

Modeling and Verification of Probabilistic Systems

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<http://moves.rwth-aachen.de/teaching/ws-1516/movep15/>

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Overview

- 1 Recall: continuous-time Markov chains
- 2 Probability measure on CTMC paths
- 3 Reachability probabilities
 - Untimed reachability
 - Timed reachability
 - Reduction to transient analysis
 - Bisimulation and timed reachability
- 4 Summary

Continuous-time Markov chain

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A **CTMC** is a tuple $(S, \mathbf{P}, r, \iota_{\text{init}}, AP, L)$ where

- ▶ $(S, \mathbf{P}, \iota_{\text{init}}, AP, L)$ is a DTMC, and
- ▶ $r : S \rightarrow \mathbb{R}_{>0}$, the **exit-rate function**

Let $\mathbf{R}(s, s') = \mathbf{P}(s, s') \cdot r(s)$ be the transition rate of transition (s, s')

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- ▶ **residence** time in state s is exponentially distributed with **rate** $r(s)$.
- ▶ phrased alternatively, the **average** residence time of state s is $\frac{1}{r(s)}$.

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Residence time distribution

The probability to *take some* outgoing transition from s in $[0, t]$ is:

$$\int_0^t r(s) \cdot e^{-r(s) \cdot x} dx = 1 - e^{-r(s) \cdot t}$$

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- ▶ Cylinder set of finite interval-timed paths := set of all infinite timed paths with a prefix in the finite interval-timed path

Probability measure on CTMCs

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Let $s_0, \dots, s_k \in S$ with $\mathbf{P}(s_i, s_{i+1}) > 0$ for $0 \leq i < k$ and I_0, \dots, I_{k-1} non-empty intervals in $\mathbb{R}_{\geq 0}$ with rational bounds.

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The cylinder set spanned by $s_0, l_0, \dots, l_{k-1}, s_k$ thus consists of all infinite timed paths that have a prefix $\hat{\pi}$ that lies in $s_0, l_0, \dots, l_{k-1}, s_k$.

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σ -algebra of a CTMC

The σ -algebra associated with CTMC \mathcal{C} is the smallest σ -algebra $\mathcal{F}(\text{Paths}(s_0))$ that contains all cylinder sets $\text{Cyl}(s_0, l_0, \dots, l_{k-1}, s_k)$ where $s_0 \dots s_k$ is a path in the state graph of \mathcal{C} (starting in s_0) and l_0, \dots, l_{k-1} range over all sequences of non-empty intervals in $\mathbb{R}_{\geq 0}$.

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Solving the integral

$$Pr(Cyl(s_0, I_0, \dots, I_{k-2}, s_{k-1})) \cdot \mathbf{P}(s_{k-1}, s_k) \cdot (e^{-r(s_{k-1}) \cdot \inf I_{k-1}} - e^{-r(s_{k-1}) \cdot \sup I_{k-1}}).$$

Zeno theorem

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Zeno path

Path $s_0 \xrightarrow{t_0} s_1 \xrightarrow{t_1} s_2 \xrightarrow{t_2} s_3 \dots$ is called **Zeno**¹ if $\sum_i t_i$ converges.

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In case $\sum_i t_i$ does not diverge, the timed path represents an “unrealistic” computation where infinitely many transitions are taken in a finite amount of time.

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For all states s in any CTMC, $Pr\{\pi \in Paths(s) \mid \pi \text{ is Zeno}\} = 0$.

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Proof:

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$$\overline{F} U G = \{ \pi \in Paths(\mathcal{C}) \mid \exists i \in \mathbb{N}. \pi[i] \in G \wedge \forall j < i. \pi[j] \notin F \}$$

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Proof:

Consider $\diamond G$. $\diamond G$ is the union of all cylinders $Cyl(s_0, [0, \infty), \dots, [0, \infty), s_n)$ where $s_0, \dots, s_{n-1} \notin G$ and $s_n \in G$.

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$$x_s = \underbrace{\sum_{t \in S \setminus G} \mathbf{P}(s, t) \cdot x_t}_{\text{reach } G \text{ via } t \in S \setminus G} + \underbrace{\sum_{u \in G} \mathbf{P}(s, u)}_{\text{reach } G \text{ in one step}}$$

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As the above temporal logic formulas or events do not refer to elapsed time, it is not surprising that they can be checked on the embedded DTMC.

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Timed reachability probabilities: example

On the blackboard.

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Example

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Constrained timed reachability probabilities

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Let \mathcal{C} be a CTMC with finite state space S , $s \in S$, $t \in \mathbb{R}_{\geq 0}$ and $G, F \subseteq S$.

Aim: $Pr(s \models \overline{F} U^{\leq t} G) = Pr_s(\overline{F} U^{\leq t} G) = Pr_s\{\pi \in Paths(s) \mid \pi \models \overline{F} U^{\leq t} G\}$.

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$$x_s(t) = \int_0^t \sum_{s' \in S} \underbrace{R(s, s') \cdot e^{-r(s) \cdot x}}_{\text{probability to move to state } s' \text{ at time } x} \cdot \underbrace{x_{s'}(t-x)}_{\text{prob. to fulfill } \overline{F} U^{\leq t-x} G \text{ from } s'} dx$$

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Proof:

Left as an exercise.

Example

Overview

- 1 Recall: continuous-time Markov chains
- 2 Probability measure on CTMC paths
- 3 Reachability probabilities
 - Untimed reachability
 - Timed reachability
 - Reduction to transient analysis
 - Bisimulation and timed reachability
- 4 Summary

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- ▶ Timed reachability probabilities can be characterised as Volterra integral equation system.
- ▶ Computing timed reachability probabilities can be reduced to transient probabilities.
- ▶ Weak and strong bisimulation preserve timed reachability probabilities.