Theoretical Foundations of the UML Lecture 12: Regular MSCs

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moves.rwth-aachen.de/teaching/ss-16/theoretical-foundations-of-the-uml/

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- Realisability and safe realisability
- 2 Regular MSCs
- 3 Regularity and realisability for MSCs
- Regularity and realisability for MSGs
 Communication closedness

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Definition (Realisability)

- **(**) MSC *M* is realisable whenever $\{M\} = \mathcal{L}(\mathcal{A})$ for some CFM \mathcal{A} .
- **2** A finite set $\{M_1, \ldots, M_n\}$ of MSCs is realisable whenever $\{M_1, \ldots, M_n\} = \mathcal{L}(\mathcal{A})$ for some CFM \mathcal{A} .
- So MSG G is realisable whenever $\mathcal{L}(G) = \mathcal{L}(\mathcal{A})$ for some CFM \mathcal{A} .

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Definition (Safe realisability)

Same as above except that the CFM should be deadlock-free.

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Approach so far:

The (safe) realisation of a (finite) set of MSCs by a weak CFM is the one where the automaton \mathcal{A}_p of process p generates the projections of these MSCs on p.



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Approach so far:

The (safe) realisation of a (finite) set of MSCs by a weak CFM is the one where the automaton \mathcal{A}_p of process p generates the projections of these MSCs on p.

Results so far:

- Conditions for (safe) realisability for finite sets of MSCs.
- ② Checking safe realisability for finite sets of MSCs is in P.
- Checking realisability for finite sets of MSCs is co-NP complete.

• Can similar results be obtained for larger classes of MSGs?



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- What happens if we allow synchronisation messages?
 - recall that weak CFMs do not involve synchronisation messages

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- How do we obtain a CFM realising an MSG algorithmically?
 - in particular, for non-local choice MSGs

- Can similar results be obtained for larger classes of MSGs?
- What happens if we allow synchronisation messages?
 - recall that weak CFMs do not involve synchronisation messages
- How do we obtain a CFM realising an MSG algorithmically?
 - in particular, for non-local choice MSGs
- Are there simple conditions on MSGs that guarantee realisability?
 - e.g., easily identifiable subsets of (safe) realisable MSGs

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Today's lecture



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Today's lecture

Today's setting

(Safe) Realisability of a regular set of MSCs.



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Or, equivalently: (safe) realisability of a regular set of well-formed words (that is, a regular language).



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Results:

 \blacksquare Checking whether a regular language L is well-formed is decidable.

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Results:

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- **2** For well-formed language L:
 - L is regular iff it is (safely) realisable by a \forall -bounded CFM.

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- Every (locally) communication-closed MSG is regular.

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Realisability and safe realisability

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Let \mathbb{M} be the set of MSCs over \mathcal{P} and \mathcal{C} .

Definition (Regular)

- $\mathcal{M} = \{M_1, \ldots, M_n\}$ with $n \in \mathbb{N} \cup \{\infty\}$ is called regular if $Lin(\mathcal{M}) = \bigcup_{i=1}^n Lin(M_i)$ is a regular word language over Act^* .
- **2** MSG G is regular if Lin(G) is a regular word language over Act^* .
- So CFM \mathcal{A} is regular if $Lin(\mathcal{A})$ is a regular word language over Act^* .

Here, Act is the set of actions in \mathcal{M} , G, and \mathcal{A} , respectively.

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On the black board.



[Henriksen et. al, 2005]

The decision problem "is a regular language $L \subseteq Act^*$ well-formed"? that is, does L represent a set of MSCs?— is decidable.

Proof.		
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Proof.

Since L is regular, there exists a minimal DFA $\mathcal{A} = (S, Act, s_0, \delta, F)$ with $\mathcal{L}(\mathcal{A}) = L$.

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• $s \in F \cup \{s_0\}$, implies $K_s((p,q)) = 0$ for every channel (p,q).



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s ∈ F ∪ {s₀}, implies K_s((p,q)) = 0 for every channel (p,q).
 δ(s,!(p,q,a)) = s' implies

$$K_{s'}(c) = \begin{cases} K_s(c) + 1 & \text{if } c = (p, q) \\ K_s(c) & \text{otherwise.} \end{cases}$$



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$$\delta(s,?(p,q,a)) = s' \text{ implies } K_s((q,p)) > 0 \text{ and}$$

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• $\delta(s, \alpha) = s_1$ and $\delta(s_1, \beta) = s_2$ with $\alpha \in Act_p$ and $\beta \in Act_q$, $p \neq q$, implies

not
$$(\alpha = !(p, q, a) \text{ and } \beta = ?(q, p, a))$$
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implies $\delta(s, \beta) = s'_1$ and $\delta(s'_1, \alpha) = s_2$ for some $s'_1 \in S$.

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Constraints on state-labelling

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These constraints can be checked in linear time in the size of relation δ .

Yannakakis' example



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Definition (*B*-bounded words)

Let $B \in \mathbb{N}$ and B > 0. A word $w \in Act^*$ is called *B*-bounded if for any prefix u of w and any channel $(p, q) \in Ch$:

$$0 \hspace{0.1 in} \leqslant \hspace{0.1 in} \sum_{a \in \mathcal{C}} |u|_{!(p,q,a)} - \sum_{a \in \mathcal{C}} |u|_{?(q,p,a)} \hspace{0.1 in} \leqslant \hspace{0.1 in} B$$



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Corollary:

For any regular, well-formed language L, there exists $B \in \mathbb{N}$ and B > 0 such that every $w \in L$ is B-bounded.

14/30

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Corollary:

For any regular, well-formed language L, there exists $B \in \mathbb{N}$ and B > 0 such that every $w \in L$ is B-bounded.

Proof.

The bound B is the largest value attained by the channel-capacity functions assigned to productive states in the proof of the previous theorem.

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Realisability and safe realisability

2 Regular MSCs

8 Regularity and realisability for MSCs

Regularity and realisability for MSGs
Communication closedness

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Regularity and realisability

Theorem:

[Henriksen et al., 2005], [Baudru & Morin, 2007]

For any set L of well-formed words, the following four statements are equivalent:

- 0 L is regular.
- **2** L is realisable by a \forall -bounded CFM.
- **③** *L* is realisable by a deterministic \forall -bounded CFM.
- **③** L is safely realisable by a \forall -bounded CFM.

Regularity and realisability

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Lemma:

The maximal size of the CFM realising L is such that for each process p, the number $|Q_p|$ of states of local automaton \mathcal{A}_p is:

- **Q** double exponential in the bound B and k^2 , where $k = |\mathcal{P}|$, and
- **2** exponential in $m \log m$ where m is the size of the minimal DFA for L.

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Theorem

[Henriksen et. al, 2005]

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The decision problem "is MSG G regular"? is undecidable.

Proof

Outside the scope of this lecture.



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• MSG G is regular if Lin(G) is a regular language



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19/30

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- Is it possible to impose structural conditions on MSGs that guarantee regularity?

- MSG G is regular if Lin(G) is a regular language
- Regularity yields deterministic, or safe, but bounded CFMs
- But, "is MSG G regular"? is unfortunately undecidable
- Is it possible to impose structural conditions on MSGs that guarantee regularity?
- Yes we can. For instance, by constraining:
 - () the communication structure of the MSCs in loops of G, or
 - **2** the structure of expressions describing the MSCs in G

Definition (Communication graph)

The communication graph of the MSC $M = (\mathcal{P}, E, \mathcal{C}, l, m, <)$ is the directed graph (V, \rightarrow) with:

• $V = \mathcal{P} \setminus \{ p \in \mathcal{P} \mid E_p = \emptyset \}$, the set of active processes

• $(p,q) \in \rightarrow$ if and only if $\mathcal{L}(e) = !(p,q,a)$ for some $e \in E$ and $a \in \mathcal{C}$



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Example



Let $G = (V, \rightarrow)$ be a directed graph.

Strongly connected component

• $T \subseteq V$ is strongly connected if for every $v, w \in T$, vertices v and w are mutually reachable (via \rightarrow) from each other.



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Determining the SCCs of a digraph can be done in linear time in the size of V and \rightarrow .

Communication closedness



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A loop is simple if it visits a vertex at most once, except for the start- and end-vertex which are visited twice.



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Definition (Communication closedness)

MSG G is communication-closed if for every simple loop $\pi = v_1 v_2 \dots v_n$ (with $v_1 = v_n$) in G, the communication graph of the MSC $M(\pi) = \lambda(v_1) \bullet \lambda(v_2) \bullet \dots \bullet \lambda(v_n)$ is strongly connected.



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Example

On the black board.



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Theorem:

Every communication-closed MSG G is regular.

Example

Example on the black board.

Note:

The converse does not hold (cf. next slide).

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Communication-closedness is not a necessary condition for regularity:



MSG G is not communication-closed, but Lin(G) is regular.

Theorem:

[Genest et. al, 2006]

The decision problem "is MSG G communication closed?" is co-NP complete.



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Theorem:

[Genest et. al, 2006]

The decision problem "is MSG G communication closed?" is co-NP complete.

Proof

- Membership in co-NP can be proven in a standard way: guess a sub-graph of G, check in polynomial time whether this sub-graph has a loop passing through all its vertices, and check whether its communication graph is not strongly connected.
- **2** Co-NP hardness can be shown by a reduction from the 3-SAT problem.

Definition (Asynchronous iteration)

For $\mathcal{M}_1, \mathcal{M}_2 \subseteq \mathbb{M}$ sets of MSCs, let:

$$\mathcal{M}_1 \bullet \mathcal{M}_2 = \{ M_1 \bullet M_2 \mid M_1 \in \mathcal{M}_1, M_2 \in \mathcal{M}_2 \}$$

For $\mathcal{M} \subseteq \mathbb{M}$ let

$$\mathcal{M}^{i} = \begin{cases} \{M_{\epsilon}\} & \text{if } i=0, \text{ where } M_{\epsilon} \text{ denotes the empty MSC} \\ \mathcal{M} \bullet \mathcal{M}^{i-1} & \text{if } i>0 \end{cases}$$

The asynchronous iteration of \mathcal{M} is now defined by:

$$\mathcal{M}^* = \bigcup_{i \ge 0} \mathcal{M}^i.$$

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Definition (Finitely generated)

Set of MSCs \mathcal{M} is finitely generated if there is a finite set of MSCs $\widehat{\mathcal{M}}$ such that $\mathcal{M} \subseteq \widehat{\mathcal{M}}^*$.



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Remarks:

- \blacksquare Each set of MSCs defined by an MSG G is finitely generated.
- **2** Not every regular well-formed language is finitely generated.
- Not every finitely generated set of MSCs is regular.
- It is decidable to check whether a set of MSCs is finitely generated.

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28/30

Definition (Local communication-closedness)

MSG G is locally communication-closed if for each vertex (v, v') in G, the MSCs $\lambda(v)$, $\lambda(v')$, and $\lambda(v) \bullet \lambda(v')$ all have weakly connected communication graphs.



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Notes:

- A directed graph is weakly connected if its induced undirected graph (obtained by ignoring the directions of edges) is strongly connected.
- **2** Checking whether MSG G is locally communication-closed can be done in linear time.

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Locally communication-closed MSGs are realisable

Theorem:

[Genest *et al.*, 2006]

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Every locally communication-closed MSG G is realisable by a CFM \mathcal{A} of size $m^{\mathcal{O}(|\mathcal{P}|)}$ where m is the number of vertices in G.



30/30

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