## Concurrency Theory

Lecture 18: True Concurrency Semantics of Petri Nets (I)

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http://moves.rwth-aachen.de/teaching/ws-1718/ct

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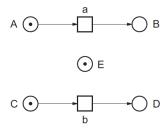


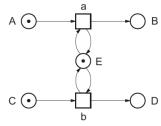
### **Overview**

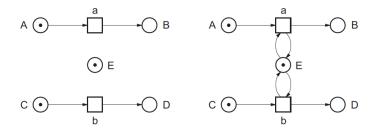
- Introduction
- 2 Nets and markings
- 3 The true concurrency semantics of Petri nets
- 4 Distributed runs
- **5** Summary

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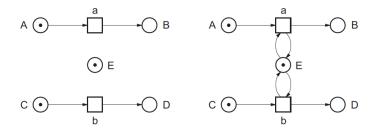
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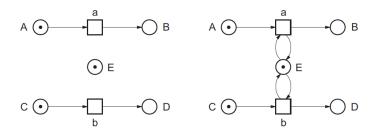


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This requires a finer perspective on transition execution.

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### Nets

#### Net

A Petri net N is a triple (P, T, F) where:

- P is the countable set of places
- ▶ T is the countable set of transitions with  $P \cap T = \emptyset$
- ▶  $F \subseteq (P \times T) \cup (T \times P)$  are the arcs.

Places and transitions are generically called nodes.

We assume that  ${}^{\bullet}t$  and  $t^{\bullet}$  are finite, for each  $t \in T$ .

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### Marking

A marking M of a net N = (P, T, F) is a mapping  $M : P \to \mathbb{I}N$ . For net N = (P, T, F) and marking  $M_0$ , the tuple  $(P, T, F, M_0)$  is called an elementary system net.  $M_0$  is the initial marking of N.

## Enabling and occurrence of a transition

A marking M enables a transition t if  $M(p) \ge 1$  for each place  $p \in {}^{\bullet} t$ .

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Transition t can occur in marking M if t is enabled at M. Its occurrence leads to marking M', denoted  $M \xrightarrow{t} M'$ , defined for place  $p \in P$  by:

$$M'(p) = M(p) - F(p, t) + F(t, p).$$

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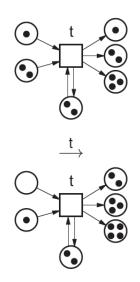
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# Reachable markings

### Step sequence

A sequence of transitions  $\sigma = t_1 t_2 \dots t_n$  is a step sequence if there exist markings  $M_1$  through  $M_n$  such that:

$$M_0 \xrightarrow{t_1} M_1 \xrightarrow{t_2} \cdots \xrightarrow{t_{n-1}} M_{n-1} \xrightarrow{t_n} M_n$$

Marking  $M_n$  is reached by the occurrence of  $\sigma$ , denoted  $M_0 \xrightarrow{\sigma} M_n$ .

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M is a reachable marking if there exists a step sequence  $\sigma$  with  $M_0 \xrightarrow{\sigma} M$ .

## Sequential runs

### Sequential run

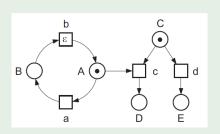
Let N be an elementary net system. A sequential run of N is a sequence

$$M_0 \xrightarrow{t_1} M_1 \xrightarrow{t_2} \cdots$$

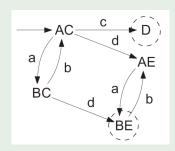
of steps of N starting with the initial marking  $M_0$ . A run can be finite or infinite. A finite run  $M_0 \xrightarrow{t_1} M_1 \xrightarrow{t_1} \cdot \xrightarrow{t_n} M_n$  is complete if  $M_n$  does not enable any transition.

# Marking graph

The marking graph of N has as nodes the reachable markings of N and as edges the reachable steps of N.



A sample elementary net system



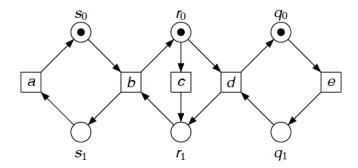
Its marking graph

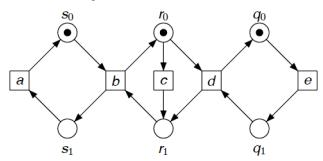
## The interleaving semantics of Petri nets

The interleaving semantics of a Petri net is its marking graph.

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 $s_0$ 

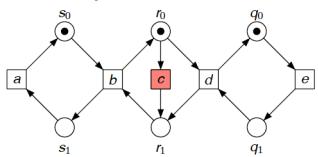
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 $\bullet$ 

 $q_0$ 

Ó



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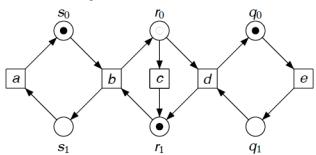


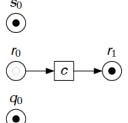
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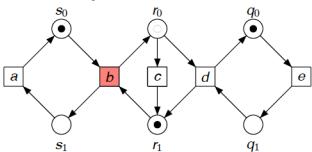


 $q_0$ 

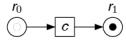




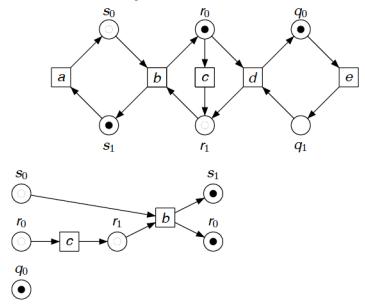


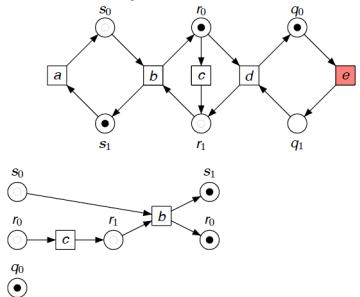


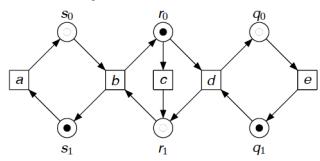


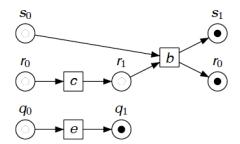


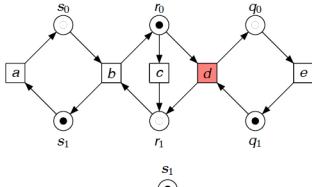
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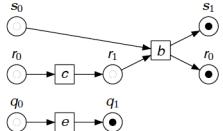


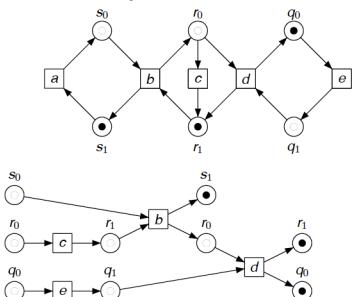


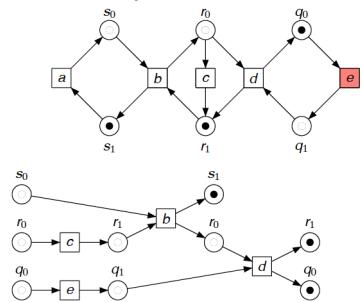


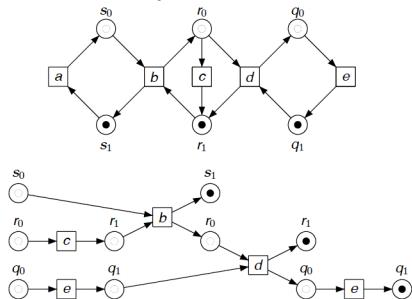


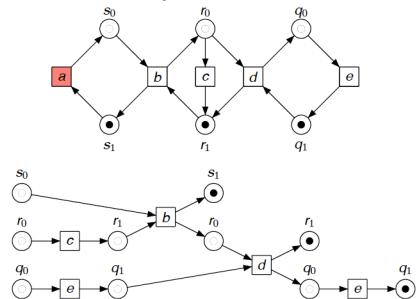


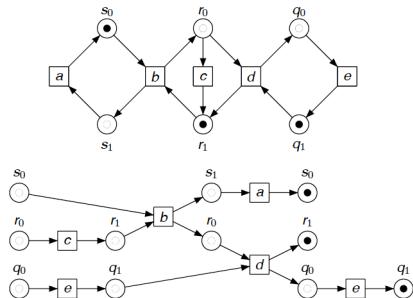


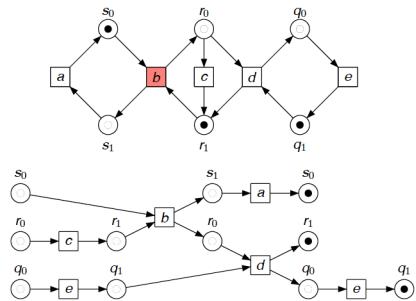




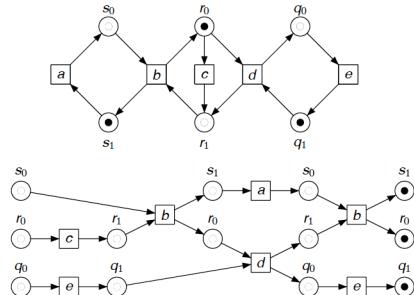








## The true concurrency semantics of Petri nets



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#### The true concurrency thesis:

The total order assumption does not correspond to physical reality and leads to awkward representations of simple phenomena

In interleaving semantics, a system composed of n independent components





has n! different executions

The automaton accepting them has  $2^n$  states

In true concurrency semantics, it has only one nonsequential execution

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A distributed run of a net is a partial-order represented as a net whose basic building blocks are actions<sup>1</sup>, simple nets

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An action is a labeled net  $A = (Q, \{v\}, G)$  with  $v \cap v = \emptyset$  and  $v \cup v = Q$ .

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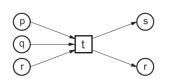
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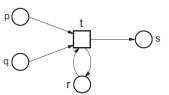
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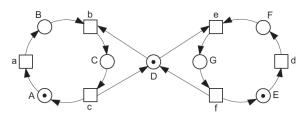


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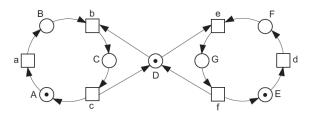


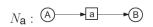
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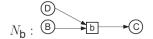
## Mutual exclusion net and its actions

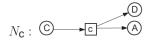


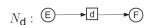
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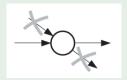
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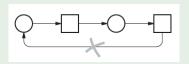
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#### Intuition

No place branches, no sequence of arcs forms a loop, and each sequence of arcs has a first node.





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A (possibly infinite) net  $K = (Q, V, G, M_0)$  is called a causal net iff:

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#### Lemma

Let  $N = (P, T, F, M_0)$  be a causal net. Then every step sequence:

$$M_0 \xrightarrow{t_1} M_1 \xrightarrow{t_2} \ldots \xrightarrow{t_k} M_k$$

of net N satisfies  $M_i \cap t_k^{\bullet} = \emptyset$  for all j = 0, ..., k-1.

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#### Proof.

Follows directly from the fact that the initial marking  $M_0$  is one-bounded, and by the above lemma.

### Absence of superfluous places and transitions

Let  $N = (P, T, F, M_0)$  be a causal net. Then there exists a possibly infinite step sequence

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A causal net thus contains no superfluous places and transitions, as every place is visited and every transition is fired in the above step sequence.

### Outset and end of a causal net

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The outset and end of causal net K = (Q, V, G, M) are defined by:

$${}^{\circ}K = \{ \ q \in Q \ | \ \ {}^{\bullet}q = \varnothing \, \} \quad \text{and} \quad K^{\circ} \ = \{ \ q \in Q \ | \ q^{\bullet} = \varnothing \, \}.$$

Places without an incoming arc form the outset  ${}^{\circ}K$ . The places without an outgoing arc form the end  $K^{\circ}$ .

#### Distributed run

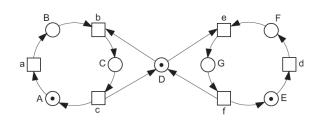
A distributed run of a one-bounded elementary net system N is:

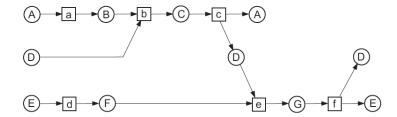
- 1. a labeled causal net  $K_N$
- 2. in which each transition t (with  $^{\bullet}t$  and  $t^{\bullet}$ ) is an action of N.

A distributed run  $K_N$  of N is complete iff (the marking)  ${}^{\circ}K$  represents the initial marking of N and (the marking)  $K_N^{\circ}$  does not enable any transition.

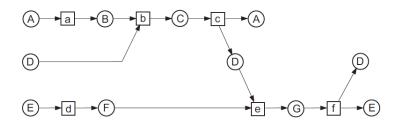
If N is clear from the context we just write K for  $K_N$ .

### A distributed run for mutual exclusion





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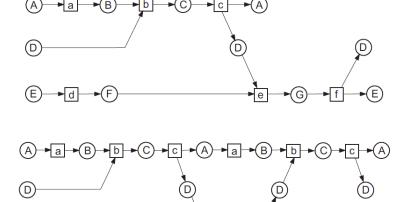
Distributed run of the mutual exclusion algorithm.

Actions  $N_a$ ,  $N_b$ ,  $N_c$  and  $N_d$  causally precede  $N_e$ . They form a chain.

 $N_a$  and  $N_d$  are not linked by actions; they are causally independent.

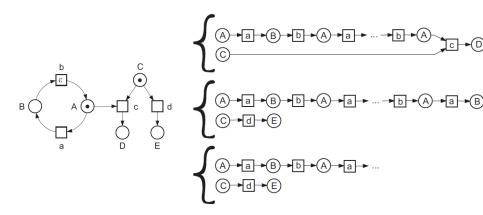
The same applies to  $N_b$  and  $N_d$  and  $N_c$  and  $N_d$ .

# Expansion of a distributed run for mutual exclusion



A distributed run (top) and its extension with actions b and c.

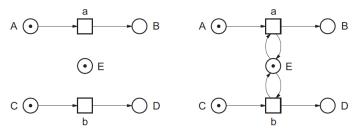
### More distributed runs



Various finite distributed runs and an infinite distributed run (right) of net (left).

### Causal order

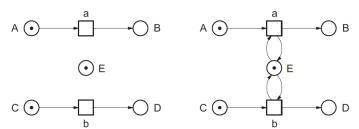
Opposed to sequential runs, distributed runs show the causal order of actions.



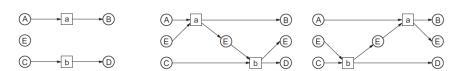
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## Causal order

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Nets with identical sequential runs (a occurs before b, or vice versa), but the left net has the left distributed run below, the right net both other ones:



### Composition of distributed runs

For i=1,2, let  $K_i=(Q_i,V_i,G_i)$  be causal nets, labeled with  $\ell_i$ . Let  $(Q_1 \cup V_1) \cap (Q_2 \cap V_2) = K_1^{\circ} = {}^{\circ}K_2$  and for each place  $p \in K_1^{\circ}$  let  $\ell_1(p) = \ell_2(p)$ .

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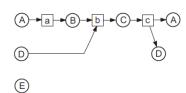
The composition  $K \bullet L$  is formed by identifying the end  $K^{\circ}$  of K with the outset  $^{\circ}L$  of L. To do this,  $K^{\circ}$  and  $^{\circ}L$  must represent the same marking.

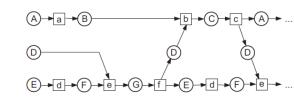
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Today: a characterization of distributed runs using homomorphisms.

<sup>&</sup>lt;sup>2</sup>Here h(X) for set X of nodes is defined by  $h(X) = \bigcup_{x \in X} h(x)$ .

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### Homomorphism

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#### Intuition

A homomorphism is a mapping between nets that preserves the nature of nodes and the environment of nodes. A homomorphism from  $N_1$  to  $N_2$  means that  $N_1$  can be folded onto a part of  $N_2$ , or in other words, that  $N_1$  can be obtained by partially unfolding a part of  $N_2$ .

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# Distributed run using homomorphisms

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[Best and Fernandez, 1988]

A distributed run of an elementary net system N is a pair (K, h) where K is a causal net and h is a homomorphism from K to N.<sup>4</sup>

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# **Examples**

### **Overview**

- Introduction
- 2 Nets and markings
- 3 The true concurrency semantics of Petri nets
- 4 Distributed runs
- **5** Summary

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- ▶ Distributed run = the "true concurrency" analogue to a sequential run