Verifying Probabilistic Programs Using a Hoare like Logic

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Seminar on Probabilistic Programs WS 2014/15

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• Aim: Verify claims regarding the variables of a program

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- For non-probabilistic programs:

Hoare Logic (1969)

• Formulate *Hoare triples* of the form

```
{ precondition } program { postcondition }
```

where the conditions are first order predicate formulae

- Check whether a Hoare triple holds, i.e.:
 - For every variable assignment satisfying the precondition
 - ...the resulting assignment after executing the program
 - satisfies the postcondition
- The *derivation system* H can be used for this purpose

The derivation system H:

$$\{p[x/e]\}\ x \coloneqq e\ \{p\} \qquad \text{(Assign)} \qquad \frac{\{p \land c\}\ \text{s}\ \{p\}}{\{p\}\ \text{while c do s od } \{p \land \neg c\}} \qquad \text{(While)}$$

$$\frac{\{p\} \text{ s } \{p'\} \text{ } \{p'\} \text{ } \text{s'} \{q\}}{\{p\} \text{ } \text{s; s'} \{q\}} \text{ (Seq) } \qquad \frac{p' \Rightarrow p \text{ } \{p\} \text{ } \text{s } \{q\} \text{ } q \Rightarrow q'}{\{p'\} \text{ } \text{s } \{q'\}} \qquad \text{(Cons)}$$

$$\langle x \bmod y = 0 \land (y = 2 \lor y = 3) \rangle$$
 if $(y = 2)$ then

$$x \coloneqq 3 \cdot x$$

else

$$x \coloneqq 2 \cdot x$$

fi
$$\langle x \mod 6 = 0 \rangle$$

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if (y=2) then
    \langle x \bmod y = 0 \land (y = 2 \lor y = 3) \land y = 2 \rangle
    x := 3 \cdot x
    \langle x \bmod 6 = 0 \rangle
else
    \langle x \bmod y = 0 \land (y = 2 \lor y = 3) \land y \neq 2 \rangle
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We need to extend the occuring notions!

- This is the topic of this talk
- Based on the paper of den Hartog (1999):
 Verifying Probabilistic Programs using a Hoare like Logic

Overview

- Probabilistic Programs
 - ullet The Language $\mathcal{L}_{\mathrm{pw}}$
 - Probabilistic States
 - ullet Semantics for $\mathcal{L}_{\mathrm{pw}}$
- Probabilistic Predicates
- 3 Hoare Logic for Probabilistic Programs
 - Hoare Triples
 - The Derivation System pH
 - Loops

The Language \mathcal{L}_{pw}

• The language of *probabilistic programs* (\mathcal{L}_{pw}) is given by:

```
\mathbf{s} ::= \mathsf{skip} \mid x := e \mid \mathbf{s}; \mathbf{s} \mid \mathbf{s} \oplus_r \mathbf{s} \mid \mathsf{if} \ c \mathsf{ then} \ \mathbf{s} \mathsf{ else} \ \mathbf{s} \mathsf{ fi} \mid \mathsf{while} \ c \mathsf{ do} \ \mathbf{s} \mathsf{ od}
```

- $\mathbf{s} \oplus_r \mathbf{s}'$ can be seen as a (biased) coin flip
 - s is executed with probability r
 - s' is executed with probability 1-r
- Semantics will be discussed later

Example: Probabilistic Program

Consider the Program $\mathbf{s} \in \mathcal{L}_{\mathrm{pw}}$:

```
(x\coloneqq 0\oplus_{0.3}x\coloneqq 1); if (x=0) then y\coloneqq 1 else y\coloneqq 0 fi
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- y = 0 with probability 0.7

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- But:
 x = y = 0 with probability 0

We need a notion to capture this information!

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After execution the variable assignment is either σ_1 or σ_2 , where

$$\sigma_1(x) = 1$$
 $\sigma_1(y) = 0$ and $\sigma_2(x) = 0$ $\sigma_2(y) = 1$

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Yielding the probabilistic state θ with

$$\theta(\sigma_1) = 0.7 \quad \theta(\sigma_2) = 0.3$$

- A probabilistic state assigns a probability ratio to every possible assignment of all variables
- A variable assignment (= deterministic state) can be seen as a mapping $\sigma \colon \mathrm{Var} \to \mathrm{Val}$
- ullet The set of all deterministic states is denoted by ${\cal S}$

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Let:
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 $\theta(\sigma_2) = 0.3$ $\sigma_1(x) = 1$ $\sigma_1(y) = 0$ $\sigma_2(x) = 0$ $\sigma_2(y) = 1$

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 θ can also be depicted by:

Operations on Probabilistic States

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Scaling

$$(r \cdot \theta)(\sigma) = r \cdot \theta(\sigma)$$

Merging

$$(\theta + \theta')(\sigma) = \theta(\sigma) + \theta'(\sigma)$$

Restricting

$$c?\theta(\sigma) = \begin{cases} \theta(\sigma) & \text{if } c \text{ is } true \text{ with respect to } \sigma \\ 0 & \text{otherwise} \end{cases}$$

Example: Scaling and Merging

• Consider the probabilistic states θ and θ' :

$ heta(\sigma_i)$	0.3	0.2	0.1		$ heta'(\sigma_i)$	0.2
$\sigma_i(x)$	1	0	0	-	$\sigma_i(x)$	1
$\sigma_i(y)$	0	1	0		$\sigma_i(y)$	1

0.2

Example: Scaling and Merging

• Consider the probabilistic states θ and θ' :

• The *scaled* state $0.5 \cdot \theta'$ is given by:

$$\begin{array}{c|cccc} (0.5 \cdot \theta')(\sigma_i) & 0.1 & 0.1 \\ \hline \sigma_i(x) & 1 & 1 \\ \sigma_i(y) & 1 & 0 \\ \hline \end{array}$$

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• The *merged* state $\theta + \theta'$ is given by:

$$\begin{array}{c|cccc} (\theta + \theta')(\sigma_i) & 0.2 & 0.5 & 0.2 & 0.1 \\ \hline \sigma_i(x) & 1 & 1 & 0 & 0 \\ \sigma_i(y) & 1 & 0 & 1 & 0 \\ \end{array}$$

Example: Restricting

• Consider the probabilistic state θ :

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and the condition c := (x = 1)

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• The *restricted* states $c?\theta$ and $\neg c?\theta$ are given by:

$$\begin{array}{c|c}
c?\theta(\sigma_i) & 0.3 \\
\hline
\sigma_i(x) & 1 \\
\sigma_i(y) & 0
\end{array}$$

$$\begin{array}{c|cccc} c?\theta(\sigma_i) & 0.3 \\ \hline \sigma_i(x) & 1 \\ \sigma_i(y) & 0 \end{array} \qquad \begin{array}{c|cccc} \neg c?\theta(\sigma_i) & 0.2 & 0.1 \\ \hline \sigma_i(x) & 0 & 0 \\ \hline \sigma_i(y) & 1 & 0 \end{array}$$

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• It holds that $c?\theta + \neg c?\theta = \theta$

Semantics for \mathcal{L}_{pw}

ullet The semantics for $\mathcal{L}_{\mathrm{pw}}$ is given by a mapping

$$\mathcal{D} \colon \mathcal{L}_{\mathrm{pw}} \to (\Pi \to \Pi)$$

where Π is the set of all probabilistic states

• $\mathcal{D}(s)(\theta) \in \Pi$ is obtained when starting in θ and executing s

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• $\mathcal{D}(s)(\theta) \in \Pi$ is obtained when starting in θ and executing s

$$\mathcal{D}(\mathsf{skip})(\theta) = \theta$$

$$\mathcal{D}(\mathsf{s}; \mathsf{s}')(\theta) = \mathcal{D}(\mathsf{s}')(\mathcal{D}(\mathsf{s})(\theta))$$

$$\mathcal{D}(\mathsf{s} \oplus_r \mathsf{s}')(\theta) = \left(r \cdot \mathcal{D}(\mathsf{s})(\theta)\right) + \left((1 - r) \cdot \mathcal{D}(\mathsf{s}')(\theta)\right)$$

$$\vdots$$

- We need to express conditions on probabilistic states
- Evaluation to either true or false is desired
- Deterministic predicates as used for non-probabilistic programs are not feasible

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Solution: Probabilistic predicates

Consider the probability that a deterministic predicate holds

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•
$$\theta \models x = 0 \land y \le 1$$
 ... only holds with probability 0.3

$$\bullet \ \theta \models \mathbb{P}(x = 0 \land y \le 1) = 0.3$$

Solution: Probabilistic predicates

Consider the probability that a deterministic predicate holds

• $\mathbb{P}(dp) \prec r$ is a probabilistic predicate for $\prec \in \{<, \leq, =, \geq, >\}$

$$\theta \models \mathbb{P}(dp) \prec r \iff \sum_{\sigma \models dp} \theta(\sigma) \prec r$$

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More probabilistic predicates:

- $\bullet \neg p$, $p \land q$, $\exists i : p$,
- \bullet p[x/e]
- \bullet $r \cdot p$, p + q, c?p

(common logical operators)

(replace $x \in \text{Var with } e \in \text{Exp}$)

(describe scaled, merged, restricted versions of states satisfying p, q)

Scaled States

 $\theta \models r \cdot p$ if θ is a scaled state $r \cdot \theta'$ for some state θ' that satisfies p

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Example

• Consider the state θ :

$$\begin{array}{c|cccc} \theta(\sigma_i) & 0.2 & 0.1 & 0.2 \\ \hline \sigma_i(x) & 1 & 0 & 0 \\ \sigma_i(y) & 1 & 1 & 0 \\ \hline \end{array}$$

and the predicate
$$p \coloneqq \left(\mathbb{P}(x=0) = 0.6\right) \land \left(\mathbb{P}(y=1) = 0.6\right)$$

 $\bullet \theta \models 0.5 \cdot p$?

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• Consider the state θ :

and the predicate
$$p \coloneqq \Big(\mathbb{P}(x=0) = 0.6\Big) \land \Big(\mathbb{P}(y=1) = 0.6\Big)$$

• $\theta \models 0.5 \cdot p$ since $\theta = 0.5 \cdot \theta'$ and $\theta' \models p$

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$$\theta \models p + q$$
 if θ is a merged state $\theta_1 + \theta_2$ for some states θ_1, θ_2 with $\theta_1 \models p$ and $\theta_2 \models q$

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Example

• Consider the state θ and the predicates p and q:

$$\begin{array}{c|ccccc} \theta(\sigma_i) & 0.2 & 0.3 & 0.1 & 0.4 \\ \hline \sigma_i(x) & 1 & 1 & 0 & 0 \\ \sigma_i(y) & 1 & 0 & 1 & 0 \\ \hline \end{array}$$

$$p := \mathbb{P}(x = 0 \land y = 1) = 0.1$$

 $q := \mathbb{P}(x = 0) = 0.2$

• $\theta \models p + q$?

Merged States

$$\theta \models p + q$$
 if θ is a merged state $\theta_1 + \theta_2$ for some states θ_1, θ_2 with $\theta_1 \models p$ and $\theta_2 \models q$

Example

• Consider the state θ and the predicates p and q:

• $\theta \models p + q$ since $\theta = \theta_1 + \theta_2$, $\theta_1 \models p$ and $\theta_2 \models q$ with

$\theta_1(\sigma_i)$	0.2	0.3	0.1	0.2	$\theta_2(\sigma_i)$	0.2
$\sigma_i(x)$	1	1	0	0	$\sigma_i(x)$	0
$\sigma_i(y)$	1	0	1	0	$\sigma_i(y)$	0

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Restricted States

 $\theta \models c?p$ if θ is a restricted state $c?\theta'$ for some state θ' that satisfies p

Example

• Consider the states θ and θ' :

• For c := (y = 1) it holds that $\theta = c?\theta'$

 $\implies \theta \models c?p$ for all predicates p that are satisfied by θ'

$$\implies \theta \models \mathbb{P}(\neg c) = 0$$

$$\implies \theta \models (\mathbb{P}(true) = r) \leftrightarrow (\mathbb{P}(c) = r)$$

•
$$[dp] := \mathbb{P}(dp) = 1$$

•
$$p \oplus_r q := (r \cdot p) + ((1-r) \cdot q)$$

- \bullet $\lceil dp \rceil := \mathbb{P}(dp) = 1$
- $p \oplus_r q := (r \cdot p) + ((1-r) \cdot q)$

Example

• Consider the state θ and the predicate p:

$$p = [y = 1] \lor [y = 0]$$

•
$$\theta \not\models p$$

- $\bullet \ [dp] \coloneqq \mathbb{P}(dp) = 1$
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Example

• Consider the state θ and the predicate p:

$$\begin{array}{c|cccc} \theta(\sigma_i) & 0.3 & 0.7 \\ \hline \sigma_i(y) & 1 & 0 \end{array} \qquad p = [y = 1] \lor [y = 0]$$

- $\theta \not\models p$
- $\theta \models p \oplus_{0.3} p$ since $\theta = \theta_1 + \theta_2$

$$\begin{array}{c|cccc} \theta_1(\sigma_i) & 0.3 \\ \hline \sigma_i(y) & 1 & \hline & \sigma_i(y) & 0 \end{array}$$

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Example

• Consider the state θ and the predicate p:

$$\begin{array}{c|cccc} \theta(\sigma_i) & 0.3 & 0.7 \\ \hline \sigma_i(y) & 1 & 0 \end{array} \qquad p = [y = 1] \lor [y = 0]$$

- $\bullet \theta \not\models p$
- $\theta \models p \oplus_{0.3} p$ since $\theta = \theta_1 + \theta_2 = 0.3 \cdot \theta'_1 + 0.7 \cdot \theta'_2$ where

Note that: $\theta_1', \theta_2' \models p$

Hoare Triples for Probabilistic Programs

• Almost similar to the non-probabilistic case

Hoare Triples for Probabilistic Programs

- Almost similar to the non-probabilistic case
- A *Hoare triple* is of the form $\{p\}$ s $\{q\}$
 - p and q are probabilistic predicates called precondition and postcondition
 - s is a probabilistic program
- $\{p\}$ s $\{q\}$ is said to *hold* if:
 - ullet For all probabilistic states satisfying the precondition p
 - ...the resulting state after executing the program s
 - ... satisfies the postcondition q
- In this case we write \models { p } \mathbf{s} { q }

Consider the Program s:

```
\begin{aligned} &(x\coloneqq 0\oplus_{0.3}x\coloneqq 1);\\ &\text{if }(x=0)\text{ then}\\ &y\coloneqq 1\\ &\text{else}\\ &y\coloneqq 0\\ &\text{fi} \end{aligned}
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- $\bullet \not\models \{ [true] \} \mathbf{s} \{ \mathbb{P}(x=0 \land y=0) {>} 0 \}$
- $\not\models \{\mathbb{P}(true) \geq 0\}$ s $\{\mathbb{P}(y=0) = 0.7\}$

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- $\bullet \not\models \{ [true] \} \mathbf{s} \{ \mathbb{P}(x=0 \land y=0) {>} 0 \}$
- $\not\models \{\mathbb{P}(true) \ge 0\}$ s $\{\mathbb{P}(y=0) = 0.7\}$
- $\bullet \models \{ [true] \} \mathbf{s} \{ \mathbb{P}(y=0) = 0.7 \}$

- The derivation system H needs to be adjusted to work for probabilistic programs:
 - Handling of probabilistic choices: $s \oplus_r s'$
 - Handling of probabilistic states where a Boolean condition $c \in BC$ evaluates to true (or false) with probability < 1
- This yields the new derivation system pH

$$\{p\} \text{ skip } \{p\}$$
 (Skip)

$$\{p[x/e]\}\ x := e\ \{p\}$$
 (Assign)

$$\frac{\{p\} \mathbf{s} \{p'\} \{p'\} \mathbf{s}' \{q\}}{\{p\} \mathbf{s}; \mathbf{s}' \{q\}}$$
(Seq)

$$\frac{p' \Rightarrow p \quad \{p\} \text{ s } \{q\} \quad q \Rightarrow q'}{\{p'\} \text{ s } \{q'\}} \text{(Cons)}$$

$$\frac{\{p\} \mathsf{s} \{q\} \quad \{p\} \mathsf{s}' \{q'\}}{\{p\} \mathsf{s} \oplus_r \mathsf{s}' \{q \oplus_r q'\}} \quad (\mathsf{Prob})$$

$$\frac{\{p\} \mathbf{s} \{q\} \quad \{p'\} \mathbf{s} \{q\}}{\{p \lor p'\} \mathbf{s} \{q\}} \quad \text{(Or)}$$

$$\frac{\{p[j]\} \mathbf{s} \{q\} \quad j \notin p, q}{\{\exists i \colon p[i]\} \mathbf{s} \{q\}}$$
 (Exists)

$$\frac{\{p\} \mathbf{s} \{q[j]\} \quad j \notin p, q}{\{p\} \mathbf{s} \{\forall i : q[i]\}}$$
 (Forall)

$$\frac{\{c?p\} \text{ s } \{q\} \quad \{\neg c?p\} \text{ s' } \{q'\}}{\{p\} \text{ if } c \text{ then s else s' fi } \{q+q'\}} \text{ (If)}$$

$$\frac{p \text{ invariant for } \langle c, \mathbf{s} \rangle}{\{p\} \text{ while } c \text{ do s od } \{p \land \mathbb{P}(c) = 0\}}$$
(While)

pH is correct:

- Only valid Hoare triples can be derived from pH
- This can be shown by induction on the depth of a proof tree
- Consider the last used rule and conclude that the obtained Hoare triple holds

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- Only valid Hoare triples can be derived from pH
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Is pH complete?

- Can we derive every valid Hoare triple from pH?
- This question is still open

Consider again the Program s:

```
(x := 0 \oplus_{0.3} x := 1);

if (x = 0) then

y := 1

else

y := 0

fi
```

We want to show that

$$\models \{\,[true]\,\} \text{ s } \{\,\mathbb{P}(y=0){=}0.7\,\}$$

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We want to show that

$$\models \{ [true] \}$$
 s $\{ \mathbb{P}(y=0)=0.7 \}$

Auxiliary statement:

$$\models \{ [true] \} \ x := 0 \oplus_{0.3} x := 1 \{ (\mathbb{P}(x=0)=0.3) \land (\mathbb{P}(x \neq 0)=0.7) \}$$

$$\{ [true] \} x := 0 \oplus_{0.3} x := 1 \{ (\mathbb{P}(x=0)=0.3) \land (\mathbb{P}(x \neq 0)=0.7) \}$$

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Show that

$$[x=0] \oplus_{0.3} [x \neq 0]$$
 implies $(\mathbb{P}(x=0)=0.3) \land (\mathbb{P}(x \neq 0)=0.7)$

Proof:

$$\theta \models [x = 0] \oplus_{0.3} [x \neq 0]$$

$$\implies \theta \models 0.3 \cdot [x = 0] + 0.7 \cdot [x \neq 0]$$

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$$\theta \models [x = 0] \oplus_{0.3} [x \neq 0]$$

$$\Rightarrow \theta \models 0.3 \cdot [x = 0] + 0.7 \cdot [x \neq 0]$$

$$\Rightarrow \theta = \theta_1 + \theta_2 \text{ with } \theta_1 \models 0.3 \cdot ([x = 0])$$

$$\theta_2 \models 0.7 \cdot ([x \neq 0])$$

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$$\Rightarrow \theta = \theta_1 + \theta_2 \text{ with } \theta_1 \models 0.3 \cdot ([x = 0] \land \mathbb{P}(x \neq 0) = 0)$$

$$\theta_2 \models 0.7 \cdot ([x \neq 0] \land \mathbb{P}(x = 0) = 0)$$

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$$\begin{split} \theta &\models [x=0] \oplus_{0.3} [x \neq 0] \\ \Longrightarrow \theta &\models 0.3 \cdot [x=0] + 0.7 \cdot [x \neq 0] \\ \Longrightarrow \theta &= \theta_1 + \theta_2 \text{ with } \theta_1 \models 0.3 \cdot \left([x=0] \land \mathbb{P}(x \neq 0) = 0 \right) \\ \theta_2 &\models 0.7 \cdot \left([x \neq 0] \land \mathbb{P}(x=0) = 0 \right) \\ \Longrightarrow \theta &= \theta_1 + \theta_2 \text{ with } \theta_1 \models \left(\mathbb{P}(x=0) = 0.3 \right) \land \left(\mathbb{P}(x \neq 0) = 0 \right) \\ \theta_2 &\models \left(\mathbb{P}(x \neq 0) = 0.7 \right) \land \left(\mathbb{P}(x=0) = 0 \right) \end{split}$$

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$$\{p[x/e]\} x \coloneqq e \{p\} \text{ (Assign)}$$

$$(x \coloneqq 0 \oplus_{0.3} x \coloneqq 1);$$

if
$$(x=0)$$
 then

$$y := 1$$

Recall the derivation rules:

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$$\langle [true] \rangle$$

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$$u := 0$$

$$\langle \mathbb{P}(y=0)=0.7 \rangle$$

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$$\begin{split} &\langle [true] \rangle \\ &(x \coloneqq 0 \oplus_{0.3} x \coloneqq 1); \\ &\langle \left(\mathbb{P}(x=0) {=} 0.3 \right) \wedge \left(\mathbb{P}(x \neq 0) {=} 0.7 \right) \rangle \end{split}$$
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$$u \coloneqq 0$$

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$$\begin{split} &\langle \big(x\neq 0\big)? \big(\mathbb{P}(x\neq 0){=}0.7\big)\rangle\\ &\langle \mathbb{P}(0=0){=}0.7\rangle\\ &y \coloneqq 0\\ &\langle \mathbb{P}(y=0){=}0.7\rangle\\ &\text{fi}\\ &\langle \big(\mathbb{P}(y=0){=}0\big)+\big(\mathbb{P}(y=0){=}0.7\big)\rangle\\ &\langle \mathbb{P}(y=0){=}0.7\rangle \end{split}$$

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While Loops

Recall:
$$\frac{p \text{ invariant for } \langle c, \mathbf{s} \rangle}{\{p\} \text{ while } c \text{ do s od } \{p \land \mathbb{P}(c) = 0\}} \text{ (While)}$$

When is a predicate p invariant for $\langle c, s \rangle$?

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 If while c do s od always terminates (independent of probabilistic choices), it suffices to show

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When is a predicate p invariant for $\langle c, s \rangle$?

 If while c do s od always terminates (independent of probabilistic choices), it suffices to show

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 if c then s else skip fi $\{p\}$

• Otherwise, it is additionally required that p is $\langle c, s \rangle$ -closed (Definition not trivial and therefore omitted in this talk)

Conclusion

- The idea of Hoare triples can be applied to probabilistic programs by using probabilistic states and probabilistic predicates
- Proving correctness of Hoare triples can be challenging
- A new *derivation system* pH can be used for this purpose

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Thank you for your attention!

Semantics for \mathcal{L}_{pw}

ullet The semantics for $\mathcal{L}_{\mathrm{pw}}$ is given by a mapping

$$\mathcal{D} \colon \mathcal{L}_{pw} \to (\Pi \to \Pi)$$

where Π is the set of all probabilistic states

$$\begin{split} \bullet \ \mathcal{D}(\mathbf{s})(\theta) \in \Pi \ \text{is obtained when starting in } \theta \ \text{and executing } \mathbf{s} \\ \mathcal{D}(\mathsf{skip})(\theta) &= \theta \\ \mathcal{D}(x := e)(\theta) = \theta[x/\mathrm{eval}(e)] \\ \mathcal{D}(\mathbf{s}; \mathbf{s}')(\theta) &= \mathcal{D}(\mathbf{s}')(\mathcal{D}(\mathbf{s})(\theta)) \\ \mathcal{D}(\mathbf{s} \oplus_r \mathbf{s}')(\theta) &= \left(r \cdot \mathcal{D}(\mathbf{s})(\theta)\right) + \left((1-r) \cdot \mathcal{D}(\mathbf{s}')(\theta)\right) \\ \mathcal{D}(\text{if } c \ \text{then } \mathbf{s} \ \text{else } \mathbf{s}' \ \text{fi})(\theta) &= \left(\mathcal{D}(\mathbf{s})(c?\theta)\right) + \left(\mathcal{D}(\mathbf{s}')(\neg c?\theta)\right) \\ \mathcal{D}(\text{while } c \ \text{do } \mathbf{s} \ \text{od})(\theta) &= \text{the least fixed point of } \Psi_{\langle c, \mathbf{s} \rangle} \\ \Psi_{\langle c, \mathbf{s} \rangle}(\psi)(\theta) &= \psi \left(\mathcal{D}(\mathbf{s})(c?\theta)\right) + \neg c?\theta \end{split}$$

- ullet Consider sequences of states $(\theta_n)_{n\in\mathbb{N}}$ where
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Example

- Consider: while $\underbrace{(x=0)}_{=:c}$ do $\underbrace{x:=1\oplus_{0.5}\text{skip}}_{=:s}$ od

- Consider sequences of states $(\theta_n)_{n\in\mathbb{N}}$ where
 - θ_n corresponds to the state reached after n iterations of while c do s od
 - $\theta_n \models p$ for the considered predicate p
- The limit of the sequence $(\neg c?\theta_n)_{n\in\mathbb{N}}$ also has to satisfy p

Example

- Consider: while $\underbrace{(x=0)}_{=:c}$ do $\underbrace{x:=1\oplus_{0.5}\text{skip}}_{=:s}$ od
- One of the sequences might be: $\begin{array}{c|cc} \theta_n(\sigma_i) & 0.5^n & 1-0.5^n \\ \hline \sigma_i(x) & 0 & 1 \\ \hline \end{array}$

- ullet Consider sequences of states $(\theta_n)_{n\in\mathbb{N}}$ where
 - ullet θ_n corresponds to the state reached after n iterations of while c do s od
 - $\theta_n \models p$ for the considered predicate p
- The limit of the sequence $(\neg c?\theta_n)_{n\in\mathbb{N}}$ also has to satisfy p

Example

- $\bullet \ \ \text{Consider: while} \ \underbrace{(x=0)}_{=:c} \ \ \text{do} \ \underbrace{x \coloneqq 1 \oplus_{0.5} \, \text{skip}}_{=:s} \ \ \text{od}$
- The limit of $\frac{\neg c?\theta_n(\sigma_i) \mid 1 0.5^n}{\sigma_i(x) \mid 1}$ is $\frac{\theta(\sigma_i) \mid 1}{\sigma_i(x) \mid 1}$

Consider a program while c do s od and a probabilistic predicate p

- A $\langle c, \mathbf{s} \rangle$ -sequence within p is a sequence of probabilistic states $(\theta_n)_{n \in \mathbb{N}}$ such that
 - $\theta_n \models p$ for all $n \in \mathbb{N}$
 - $(\neg c?\theta_n)_{n\in\mathbb{N}}$ is an ascending chain
 - the probability for $\neg c$ in the state θ_n is at least the n-step termination ratio, i.e.,

$$\sum_{\sigma \models \neg c} \theta_n(\sigma) \ge r_{\langle c, \mathbf{s} \rangle}^n.$$

where $r^n_{\langle c, \mathbf{s} \rangle}$ is the minimum probability that, starting from a state satisfying p, the loop terminates within n steps

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• The predicate p is $\langle c, s \rangle$ -closed if for all $\langle c, s \rangle$ -sequences $(\theta_n)_{n \in \mathbb{N}}$ within p the least upper bound of the chain $(\neg c?\theta_n)_{n \in \mathbb{N}}$ satisfies p.