

Introduction

Modelling parallel systems

Transition systems



Modeling hard- and software systems

Parallelism and communication

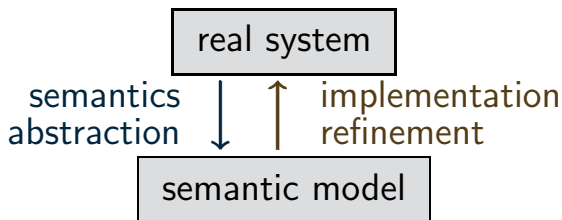
Linear Time Properties

Regular Properties

Linear Temporal Logic

Computation-Tree Logic

Equivalences and Abstraction



The semantic model yields a formal representation of:

- the **states** of the system ← **nodes**
- the **stepwise behaviour** ← **transitions**
- the **initial states**
- **additional information** on
 - communication ← **actions**
 - state properties ← **atomic proposition**

Transition system (TS)

TS1.4-TS-DEF

A transition system is a tuple

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where $s, s' \in \mathcal{S}$ and $\alpha \in \mathit{Act}$

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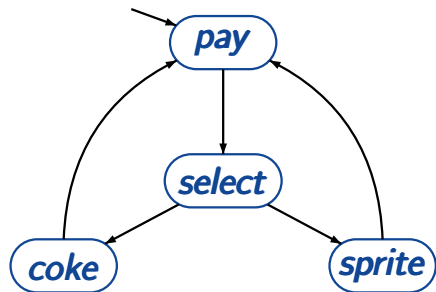
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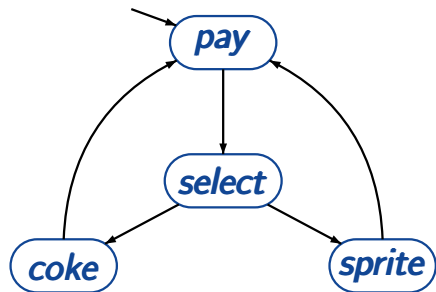
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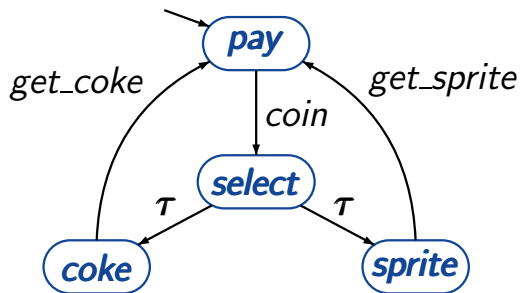
- $\mathcal{S}_0 \subseteq \mathcal{S}$ the set of **initial states**,
- AP a set of **atomic propositions**,
- $L : \mathcal{S} \rightarrow 2^{\mathit{AP}}$ the **labeling function**





state space $S = \{pay, select, coke, sprite\}$

set of initial states: $S_0 = \{pay\}$



actions:

coin

τ

get_sprite

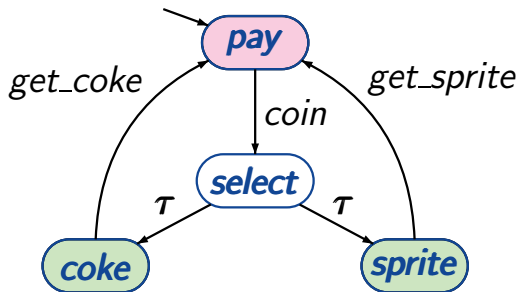
get_coke

state space $S = \{\textit{pay}, \textit{select}, \textit{coke}, \textit{sprite}\}$

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Transition system for beverage machine

TS1.4-2



actions:
coin
 τ
get_sprite
get_coke

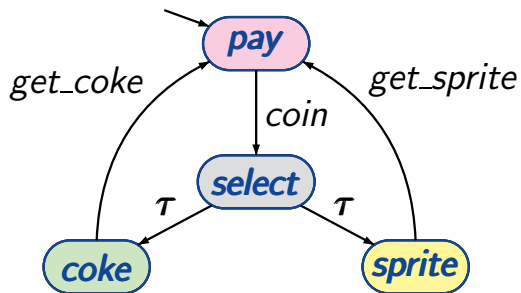
state space $S = \{\text{pay}, \text{select}, \text{coke}, \text{sprite}\}$

set of initial states: $S_0 = \{\text{pay}\}$

set of atomic propositions: $AP = \{\text{pay}, \text{drink}\}$

labeling function: $L(\text{coke}) = L(\text{sprite}) = \{\text{drink}\}$

$L(\text{pay}) = \{\text{pay}\}, L(\text{select}) = \emptyset$



actions:

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τ

get_sprite

get_coke

state space $S = \{pay, select, coke, sprite\}$

set of initial states: $S_0 = \{pay\}$

set of atomic propositions: $AP = S$

labeling function: $L(s) = \{s\}$ for each state s

possible behaviours of a TS result from:

select **nondeterministically** an initial state $s \in S_0$

WHILE s is non-terminal DO

 select **nondeterministically** a transition $s \xrightarrow{\alpha} s'$

 execute the **action** α and put $s := s'$

OD

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executions: maximal “transition sequences”

$$s_0 \xrightarrow{\alpha_1} s_1 \xrightarrow{\alpha_2} s_2 \xrightarrow{\alpha_3} \dots \text{ with } s_0 \in S_0$$

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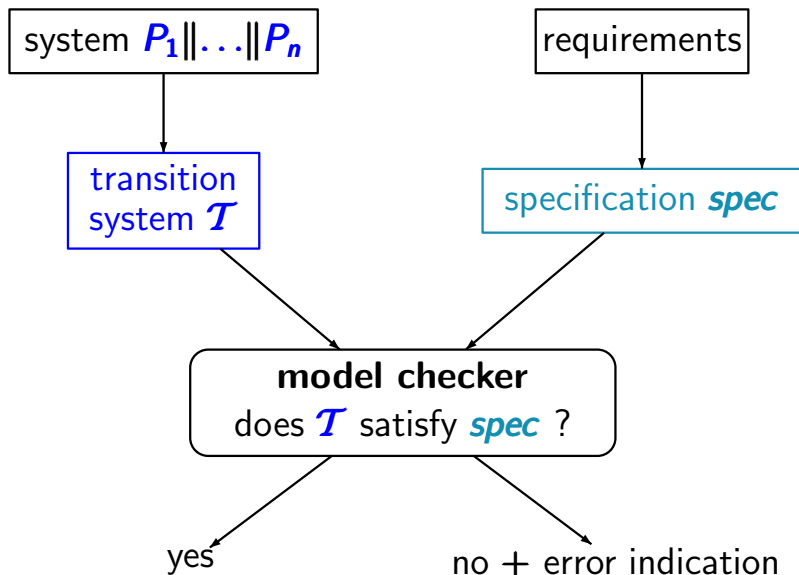
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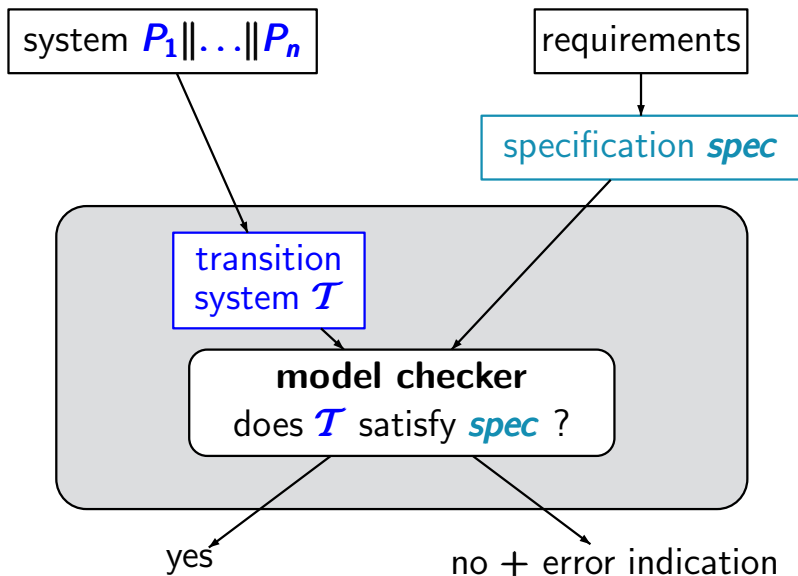
reachable fragment:

Reach(\mathcal{T}) = set of all states that are **reachable** from an initial state through some execution



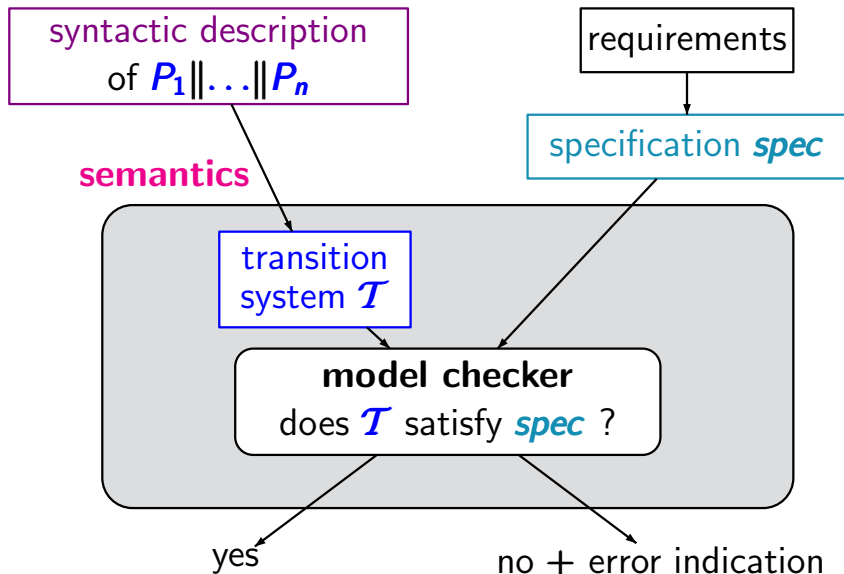
Model checking

ts1.4-9



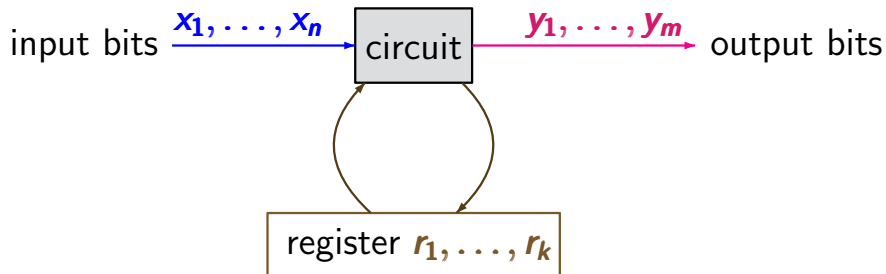
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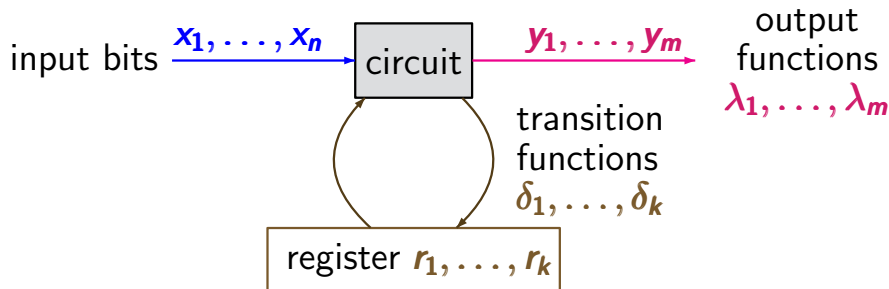
Modelling of sequential circuits by TS

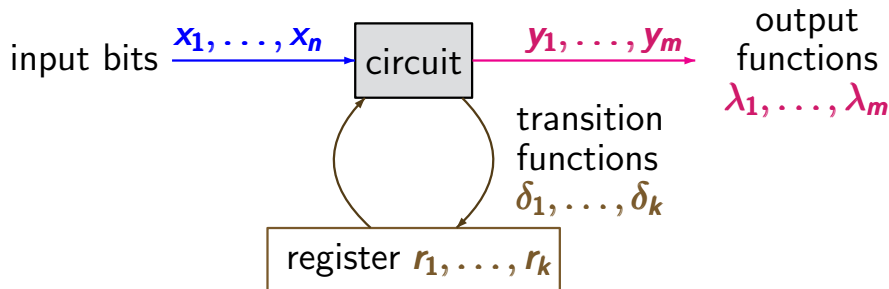
TS1.4-10



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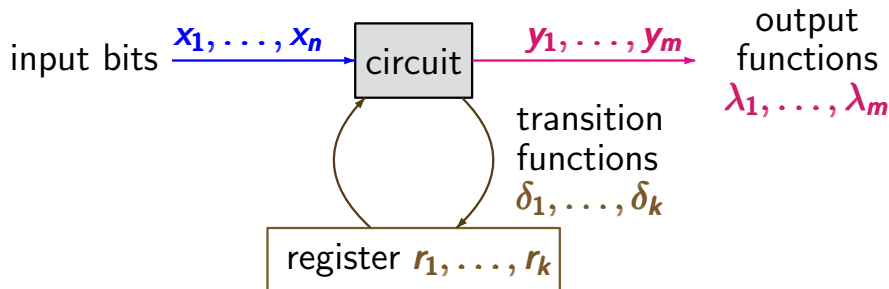




$\delta_j, \lambda_i \hat{=} \text{switching functions } \{0, 1\}^n \times \{0, 1\}^k \longrightarrow \{0, 1\}$

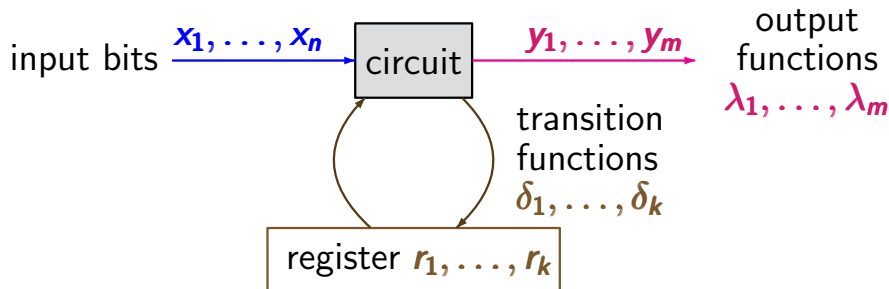
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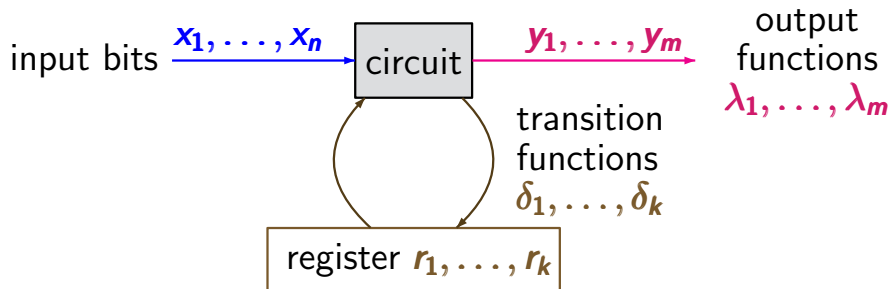


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input values a_1, \dots, a_n for the input variables + current values c_1, \dots, c_k of the registers	↦	output value $\lambda_i(\dots)$ for output variable y_i next value $\delta_j(\dots)$ for register r_j
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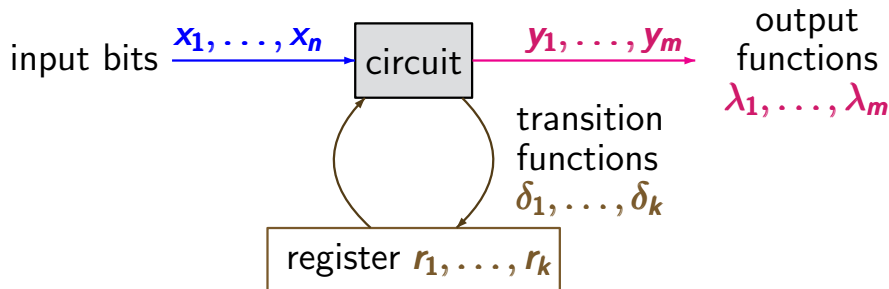
initial register evaluation $[r_1=c_{01}, \dots, r_k=c_{0k}]$



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transition system:

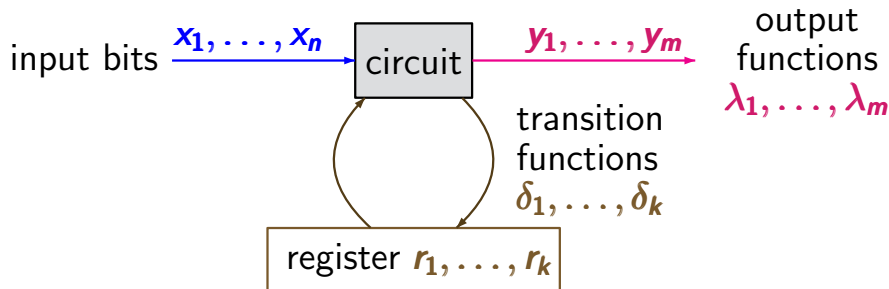
- states: evaluations of $x_1, \dots, x_n, r_1, \dots, r_k$



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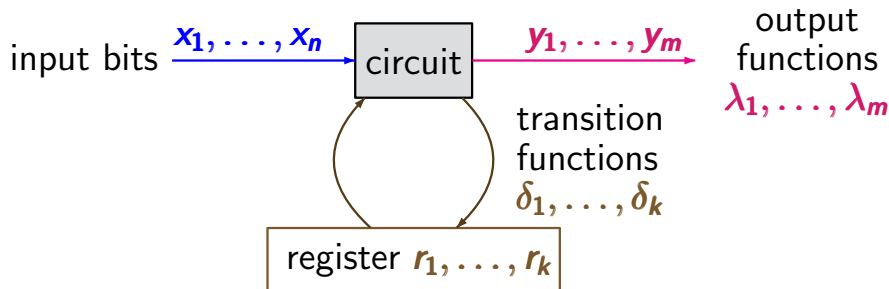
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- values of input bits change nondeterministically



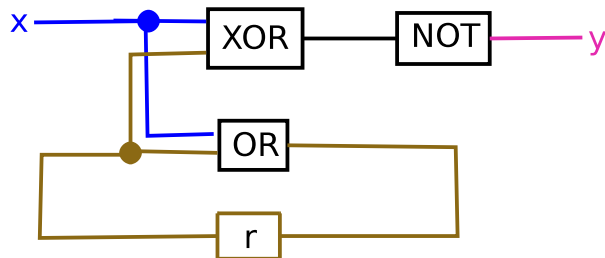
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transition system:

- states: evaluations of $x_1, \dots, x_n, r_1, \dots, r_k$
- transitions represent the stepwise behavior
- values of input bits change nondeterministically
- atomic propositions: $x_1, \dots, x_n, y_1, \dots, y_m, r_1, \dots, r_k$

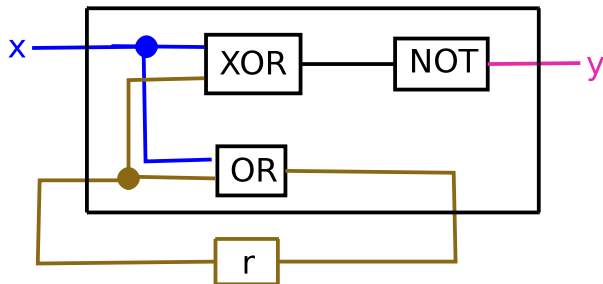
Example: sequential circuit

TS1.4-11A



Example: sequential circuit

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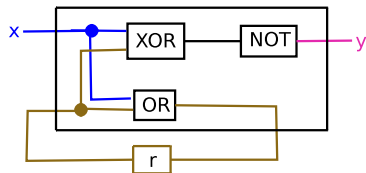


output function: $\lambda_y = \neg(x \oplus r)$

transition function: $\delta_r = x \vee r$

Example: TS for sequential circuit

TS1.4-11



output function

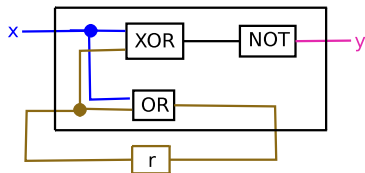
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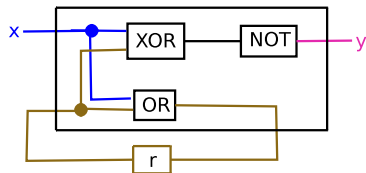
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$$x=1 \ r=0$$

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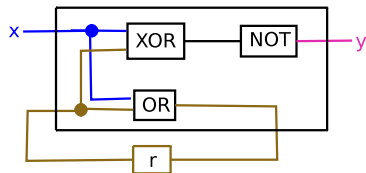
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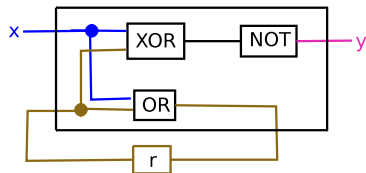
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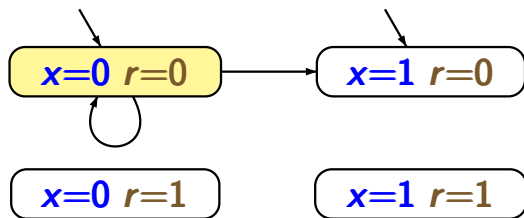
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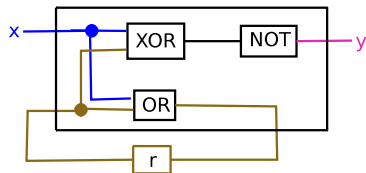
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Example: TS for sequential circuit

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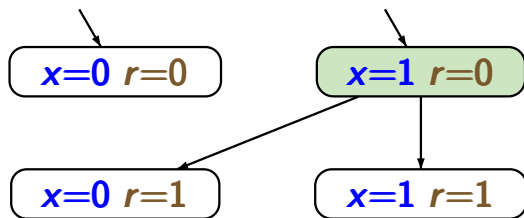
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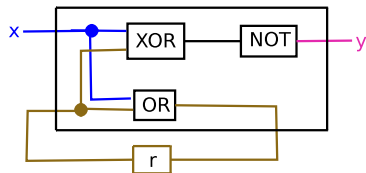
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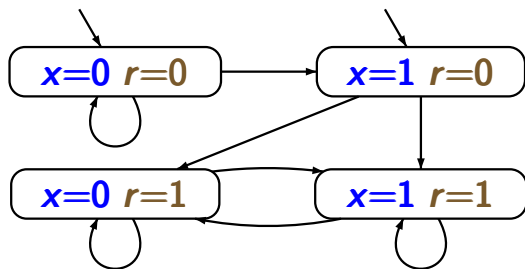
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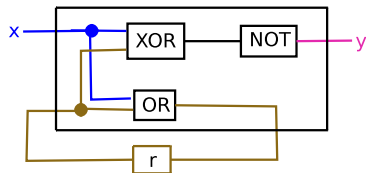
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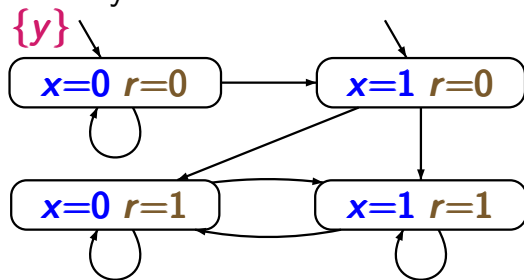
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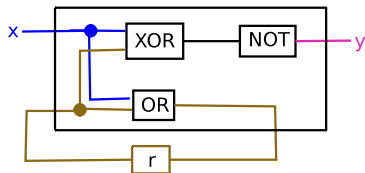
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Example: TS for sequential circuit

TS1.4-11



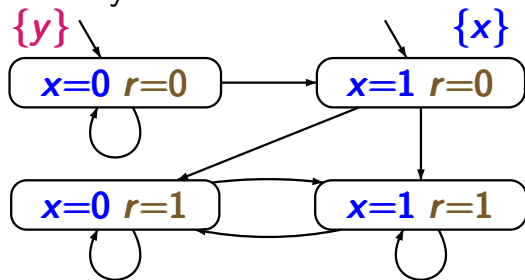
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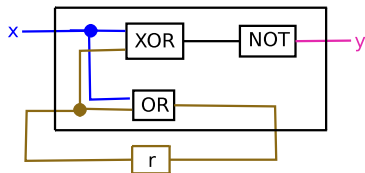
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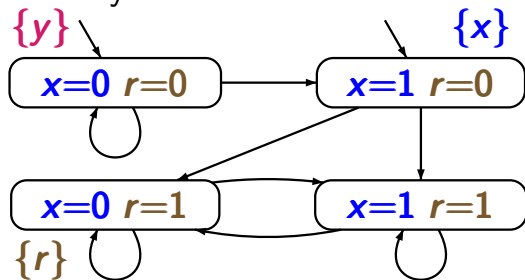
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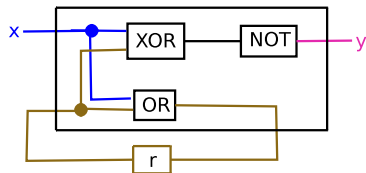
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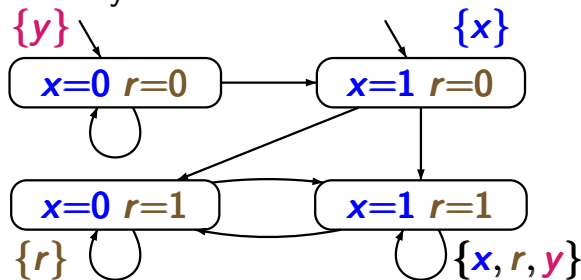
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transition system



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How many states ...

TS1.4-12

... has the transition system for a circuit of the form?



1 output bit
no input
100 registers

How many states ...

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answer: 2^{100}

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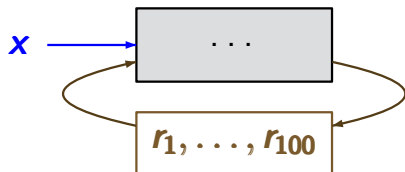
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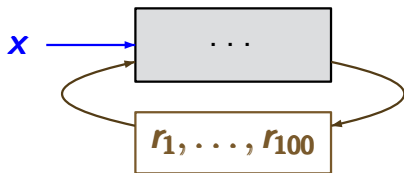
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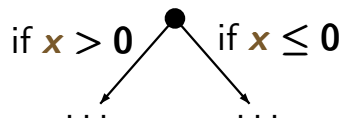
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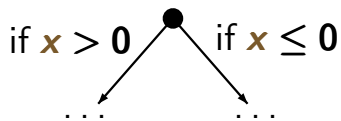
no output
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100 registers

answer: $2^{100} * 2^1 = 2^{101}$

problem: TS-representation of conditional branchings ?



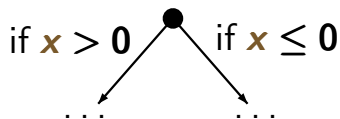
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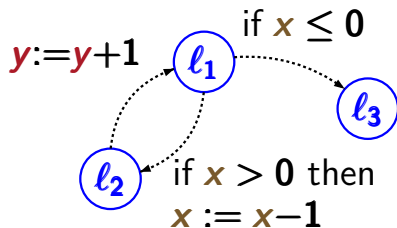
```
WHILE  $x > 0$  DO  
     $x := x - 1$ ;  
     $y := y + 1$   
OD  
...
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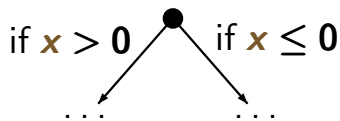


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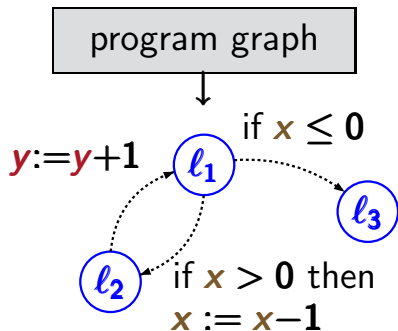


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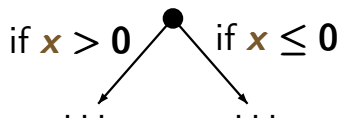


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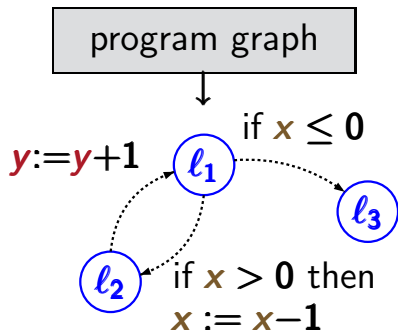
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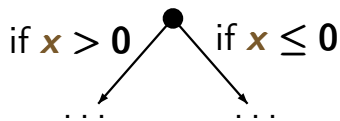
example: sequential program

$l_1 \rightarrow$ WHILE $x > 0$ DO
 $x := x - 1$;
 $l_2 \rightarrow$ $y := y + 1$
 OD
 $l_3 \rightarrow$...

l_1, l_2, l_3 are locations,
i.e., control states

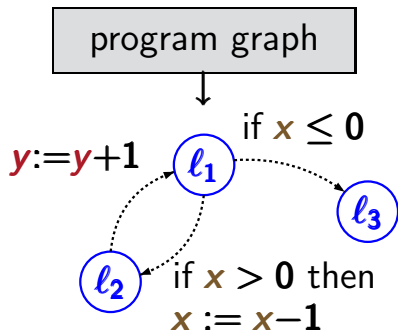


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          OD  
 $l_3 \rightarrow$  ...
```



states of the transition system:

locations + relevant data (*here:* values for x and y)

Example: TS for sequential program

TS1.4-14

initially: $x = 2$, $y = 0$

$l_1 \rightarrow$ WHILE $x > 0$ DO

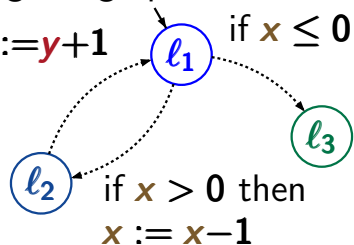
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OD

$l_3 \rightarrow$...

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TS1.4-14

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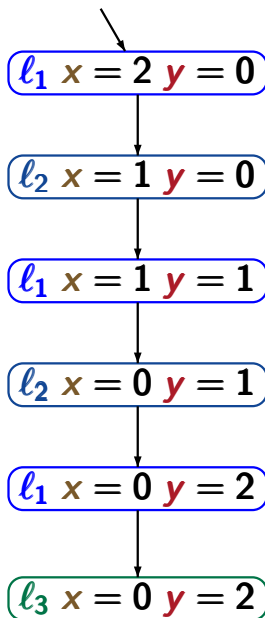
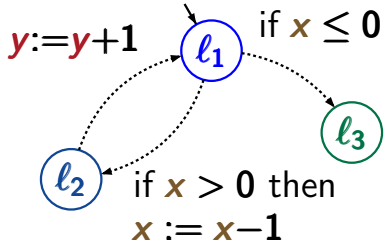
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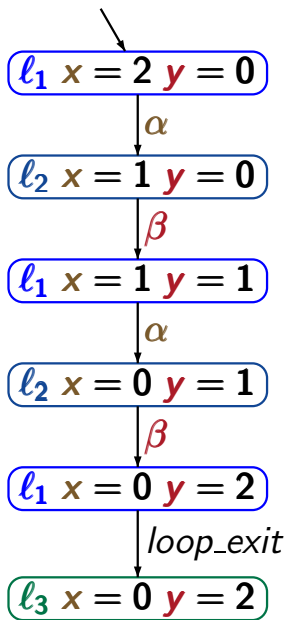
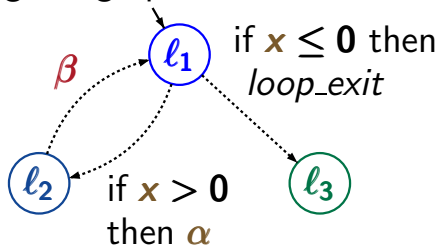
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Example:

$[x=0, y=3, z=6] \models \neg x \wedge y < z$

$[x=0, y=3, z=6] \not\models x \vee y = z$

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if γ is “ $(x, y) := (2x + y, 1 - x)$ ” then:

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Program graph (PG)

TRANSYS/TS-PROGRAM-GRAPH-DEF-1

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Let *Var* be a set of typed variables.

A *program graph* over *Var* is a tuple

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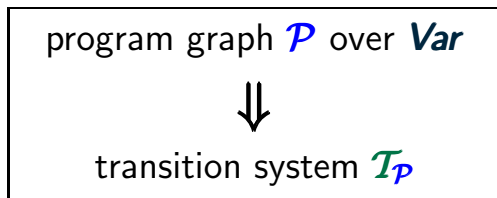
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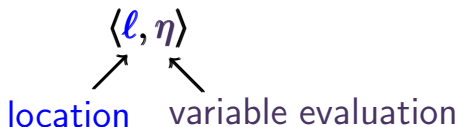
program graph \mathcal{P} over Var



transition system $\mathcal{T}_{\mathcal{P}}$



states in $\mathcal{T}_{\mathcal{P}}$ have the form



Let $\mathcal{P} = (\text{Loc}, \text{Act}, \text{Effect}, \hookrightarrow, \text{Loc}_0, g_0)$ be a PG.

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$$\frac{\text{premise}}{\text{conclusion}}$$

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It means that \longrightarrow is the **smallest relation** such that:

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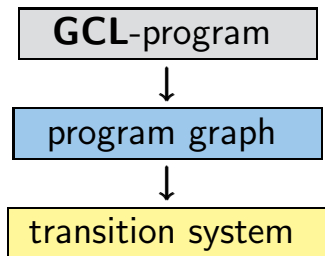
by Dijkstra

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- semantics:



guarded command $g \Rightarrow stmt$

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 $stmt$: statement

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TS1.4-15

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symbol $::$ stands for the **nondeterministic choice**
between enabled guarded commands

modeling language with nondeterministic choice

$$\begin{aligned} \textit{stmt} &\stackrel{\text{def}}{=} x := \textit{expr} \quad | \quad \textit{stmt}_1; \textit{stmt}_2 \quad | \\ &\quad \text{DO } ::g_1 \Rightarrow \textit{stmt}_1 \quad \dots \quad ::g_n \Rightarrow \textit{stmt}_n \quad \text{OD} \\ &\quad \text{IF } ::g_1 \Rightarrow \textit{stmt}_1 \quad \dots \quad ::g_n \Rightarrow \textit{stmt}_n \quad \text{FI} \\ &\quad \vdots \end{aligned}$$

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semantics of a **GCL**-program: program graph

uses two variables *#sprite*, *#coke* $\in \{0, 1, \dots, \mathit{max}\}$
for the number of available drinks (sprite or coke)

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	enabled	effect
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refill	any time	$\#sprite := max$ $\#coke := max$
insert_coin	any time	no effect on variables
return_coin	if machine is empty and user has entered a coin (no effect on variables)	

DO :: true \Rightarrow insert_coin;

IF :: #sprite = #coke = 0 \Rightarrow return_coin

:: #coke > 0 \Rightarrow #coke := #coke - 1

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FI

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OD

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            (* user selects coke *)
        :: #sprite > 0  $\Rightarrow$  #sprite := #sprite - 1
            (* user selects sprite *)
    FI
    :: true  $\Rightarrow$  #sprite := max; #coke := max
        (* refilling of the machine *)
OD
```

```
DO :: true  $\Rightarrow$  insert_coin; (* user inserts a coin *)
    IF :: #sprite = #coke = 0  $\Rightarrow$  return_coin
        (* no beverage available *)
        :: #coke > 0  $\Rightarrow$  get_coke
            (* user selects coke *)
        :: #sprite > 0  $\Rightarrow$  get_sprite
            (* user selects sprite *)
    FI
    :: true  $\Rightarrow$  refill
        (* refilling of the machine *)
OD
```

DO :: true \Rightarrow insert_coin;

IF :: #sprite = #coke = 0 \Rightarrow return_coin

:: #coke > 0 \Rightarrow get_coke

:: #sprite > 0 \Rightarrow get_sprite

FI

:: true \Rightarrow refill

OD

```
DO :: true  $\Rightarrow$  insert_coin;
    IF :: #sprite = #coke = 0
         $\Rightarrow$  return_coin
        :: #coke > 0  $\Rightarrow$  get_coke
        :: #sprite > 0  $\Rightarrow$  get_sprite
    FI
    OD :: true  $\Rightarrow$  refill
```

... yields a program graph with

- two variables *#sprite*, *#coke* $\in \{0, 1, \dots, max\}$

```
start → DO :: true ⇒ insert_coin;
select →      IF :: #sprite = #coke = 0
                ⇒ return_coin
                :: #coke > 0 ⇒ get_coke
                :: #sprite > 0 ⇒ get_sprite
      FI
    OD :: true ⇒ refill
```

... yields a program graph with

- two variables *#sprite*, *#coke* $\in \{0, 1, \dots, max\}$
- two locations *start* and *select*

