

Sheet 1 (Complexity of the Fixpoint Iteration):

(3 Points)

In the lecture we saw that the fixpoint iteration requires at most $m \cdot n$ steps, where m is the height of the partial order while n is the number of program points (i.e. labels). But how fast is the iterative algorithm for a concrete analysis (here: live variables)?

a) Show that LVA has the following property:

Let $c \in Cmd$, $x \in Var_c$ and $l \in L_c$. If x is live on the exit of l , then there exists an **acyclic** path from B^l to a use of x that does not re-define x .

b) Show that (standard) fixpoint iteration requires at most $|L_c|$ steps for convergence in case of LVA.

Sheet 2 (Extending Interval Analysis):

(2 Points)

The WHILE-language as presented in the lecture does not feature a division operator. In this exercise we aim to incorporate this operator in the language and adapt the interval analysis from the lecture accordingly.

a) Extend the val_b function for interval analysis to also account for division. In the case of a division by zero, you are to assume that every value is a valid result.

b) Show that the transfer functions of interval analysis (including the division operator) are monotonic.

Sheet 3 (Assertions for Interval Analysis):

(2 Points)

Consider the interval analysis using assertions. Let us now restrict the Boolean expressions to the following subset $BExp^-$ of $BExp$:

$$b := true \mid false \mid x_1 = x_2 \mid x_1 < x_2 \text{ with } x_1, x_2 \in Var_c$$

a) Give an evaluation function for statements $assert(b)$, $b \in BExp^-$ computing accurate intervals for each $x \in Var_c$.

b) Extend $BExp^-$ by the logical disjunction. Give a "precise", but "safe" approximation of the resulting intervals.

Sheet 4 (Type Correctness of Java Bytecode):

(3 Points)

Perform a *type correctness* analysis for the following Java bytecode. Check that the return value is of type C and that the program is type safe. The return value is the reference that remains on the operation stack after termination of the method. The bytecode uses three classes A, B and C that are not related. Register one is initialised with type A and the second with type B, i.e. $R(0) = A$ and $R(1) = B$.

```
1  aload 1
2  iconst 1
3  invoke B m C(int)
4  astore 0
5  aload 0
6  getfield C f int
7  iconst 0
8  if_icmpeq 1
9  aload 0
10 areturn
```
