

# Theoretical Foundations of the UML

## Lecture 11: Safe Realisability

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[moves.rwth-aachen.de/teaching/ss-16/theoretical-foundations-of-the-uml/](http://moves.rwth-aachen.de/teaching/ss-16/theoretical-foundations-of-the-uml/)

7. Juni 2016

- 1 Safe realisability
- 2 Closure and inference revisited
- 3 Characterisation and complexity of safe realisability

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- 2 If so, how complex is it to obtain such CFM?
- 3 If so, how do such algorithms work?

# Problem variants (1)

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- Consider CFMs without synchronisation messages.
- Allow CFMs that may deadlock. Possibly, a realisation deadlocks.
- Forbid CFMs that deadlock. No realisation will ever deadlock.

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## Results:

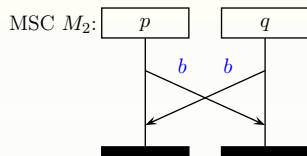
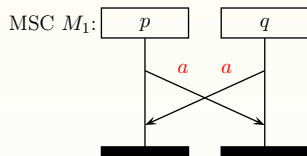
- 1 Conditions for realisability of a finite set of MSCs by a deadlock-free weak CFM.
- 2 Checking safe realisability by deadlock-free CFMs is in P.  
(Realisability for weak CFMs that may deadlock is co-NP complete.)

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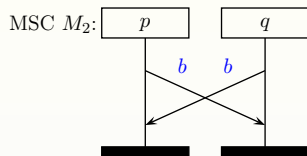
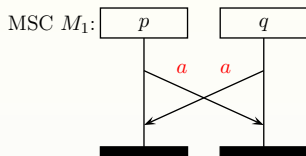
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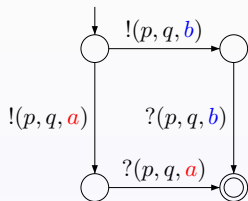
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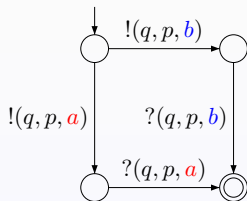


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Realisation of  $\{ M_1, M_2 \}$  by a weak CFM:



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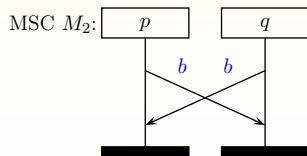
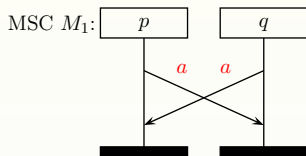


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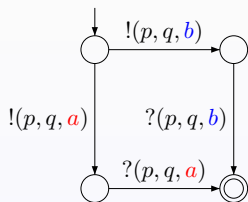
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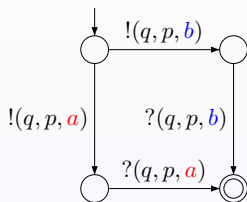


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Realisation of  $\{M_1, M_2\}$  by a weak CFM:



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Deadlock occurs when, e.g.,  
 $p$  sends  $a$  and  $q$  sends  $b$

## Definition (Safe realisability)

- 1 MSC  $M$  is **safely realisable** whenever  $\{M\} = \mathcal{L}(\mathcal{A})$  for some **deadlock-free** CFM  $\mathcal{A}$ .
- 2 A finite set  $\{M_1, \dots, M_n\}$  of MSCs is **safely realisable** whenever  $\{M_1, \dots, M_n\} = \mathcal{L}(\mathcal{A})$  for some **deadlock-free** CFM  $\mathcal{A}$ .
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## Phrased using linearisations

$L \subseteq Act^*$  is **safely realisable** if  $L = Lin(\mathcal{A})$  for some deadlock-free CFM  $\mathcal{A}$ .

## Note:

Safe realisability implies realisability, but the converse does not hold.

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## Definition (Inference relation and closure)

For well-formed  $L \subseteq Act^*$ , and well-formed word  $w \in Act^*$ , let:

$$L \models w \quad \text{iff} \quad (\forall p \in \mathcal{P}. \exists v \in L. w \upharpoonright p = v \upharpoonright p)$$

Language  $L$  is **closed** under  $\models$  whenever for every  $w \in Act^*$ , it holds:  
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## Definition (Weak closure)

Language  $L$  is **weakly closed** under  $\models$  whenever for every well-formed prefix  $w$  of some word in  $L$ , it holds  $L \models w$  implies  $w \in L$ .

Weak closure thus restricts closure under  $\models$  to well-formed prefixes in  $L$  only. So far, closure was required for all  $w \in Act^*$ .

# Deadlock-free closure

For language  $L$ , let  $\text{pref}(L) = \{w \mid \exists u. w \cdot u \in L\}$  the set of **prefixes** of  $L$ .



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For well-formed  $L \subseteq \text{Act}^*$ , and proper word  $w \in \text{Act}^*$ , i.e.,  $w$  is a **prefix of a well-formed word**, let:

$$L \models^{df} w \quad \text{iff} \quad (\forall p \in \mathcal{P}. \exists v \in \text{pref}(L). w \upharpoonright p \text{ is a prefix of } v \upharpoonright p)$$

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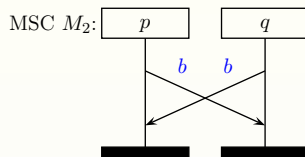
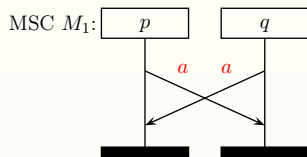
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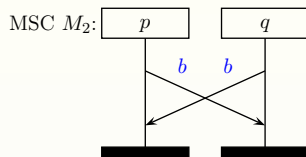
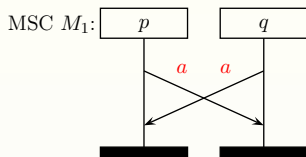
## Intuition

The closure condition asserts that the set of partial MSCs (i.e., prefixes of  $L$ ) can be constructed from the projections of the MSCs in  $L$  onto individual processes.

# Example



# Example



## Example

$L = Lin(\{M_1, M_2\})$  is not closed under  $\models^{df}$ :

$$w = !(p, q, a)!(q, p, b) \notin \text{pref}(L)$$

But:  $L \models^{df} w$  since  $w$  is a proper prefix of a well-formed word, and

- for process  $p$ , there exists  $u \in L$  with  $w \upharpoonright p = !(p, q, a) \in \text{pref}(\{u \upharpoonright p\})$ , and
- for process  $q$ , there exists  $v \in L$  with  $w \upharpoonright q = !(q, p, b) \in \text{pref}(\{v \upharpoonright q\})$ .

Note that  $L$  is closed under  $\models$ . So this shows that closure under  $\models$  does not imply closure under  $\models^{df}$ .

Deadlock-free weak CFM are closed under  $\models^{df}$

Lemma:

For every **deadlock-free** weak CFM  $\mathcal{A}$ ,  $Lin(\mathcal{A})$  is closed under  $\models^{df}$ .

Proof.

Similar proof strategy as for the closure of weak CFMs under  $\models$  (see previous lecture).

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[Alur *et al.*, 2001]

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## Corollary

The finite set of MSCs  $\{M_1, \dots, M_n\}$  is safely realisable iff  $\bigcup_{i=1}^n Lin(M_i)$  is closed under  $\models$  and  $\models^{df}$ .

## Theorem

For any well-formed  $L \subseteq Act^*$ :

$L$  is regular and closed under  $\models$   
if and only if

$L = Lin(\mathcal{A})$  for some  $\forall$ -bounded weak CFM  $\mathcal{A}$ .

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## Proof

- 1 For a given finite set of MSCs, safe realisability can be checked in time  $\mathcal{O}((n^2 + r) \cdot k)$  where  $k$  is the number of processes,  $n$  the number of MSCs, and  $r$  the number of events in all MSCs together.
- 2 If the MSCs are not safely realisable, the algorithm returns an MSC which is implied, but not included in the input set of MSCs.

(We skip the details in this lecture.)