

Theoretical Foundations of the UML

Lecture 12: Realisability for Regular Sets of MSCs

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- 1 Realisability and safe realisability
- 2 Regular MSCs , *MSGs*, *CFMs*
- 3 Regularity and realisability for MSCs
- 4 Regularity and realisability for MSGs
 - Communication closedness

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- 2 Regular MSCs
- 3 Regularity and realisability for MSCs
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Definition (Realisability)

- ① MSC M is **realisable** whenever $\{M\} = \mathcal{L}(\mathcal{A})$ for some CFM \mathcal{A} .
- ② A finite set $\{M_1, \dots, M_n\}$ of MSCs is **realisable** whenever $\{M_1, \dots, M_n\} = \mathcal{L}(\mathcal{A})$ for some CFM \mathcal{A} .
- ③ MSG G is **realisable** whenever $\mathcal{L}(G) = \mathcal{L}(\mathcal{A})$ for some CFM \mathcal{A} .

Definition (Safe realisability)

Same as above except that the CFM should be deadlock-free.

Summary of results

Approach so far:

The (safe) realisation of a (finite) set of MSCs by a weak CFM is the one where the automaton \mathcal{A}_p of process p generates the projections of these MSCs on p .

sufficient + necessary conditions

Results so far:

- 1 Conditions for (safe) realisability for finite sets of MSCs.
- 2 Checking safe realisability for finite sets of MSCs is in **P**.
- 3 Checking realisability for finite sets of MSCs is **co-NP** complete.

Some remaining questions

- Can similar results be obtained for **larger classes** of MSGs?
 - What happens if we allow **synchronisation messages**?
 - recall that weak CFMs do not involve synchronisation messages
 - How do we obtain a CFM realising an MSG **algorithmically**?
 - in particular, for local-choice MSGs
 - Are there **"simple" conditions on MSGs that guarantee realisability**?
 - e.g., easily identifiable subsets of (safe) realisable MSGs
- sufficient*
- easy to check*

Today's lecture

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(Safe) Realisability of a **regular** set of MSCs.

Or, equivalently: (safe) realisability of a **regular** set of well-formed words.

(
regular language

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Results:

- 1 Checking whether a regular language L is well-formed is decidable.
- 2 For well-formed language L :
 L is regular iff it is (safely) realisable by a \forall -bounded CFM.
- 3 Checking whether an MSG is regular is undecidable.
- 4 Every communication-closed MSG is regular.
- 5 Checking whether an MSG is comm.-closed is coNP-complete.

= same complexity as checking whether a finite set of MSCs is realisable by a weak CFM.

Today's lecture

(Safe) Realisability of a **regular** set of MSCs.

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Results:

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- 4 Every communication-closed MSG is regular.
- 5 Checking whether an MSG is comm.-closed is coNP-complete.
- 6 Checking whether an MSG is locally communication-closed is in P.

- 1 Realisability and safe realisability
- 2 Regular MSCs
- 3 Regularity and realisability for MSCs
- 4 Regularity and realisability for MSGs
 - Communication closedness

Definition (Regular MSCs, MSGs, and CFMs)

- 1 $\mathcal{M} = \{M_1, \dots, M_n\}$ with $n \in \mathbb{N} \cup \{\infty\}$ is called regular if $\underline{Lin(\mathcal{M})} = \bigcup_{i=1}^n \underline{Lin(M_i)}$ is a regular word language over Act^* .
- 2 MSG G is regular if $Lin(G)$ is a regular word language over Act^* .
- 3 CFM \mathcal{A} is regular if $Lin(\mathcal{A})$ is a regular word language over Act^* .

Here, Act is the set of actions in \mathcal{M} , G , and \mathcal{A} , respectively.

$$Lin(\mathcal{M}) = a^*b^*$$

ε is regular

\emptyset is regular

$\forall a \in \Sigma. \{a\}$ is regular

if A and B are regular, then $A+B$ (or $A \cup B$), $A.B$ and A^*

Definition (Regular MSCs, MSGs, and CFMs)

- 1 $\mathcal{M} = \{ M_1, \dots, M_n \}$ with $n \in \mathbb{N} \cup \{ \infty \}$ is called **regular** if $Lin(\mathcal{M}) = \bigcup_{i=1}^n Lin(M_i)$ is a regular word language over Act^* .
- 2 MSG G is **regular** if $Lin(G)$ is a regular word language over Act^* .
- 3 CFM \mathcal{A} is **regular** if $Lin(\mathcal{A})$ is a regular word language over Act^* .

Here, Act is the set of actions in \mathcal{M} , G , and \mathcal{A} , respectively.

Lemma:

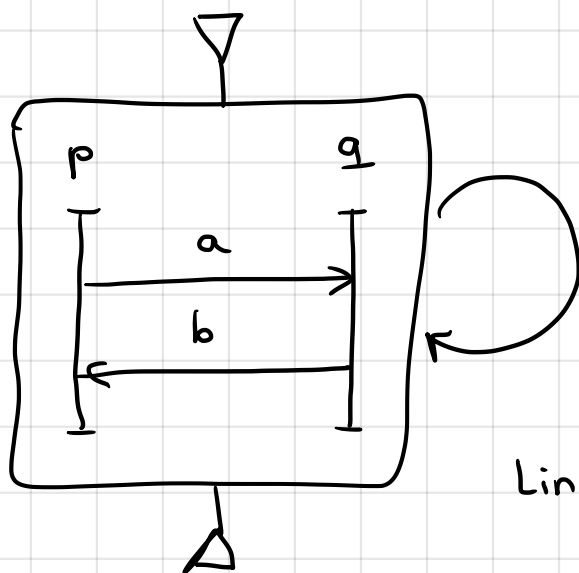
Every \forall -bounded CFM is regular.

Why?

↳ has finitely many configurations.
its configuration graph is a finite-state automaton

Examples

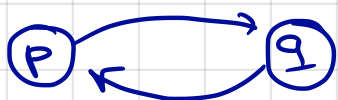
A.



claim: this MSG is regular.

$$Lin(A) = (! (p, q, a) ? (q, p, a) ! (q, p, b) ? (p, q, b))^+$$

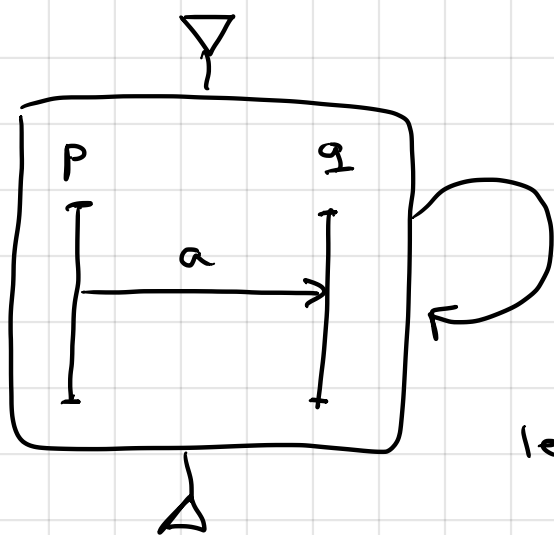
communication closed



$= (! a ? a ! b ? b)^+$
is a regular language

B.

G'



claim: this MSG is not regular.

let $!(p, q, a)$ be "["
(open bracket)
 $?(q, p, a)$ be "]"
(closing bracket)

not
comm. closed



Then $L(G') = \text{Dyck language} = \underline{\text{not}} \text{ regular}$

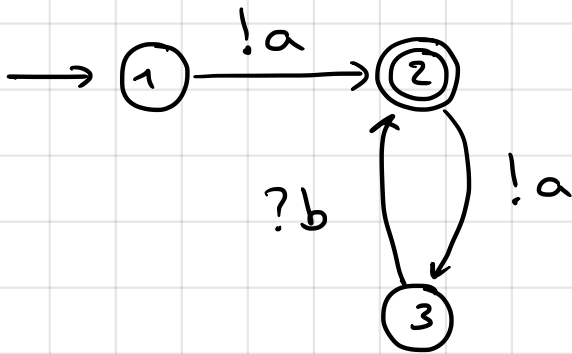
= language of words that contained a
balanced set of brackets "[" and "]"

e.g. [[]] or [[] [[]]] etc.

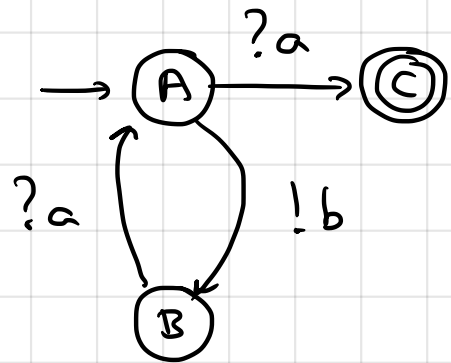
not [] []

(Yannakakis example)

C. CFM



A_p



A_q

Claim: this CFM is regular, as it is $\forall 3$ bounded

Theorem

[Henriksen *et. al*, 2005]

The decision problem “**is a regular language $L \subseteq Act^*$ well-formed**”?—that is, does regular L represent a set of MSCs?— is decidable.

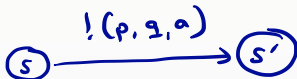
Proof.

Since L is regular, there exists a minimal DFA $\mathcal{A} = (S, Act, s_0, \delta, F)$ with $\mathcal{L}(\mathcal{A}) = L$. Consider the productive states in this DFA, i.e., all states from which some state in F can be reached. We label every productive state s with a **channel-capacity** function $K_s : Ch \rightarrow \mathbb{N}$ such that four constraints (cf. next slide) are fulfilled. Then: **L is well-formed iff each productive state in the DFA \mathcal{A} can be labelled with K_s satisfying these constraints.** In fact, if a state-labelling violates any of these constraints, it is due to a word that is not well-formed. \square

Constraints on state-labelling

- 1 $s \in F \cup \{s_0\}$, implies $K_s((p, q)) = 0$ for every channel (p, q) .
- 2 $\delta(s, !(p, q, a)) = s'$ implies

$$K_{s'}(c) = \begin{cases} K_s(c) + 1 & \text{if } c = (p, q) \\ K_s(c) & \text{otherwise.} \end{cases}$$



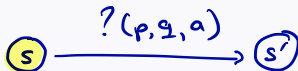
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- 3 $\delta(s, ?(p, q, a)) = s'$ implies $K_s((q, p)) > 0$ and

$$K_{s'}(c) = \begin{cases} K_s(c) - 1 & \text{if } c = (q, p) \\ K_s(c) & \text{otherwise.} \end{cases}$$



Constraints on state-labelling

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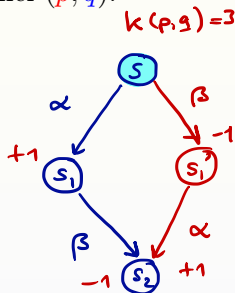
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$$K_{s'}(c) = \begin{cases} K_s(c) - 1 & \text{if } c = (q, p) \\ K_s(c) & \text{otherwise.} \end{cases}$$

④ $\delta(s, \alpha) = s_1$ and $\delta(s_1, \beta) = s_2$ with $\alpha \in Act_{\textcircled{p}}$ and $\beta \in Act_{\textcircled{q}}$ $p \neq q$, implies

not $(\alpha = !(p, q, a) \text{ and } \beta = ?(q, p, a))$, or $K_s((p, q)) > 0$
implies $\delta(s, \beta) = s'_1$ and $\delta(s'_1, \alpha) = s_2$ for some $s'_1 \in S$.



diamond

Constraints on state-labelling

- 1 $s \in F \cup \{s_0\}$, implies $K_s((p, q)) = 0$ for every channel (p, q) .
- 2 $\delta(s, !(p, q, a)) = s'$ implies

$$K_{s'}(c) = \begin{cases} K_s(c) + 1 & \text{if } c = (p, q) \\ K_s(c) & \text{otherwise.} \end{cases}$$

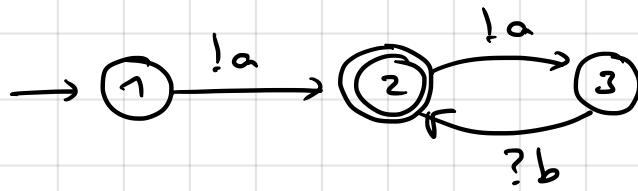
- 3 $\delta(s, ?(p, q, a)) = s'$ implies $K_s((q, p)) > 0$ and

$$K_{s'}(c) = \begin{cases} K_s(c) - 1 & \text{if } c = (q, p) \\ K_s(c) & \text{otherwise.} \end{cases}$$

- 4 $\delta(s, \alpha) = s_1$ and $\delta(s_1, \beta) = s_2$ with $\alpha \in Act_p$ and $\beta \in Act_q$, $p \neq q$, implies
not $(\alpha = !(p, q, a)$ and $\beta = ?(q, p, a))$, or $K_s((p, q)) > 0$
implies $\delta(s, \beta) = s'_1$ and $\delta(s'_1, \alpha) = s_2$ for some $s'_1 \in S$.

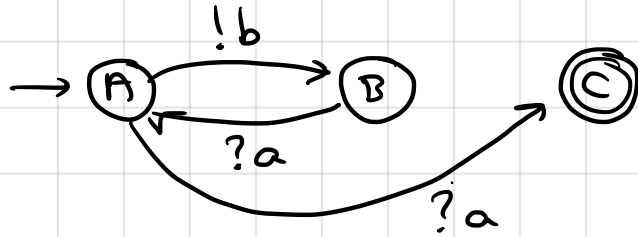
These constraints can be checked in linear time in the size of relation δ .

A_p



Yannakakis CFM

A_q



configurations

1A00

$\left\{ \begin{array}{l} A_p \text{ is in state 1} \\ A_q \text{ is in state A} \\ \underline{k(A_q)} = \underline{k(q,p)} = 0 \end{array} \right.$

Configuration graph is defined by the following rules

1A00 $\xrightarrow{!a}$ 2A10
 $\xrightarrow{!b}$ 1B01

2Anm $\xrightarrow{!a}$ 3A n+1 m
 $\xrightarrow{!b}$ 2B n m+1
 $\xrightarrow{?a}$ 2C n-1 m if $n > 0$

2Bnm $\xrightarrow{!a}$ 3B n+1 m
 $\xrightarrow{?a}$ 2A n-1 m if $n > 0$

3Anm $\xrightarrow{?b}$ 2A n m-1 if $m > 0$
 $\xrightarrow{!b}$ 3B n m+1
 $\xrightarrow{?a}$ 3C n-1 m if $n > 0$

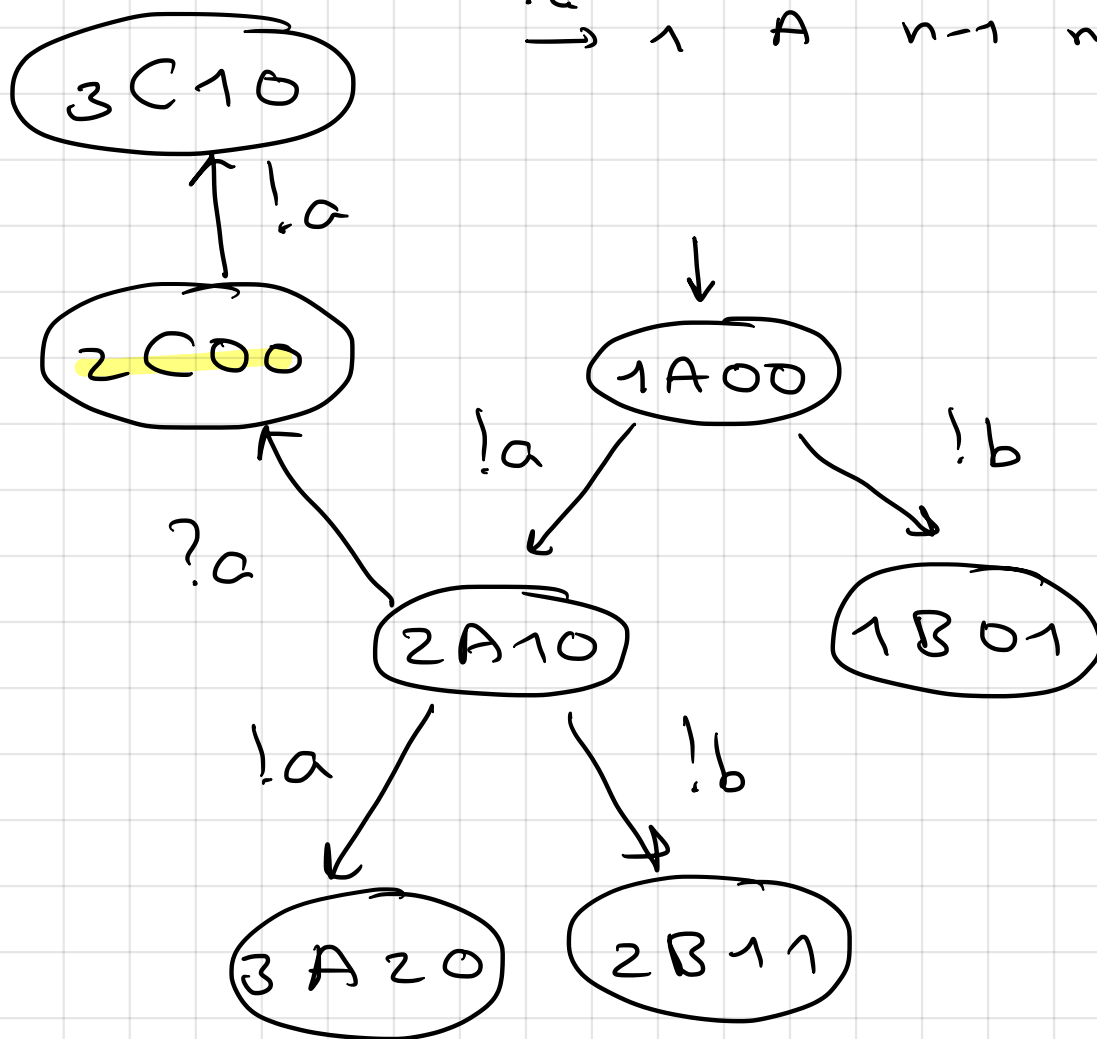
3Bnm $\xrightarrow{?b}$ 2B n m-1 if $m > 0$
 $\xrightarrow{?a}$ 3A n-1 m if $n > 0$

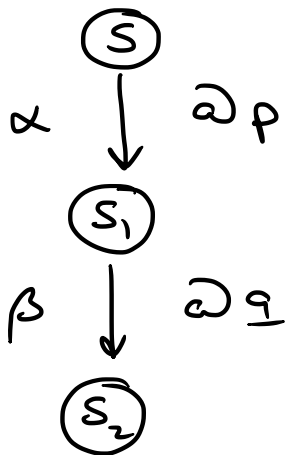
$3 \ C \ n \ m \xrightarrow{?b} 2 \ C \ n \ m-1 \quad \text{if } m > 0$

$2 \ C \ n \ m \xrightarrow{!a} 3 \ C \ n+1 \ m$

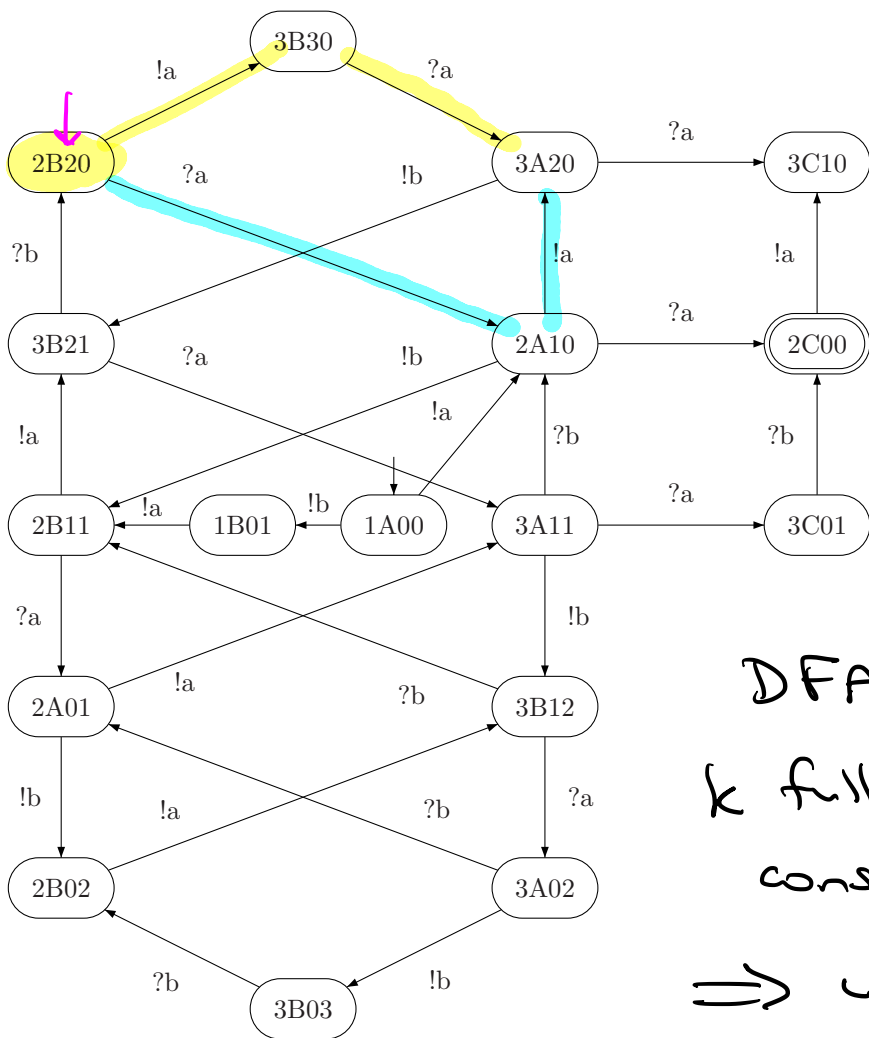
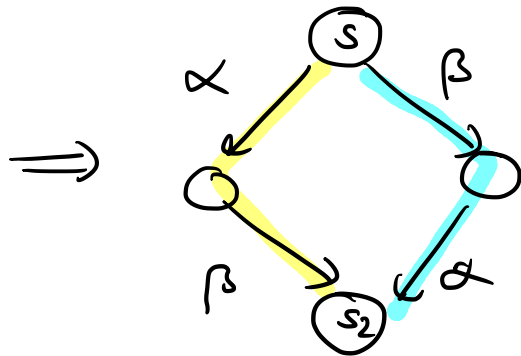
$1 \ B \ n \ m \xrightarrow{!a} 2 \ B \ n+1 \ m$

$\xrightarrow{?a} 1 \ A \ n-1 \ m \quad \text{if } n > 0$





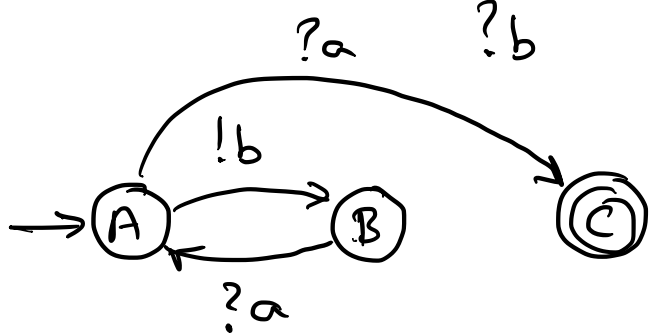
α, β are
not matched
or
 $k(p, q) > 0$



DFA
 k fulfills all
constraints
 \Rightarrow well-formed



A_p



A_q

Boundedness and regularity

Definition (B -bounded words)

Let $B \in \mathbb{N}$ and $B > 0$. A word $w \in Act^*$ is called **B -bounded** if for any prefix u of w and any channel $(p, q) \in Ch$:

$$0 \leq \sum_{a \in C} |u|_{!(p,q,a)} - \sum_{a \in C} |u|_{?(q,p,a)} \leq B$$

Corollary:

For any regular, well-formed language L , there exists $B \in \mathbb{N}$ and $B > 0$ such that every $w \in L$ is B -bounded.

Proof.

The bound B is the largest value attained by the channel-capacity functions assigned to productive states in the proof of the previous theorem. \square

- 1 Realisability and safe realisability
- 2 Regular MSCs
- 3 Regularity and realisability for MSCs**
- 4 Regularity and realisability for MSGs
 - Communication closedness

Theorem:

[Henriksen *et al.*, 2005], [Baudru & Morin, 2007]

For well-formed L , the following four statements are equivalent:

- ① L is regular.
 - ② L is realisable by a \forall -bounded CFM.
 - ③ L is realisable by a deterministic \forall -bounded CFM.
 - ④ L is safe realisable by a \forall -bounded CFM.
- } cf. lecture 10
- } cf. lecture 11

Theorem:

[Henriksen *et al.*, 2005], [Baudru & Morin, 2007]

For well-formed L , the following four statements are equivalent:

- ❶ L is regular.
- ❷ L is realisable by a \forall -bounded CFM.
- ❸ L is realisable by a deterministic \forall -bounded CFM.
- ❹ L is safe realisable by a \forall -bounded CFM.

Lemma:

The maximal size of the CFM realising L is such that for each process p , the number $|Q_p|$ of states of local automaton \mathcal{A}_p is:

- ❶ double exponential in the bound B and k^2 , where $k = |\mathcal{P}|$, and
- ❷ exponential in $m \log m$ where m is the size of the minimal DFA for L .

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Regularity for MSGs is undecidable

is $\text{Lin}(G)$ a regular language?

Theorem

[Henriksen *et. al*, 2005]

The decision problem “is MSG G regular?” is **undecidable**

Proof

Outside the scope of this lecture.

Towards structural conditions for regular MSGs

- MSG G is regular if $Lin(G)$ is a regular language
- Regularity yields deterministic, or safe, but bounded CFMs
- But, “is MSG G regular”? is unfortunately **undecidable**
- Is it possible to impose **simple structural** conditions on MSGs that guarantee regularity?

MSG G satisfies
the structural
conditions $\xrightarrow{\text{implies}}$ G is realisable

Towards structural conditions for regular MSGs

- MSG G is regular if $Lin(G)$ is a regular language
- Regularity yields deterministic, or safe, but bounded CFMs
- But, “is MSG G regular“? is unfortunately **undecidable**
- Is it possible to impose **structural** conditions on MSGs that guarantee regularity?
- **Yes we can.** For instance, by constraining:
 - ➔ ① the communication structure of the MSCs in loops of G , or
 - ② the structure of expressions describing the MSCs in G

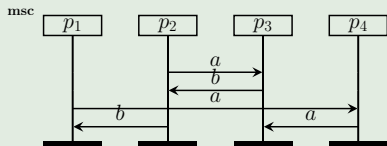
Communication graph

Definition (Communication graph)

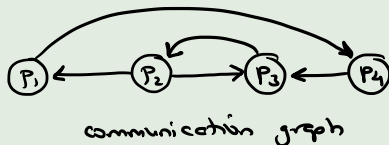
The **communication graph** of the MSC $M = (\mathcal{P}, E, \mathcal{C}, l, m, <)$ is the directed graph (V, \rightarrow) with:

- $V = \mathcal{P} \setminus \{p \in \mathcal{P} \mid E_p = \emptyset\}$, the set of **active** processes
- $(p, q) \in \rightarrow$ if and only if $\mathcal{L}(e) = !(p, q, a)$ for some $e \in E$ and $a \in \mathcal{C}$

Example



an example MSC



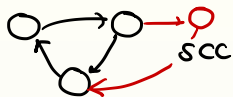
Strongly connected components

Let $G = (V, \rightarrow)$ be a directed graph.

Strongly connected component

- $T \subseteq V$ is **strongly connected** if for every $v, w \in T$, vertices v and w are mutually reachable (via \rightarrow) from each other.

Strongly connected components



Let $G = (V, \rightarrow)$ be a directed graph.

Strongly connected component

- $T \subseteq V$ is **strongly connected** if for every $v, w \in T$, vertices v and w are mutually reachable (via \rightarrow) from each other.
- T is a **strongly connected component** (SCC) of G if T is strongly connected and T is not properly contained in another SCC.

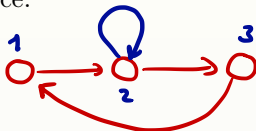
Determining the SCCs of a digraph can be done in linear time in the size of V and \rightarrow .

e.g. depth-first algorithm

Communication closedness

Communication closedness

A loop is simple if it visits a vertex at most once, except for the start- and end-vertex which are visited twice.



1 2 2 3 not simple

Communication closedness

A loop is **simple** if it visits a vertex at most once, except for the start- and end-vertex which are visited twice.

Definition (Communication closedness)

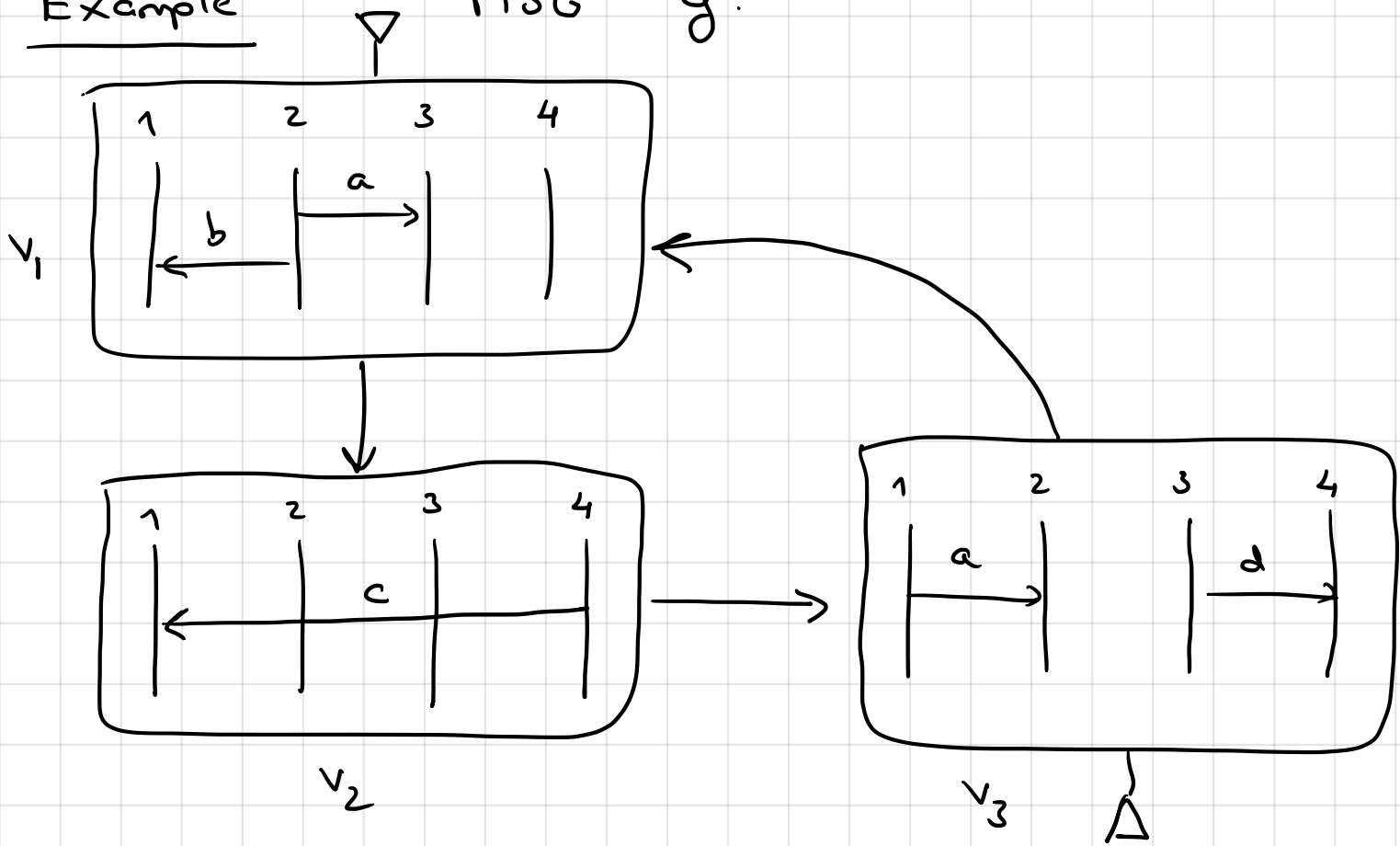
MSG G is **communication-closed** if for every simple loop $\pi = v_1 v_2 \dots v_n$ (with $v_1 = v_n$) in G , the communication graph of the MSC $M(\pi) = \lambda(v_1) \bullet \lambda(v_2) \bullet \dots \bullet \lambda(v_n)$ is strongly connected.

Example

On the black board.

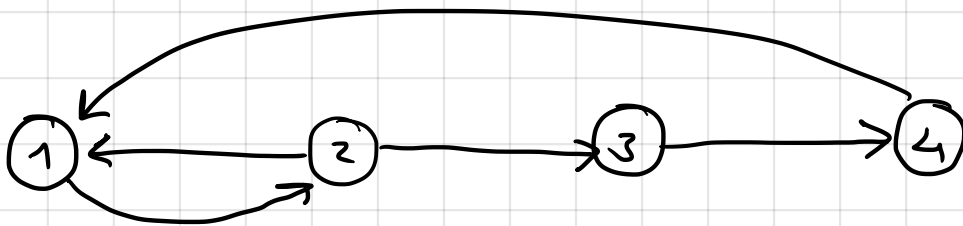
Example

MSG g :



single loop (which is simple): $v_1 v_2 v_3 v_1 = \pi$

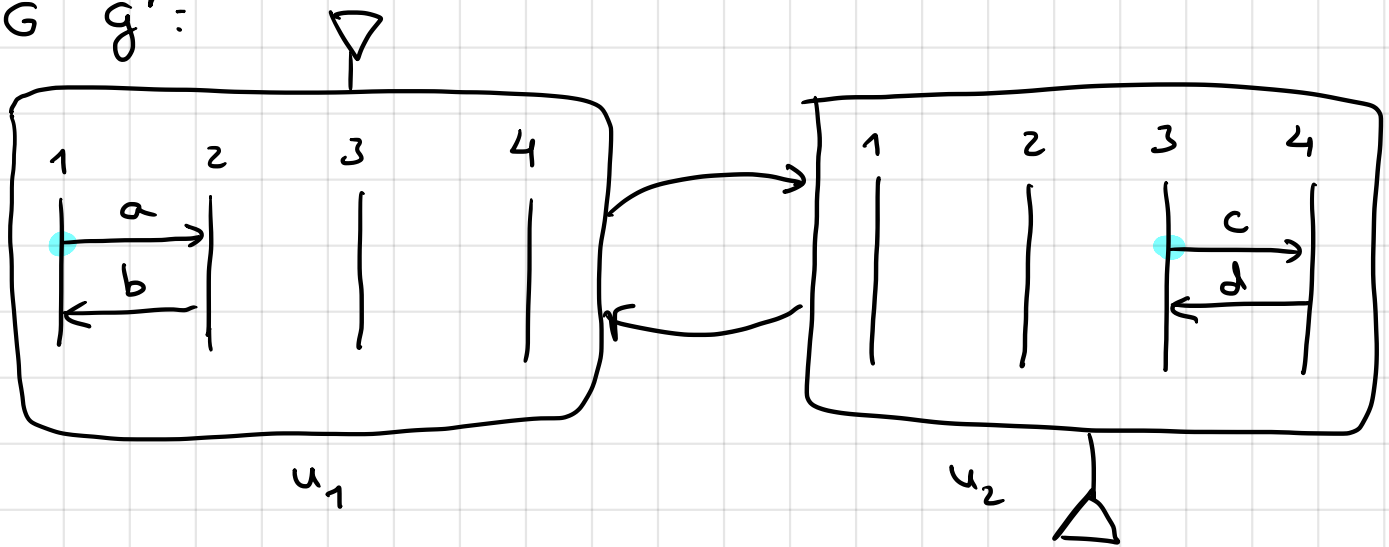
communication graph of $M(\pi)$: $\lambda(v_1) \cdot \lambda(v_2) \cdot \lambda(v_3)$



strongly connected

Thus G is communication closed.

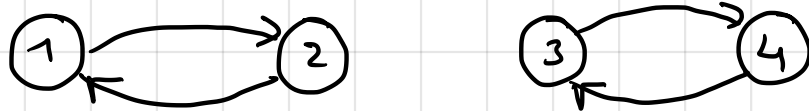
MSG g' :



Communication graph of g' :

$$\pi = u_1 u_2 u_1$$

$M(\pi)$:



not strongly connected

Thus, g' is not communication closed

$L(g')$ is not regular. To see this, consider

$$\text{Lin}(g') \cap \{!a, !c\} =$$

$$\{ \sigma \in \{!a, !c\}^* \mid \#_{!a} \sigma = \#_{!c} \sigma > 0 \}$$

is not regular. As regular languages are

closed under projections, $\text{Lin}(g')$ is not regular.

Communication-closed vs. regularity

Theorem:

Every communication-closed MSG G is regular.

sufficient criterion for being regular

Example

Example on the black board.

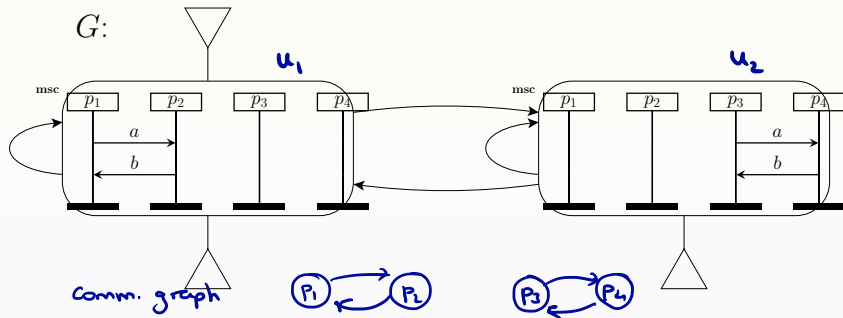
Note:

The converse does not hold (cf. next slide).

Communication-closed vs. regularity

$(!a?a!b?b)^+$ interleaved $(!a?a!b?b)^+$
between p_1 and p_2 between p_3 and p_4

Communication-closedness is not a necessary condition for regularity:



MSG G is **not** communication-closed, but $\text{Lin}(G)$ is regular.

Theorem:

[Genest *et. al*, 2006]

The decision problem “is MSG G communication closed?” is co-NP complete.

equally hard as checking whether a finite set of MSCs is realisable by a weak CFM (cf. lecture 10)

Theorem:

[Genest *et. al*, 2006]

The decision problem “is MSG G communication closed?” is co-NP complete.

Proof

- 1 Membership in co-NP can be proven in a standard way: guess a sub-graph of G , check in polynomial time whether this sub-graph has a loop passing through all its vertices, and check whether its communication graph is not strongly connected. (in poly time)
- 2 Co-NP hardness can be shown by a reduction from the 3-SAT problem.

polynomial

Theorem Checking whether MSG G is comm.-closed is coNP-hard.

Proof: Polynomial reduction from the 3SAT-problem.

3SAT: consider the Boolean formula

$$\phi = C_1 \wedge \dots \wedge C_m$$

clauses

over the variables $\{x_1, \dots, x_n\}$ such that clause

$$C_j = l_j^1 \vee l_j^2 \vee l_j^3$$

literals equals x_k or \bar{x}_k
for some $k \in \{1, \dots, n\}$

ϕ is satisfiable if \exists valuation for x_1 through x_n .
for every m , C_m is true.

Fact: 3SAT is NP-complete. Its complement is also NP-complete, thus 3SAT is also coNP-complete.

Reduction:

3SAT-formula

\longrightarrow MSG G

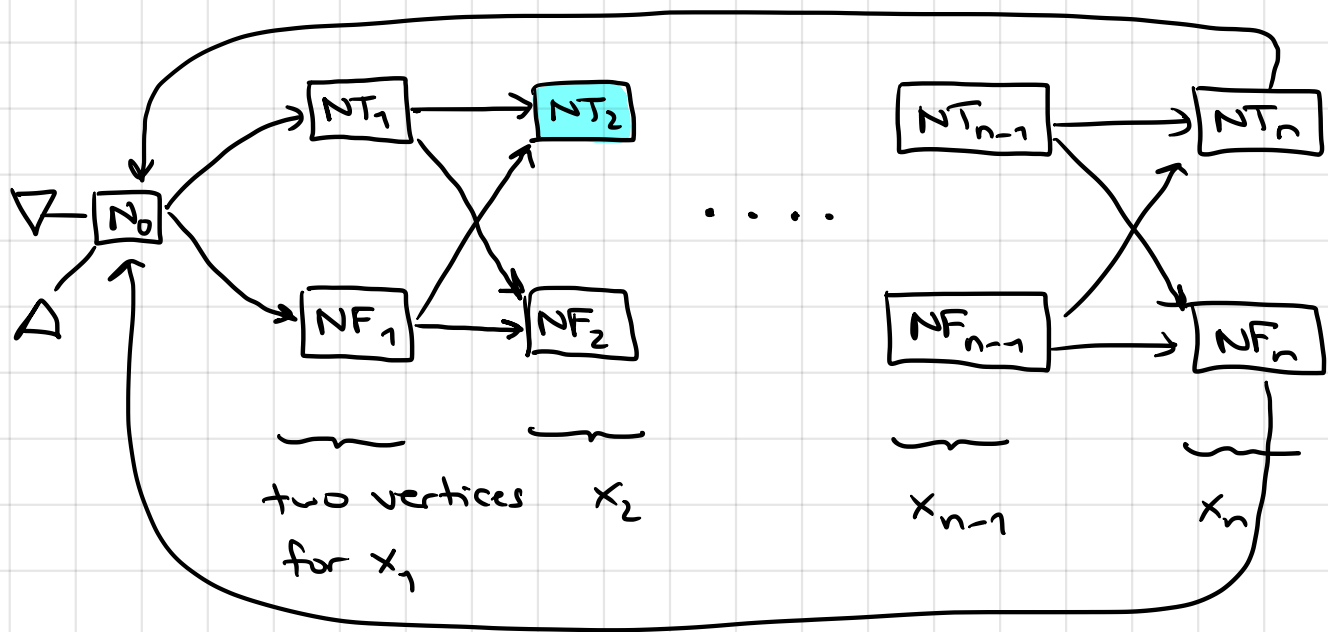
$$\phi = C_1 \wedge \dots \wedge C_m$$

over $\{x_1, \dots, x_n\}$

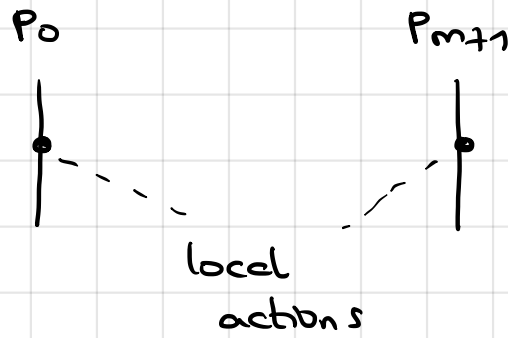
such that ϕ is satisfiable iff G has a simple loop that is not strongly connected.

G is not comm. closed.

The structure of MSG G is as follows: n variables

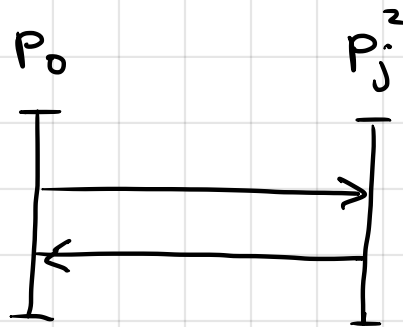


$$\lambda(N_0) =$$

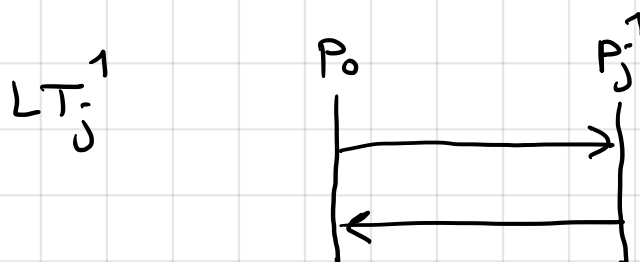
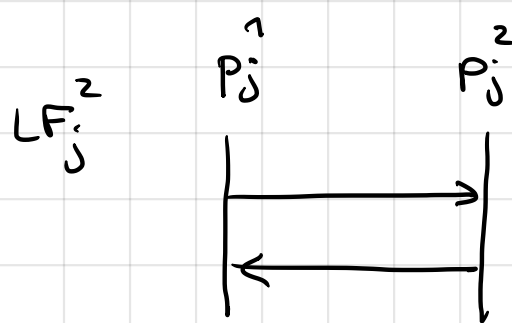
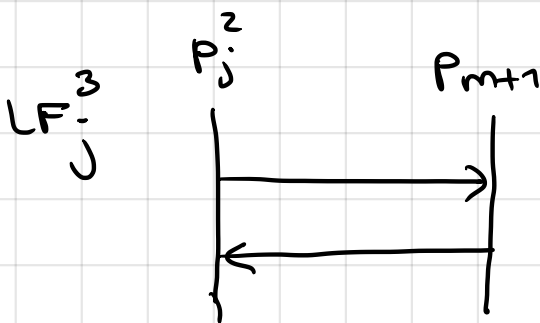


Template MSCs: $\underbrace{LT_j^1, LT_j^2, LT_j^3}_{\text{empty}} \quad (\text{true})$

$LT_j^3 ::$



Also have templates LF_j^1, LF_j^2, LF_j^3



$\lambda(NT_i) =$ the concatenation of all template
 MSCs LT_j^k with $l_j^k = x_i$
 + $(k=1,2,3)$
 all template MSCs
 LF_j^k with $l_j^k = \overline{x_i}$

$\lambda(NF_i) =$ concatenate:
 LT_j^k with $l_j^k = \overline{x_i}$
 and LF_j^k with $l_j^k = x_i$

Example

$$\phi = (x_1 \vee \overline{x_2} \vee x_3)$$

C_1

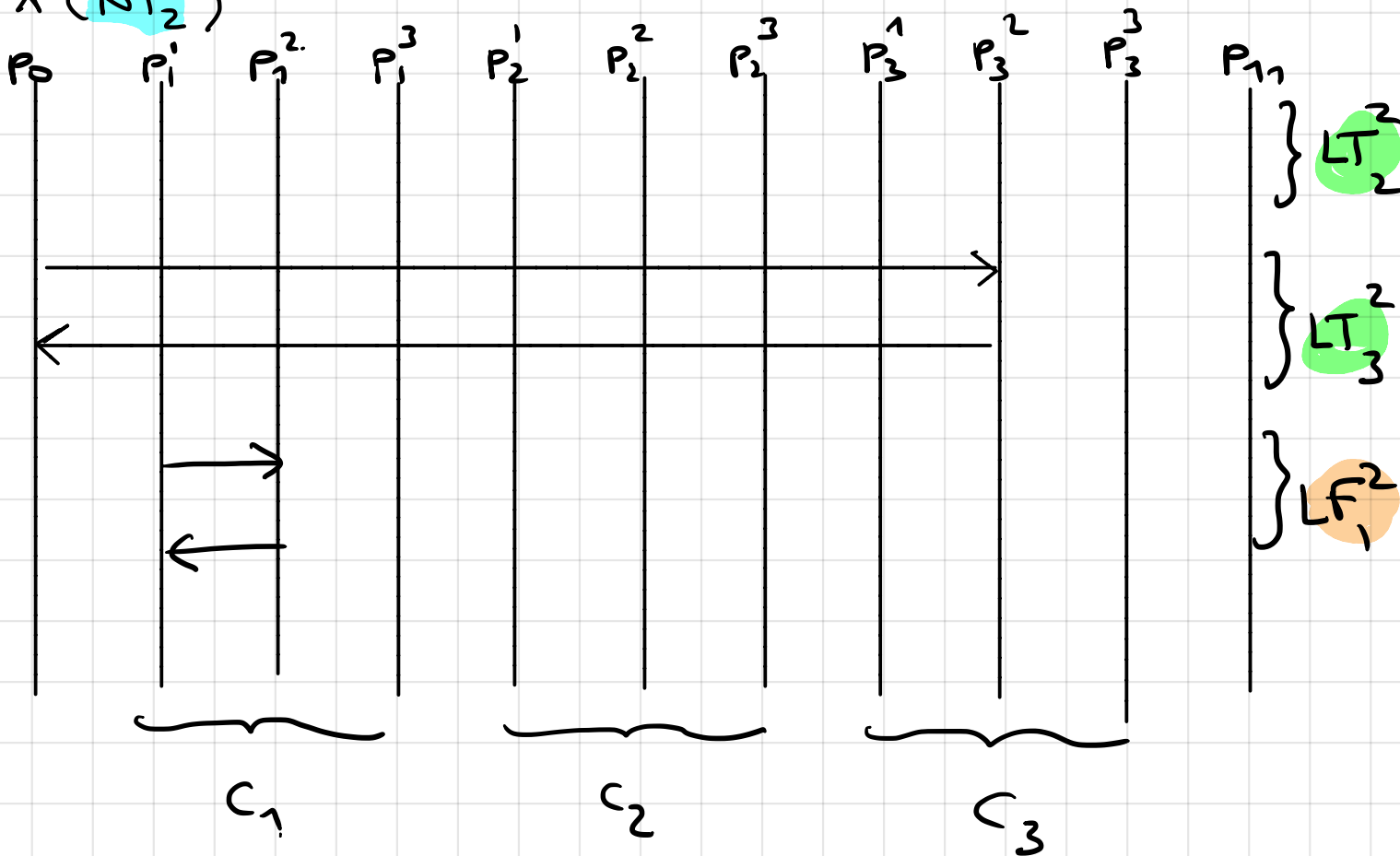
$$\wedge (\overline{x_1} \vee x_2 \vee x_3)$$

C_2

$$\wedge (x_1 \vee x_2 \vee \overline{x_3})$$

C_3

$\lambda(NT_2)$



$$\lambda(NT_2) = LT_2^2 \cdot LT_3^2 \cdot LF_1^2$$

Claim processes p_0 and p_{m+1} are connected in the communication graph of MSG G iff there exists a clause in ϕ for which all literals are false.

Asynchronous iteration

Definition

For $\mathcal{M}_1, \mathcal{M}_2 \subseteq \mathbb{M}$ sets of MSCs, let:

$$\underline{\mathcal{M}_1 \bullet \mathcal{M}_2} = \{ \underline{M_1 \bullet M_2} \mid \underline{M_1} \in \underline{\mathcal{M}_1}, \underline{M_2} \in \underline{\mathcal{M}_2} \}$$

For $\mathcal{M} \subseteq \mathbb{M}$ let

$$\mathcal{M}^i = \begin{cases} \{M_\epsilon\} & \text{if } i=0, \text{ where } M_\epsilon \text{ denotes the empty MSC} \\ \mathcal{M} \bullet \mathcal{M}^{i-1} & \text{if } i > 0 \end{cases}$$

The **asynchronous iteration** of \mathcal{M} is now defined by:

$$\mathcal{M}^* = \bigcup_{i \geq 0} \mathcal{M}^i.$$

Definition (Finitely generated)

Set of MSCs \mathcal{M} is **finitely generated** if there is a **finite** set of MSCs $\widehat{\mathcal{M}}$ such that $\mathcal{M} \subseteq \widehat{\mathcal{M}}^*$.

Remarks:

- 1 Each set of MSCs defined by an MSG G is finitely generated.
- 2 Not every regular well-formed language is finitely generated. ||
- 3 Not every finitely generated set of MSCs is regular.
- 4 It is decidable to check whether a set of MSCs is finitely generated. ✓

Theorem:

[Henriksen *et. al*, 2005]

Let \mathcal{M} be a (possibly infinite) set of MSCs. Then:

\mathcal{M} is finitely generated and regular

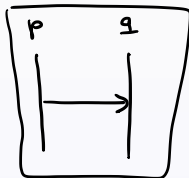
iff

$\mathcal{M} = \mathcal{L}(G)$ for some communication-closed MSG G .

Local communication-closedness

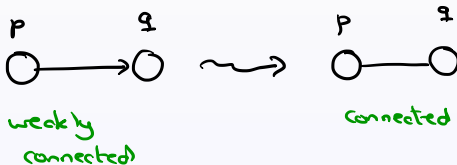
Definition (Local communication-closedness)

MSG G is **locally** communication-closed if for each edge (v, v') in G , the MSCs $\lambda(v)$, $\lambda(v')$, and $\lambda(v) \bullet \lambda(v')$ all have **weakly** connected communication graphs.



v

communication graph,
ignore the direction of edges
→ undirected graph



Definition (Local communication-closedness)

MSG G is **locally** communication-closed if for each edge (v, v') in G , the MSCs $\lambda(v)$, $\lambda(v')$, and $\lambda(v) \bullet \lambda(v')$ all have **weakly** connected communication graphs.

Notes:

- 1 A directed graph is weakly connected if its induced **undirected** graph (obtained by ignoring the directions of edges) is strongly connected.
- 2 Checking whether MSG G is locally communication-closed can be done in linear time.

Locally communication-closed MSGs are realisable

Theorem:

[Genest *et al.*, 2006]

Every locally communication-closed MSG G is realisable by a CFM \mathcal{A} (of size $m^{\mathcal{O}(|\mathcal{P}|)}$ where m is the number of vertices in G)