(6,2,2)	P	4	379	1 127	621 175	944	917	TO ⁴
	zeroconf	(10,3,3)	P	4	1 850	6 561	TO	TO	TO	TO ⁴
(2)		P	2	88 858	203 550	186	86	1 295	TO	
		(5)	P	2	494 930	1 133 781	403	2 400	TO	TO

What is the Output of Parameter Synthesis?

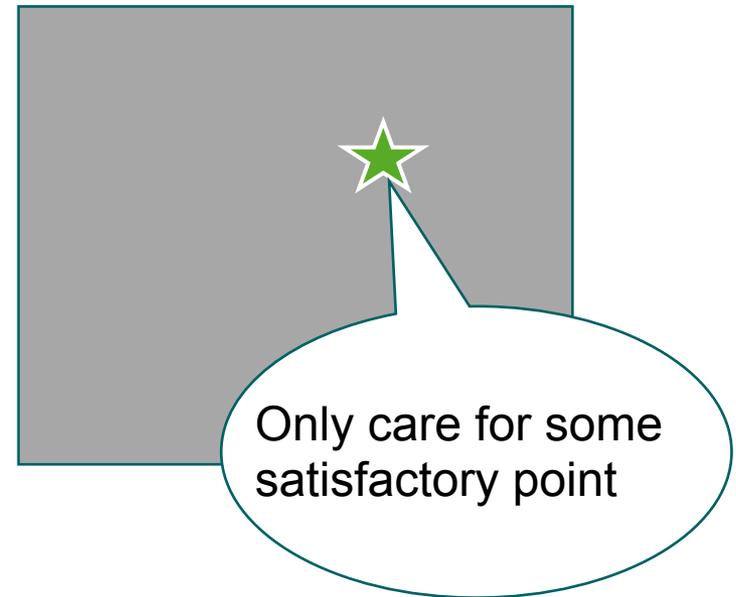
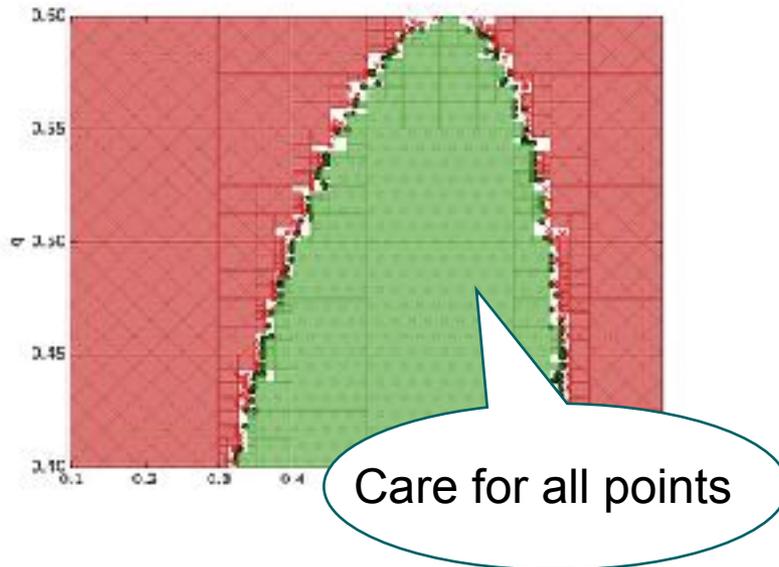
So far, three options have been considered in the literature

- Option A:
A generalisation of the output of non-parametric Markov Chain model checking
- Option B:
A concise description of parameter values that yield satisfactory performance
- Option C:
One parameter valuation that yields satisfactory performance

Finding satisfactory parameter valuations

A more practical approach

- Methods so far are limited to ~ 10 parameters.
- Applications as e.g. originating from control under partial observability require thousands of parameters.



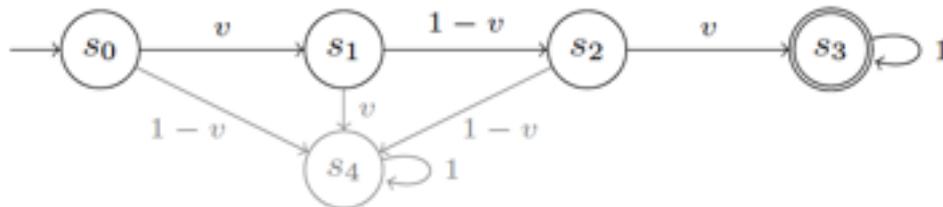
Curse of dimensionality

In more than 100 dimensions, sampling becomes a challenge.

- Sampling via model checking instantiated Markov chains.
- Select sampling points via, e.g., particle swarm optimisation: Fitness via model checking result.
- Neglects much of the underlying structure.

Use (non)linear optimisation?

Convex optimisation problems use structure more



pMCs typically are not convex
NLPs

Solution: Linearise concave
part, boost with model
checking

Set	Problem		Info			PSO			SMT	CCP		
	Inst	Spec	States	Trans.	Par.	tmin	tmax	tavg	t	t	solv	iter
Brp	16,2	$P_{\leq 0.1}$	98	194	2	0	0	0	40	0	30%	3
Brp	512,5	$P_{< 0.1}$	6146	12290	2	24	36	28	TO	33	24%	3
Crowds	10,5	$P_{< 0.1}$	42	82	2	4	5	5	8	4	2%	4
Nand	5,10	$P_{< 0.05}$	10492	20982	2	21	51	28	TO	22	21%	2
Zeroconf	10000	$E_{\leq 10010}$	10003	20004	2	2	4	3	TO	57	81%	3
GridA	4	$P_{> 0.84}$	1026	2098	72	11	11	11	TO	22	81%	11
GridB	8,5	$P_{\geq 0.84}$	8653	17369	700	409	440	427	TO	213	84%	8
GridB	10,6	$P_{\geq 0.84}$	16941	33958	1290	533	567	553	TO	426	84%	7
GridC	6	$E_{\leq 4.8}$	1665	305	168	261	274	267	TO	169	90%	23
Maze	5	$E_{< 14}$	1303	2658	590	213	230	219	TO	67	89%	8
Maze	5	$E_{< 6}$	1303	2658	590				TO	422	85%	97
Maze	7	$E_{\leq 6}$	2580	5233	1176	-	-		TO	740	90%	60
Netw	5,2	$E_{< 11.5}$	21746	63158	2420	312	523	359	TO	207	39%	3
Netw	5,2	$E_{\leq 10.5}$	21746	63158	2420	-	-		TO	210	38%	4
Netw	4,3	$E_{< 11.5}$	38055	97335	4545	-	-		TO	MO	-	-
Repud	8,5	$P_{> 0.1}$	1487	3002	360	16	22	18	TO	4	36%	2
Repud	8,5	$P_{\leq 0.05}$	1487	3002	360	273	324	293	TO	14	72%	4
Repud	16,2	$P_{< 0.01}$	790	1606	96	-	-		TO	15	78%	9
Repud	16,2	$P_{\geq 0.062}$	790	1606	96	-	-		TO	TO	-	-