

Exercise 1 (Muller automata):

(2 points)

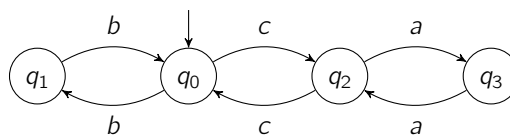
A nondeterministic Muller automaton is a quintuple $\mathcal{A} = (Q, \Sigma, \delta, Q_0, \mathcal{F})$ where Q, Σ, δ and Q_0 are as for NBA and $\mathcal{F} \subseteq 2^Q$. For an infinite run ρ of \mathcal{A} , let

$$\text{inf}(\rho) := \{q \in Q \mid \exists^\infty i \geq 0. \rho[i] = q\}.$$

Let $\alpha \in \Sigma^\omega$.

$$\mathcal{A} \text{ accepts } \alpha \iff \text{ex. inf. run } \rho \text{ of } \mathcal{A} \text{ on } \alpha \text{ s.t. } \text{inf}(\rho) \in \mathcal{F}$$

- a) Consider the following Muller automaton \mathcal{A} with $\mathcal{F} = \{\{q_2, q_3\}, \{q_1, q_3\}, \{q_0, q_2\}\}$:



Give the language accepted by \mathcal{A} by means of an ω -regular expression.

- b) Show that every GNBA \mathcal{G} can be transformed into a nondeterministic Muller automaton \mathcal{A} such that $\mathcal{L}_\omega(\mathcal{A}) = \mathcal{L}_\omega(\mathcal{G})$ by defining the corresponding transformation.

Exercise 2 (A-recognizable):

(2 points)

A language $\mathcal{L} \subseteq \Sigma^\omega$ is said to be A-recognized by a (nondeterministic) Büchi automaton $\mathcal{A} = (Q, \Sigma, \delta, Q_0, F)$ if

$$\alpha \in \mathcal{L} \iff \text{ex. a run } \rho \text{ of } \mathcal{A} \text{ on } \alpha \text{ s.t. } \forall i. \rho[i] \in F.$$

\mathcal{L} is called A-recognizable if there exists an automaton \mathcal{A} that A-recognizes \mathcal{L} .

Prove or disprove that an LT property E is a safety property if and only if E is A-recognizable.

Exercise 3 (DBA):

(2 points)

Formally prove that there is no DBA \mathcal{A} over the alphabet $\Sigma = \{a, b\}$ that accepts the language

$$\mathcal{L} := \mathcal{L}_\omega((a + b)^* . a^\omega).$$

Exercise 4 (Model Checking ω -regular Properties):

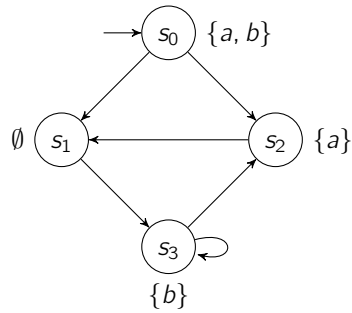
(4 points)

Let the ω -regular LT properties P_1 and P_2 over the set of atomic propositions $AP = \{a, b\}$ be given by

$$P_1 := \text{“if } a \text{ holds infinitely often, then } b \text{ holds finitely often”}$$

$$P_2 := \text{“} a \text{ holds infinitely often and } b \text{ holds infinitely often”}$$

The model is given by the transition system TS as follows:



Algorithmically check whether $TS \models P_1$ and $TS \models P_2$. For this, proceed as follows.

- a) Derive *suitable* NBA \mathcal{A}_{P_1} , \mathcal{A}_{P_2} , where suitable means “appropriate for part b)-d)”.
Hint: For P_1 you can find an automaton with 3 states and for P_2 4 states suffice. Derive the automata directly.
- b) Outline the reachable fragments of the product transition systems $TS \otimes \mathcal{A}_{P_1}$ and $TS \otimes \mathcal{A}_{P_2}$.
- c) Decide whether $TS \models P_1$ by checking an appropriate persistence property via nested depth-first search on $TS \otimes \mathcal{A}_{P_1}$. Document *all* changes to the contents of U , V , π and ξ (the state sets and stacks of the nested depth-first search, see lecture). If the property is violated, provide a counterexample *based on the execution of the algorithm*.
- d) Decide whether $TS \models P_2$ by checking an appropriate persistence property via SCC analysis on $TS \otimes \mathcal{A}_{P_2}$. If the property is violated, provide a counterexample *based on your analysis*.