

# Reduced Ordered Binary Decision Diagrams

## Lecture #13 of Advanced Model Checking

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## Basic approach

- let  $TS = (S, \rightarrow, I, AP, L)$  be a “large” finite transition system
  - the set of actions is irrelevant here and has been omitted, i.e.,  $\rightarrow \subseteq S \times S$
- For  $n \geq \lceil \log |S| \rceil$ , let injective function  $enc : S \rightarrow \{0, 1\}^n$ 
  - note:  $enc(S) = \{0, 1\}^n$  is no restriction, as all elements  $\{0, 1\}^n \setminus enc(S)$  can be treated as the encoding of pseudo states that are unreachable
- Identify the states  $s \in S = enc^{-1}(\{0, 1\}^n)$  with  $enc(s) \in \{0, 1\}^n$
- And  $T \subseteq S$  by its **characteristic** function  $\chi_T : \{0, 1\}^n \rightarrow \{0, 1\}$ 
  - that is  $\chi_T(enc(s)) = 1$  if and only if  $s \in T$
- And  $\rightarrow \subseteq S \times S$  by the Boolean function  $\Delta : \{0, 1\}^{2n} \rightarrow \{0, 1\}$ 
  - such that  $\Delta(enc(s), enc(s')) = 1$  if and only if  $s \rightarrow s'$

## Switching functions

- Let  $Var = \{z_1, \dots, z_m\}$  be a finite set of Boolean variables
- An **evaluation** is a function  $\eta : Var \rightarrow \{0, 1\}$ 
  - let  $Eval(z_1, \dots, z_m)$  denote the set of evaluations for  $z_1, \dots, z_m$
  - shorthand  $[z_1 = b_1, \dots, z_m = b_m]$  for  $\eta(z_1) = b_1, \dots, \eta(z_m) = b_m$
- $f : Eval(Var) \rightarrow \{0, 1\}$  is a **switching function** for  $Var = \{z_1, \dots, z_m\}$
- Logical operations and quantification are defined by:

$$\begin{aligned} f_1(\cdot) \wedge f_2(\cdot) &= \min\{f_1(\cdot), f_2(\cdot)\} \\ f_1(\cdot) \vee f_2(\cdot) &= \max\{f_1(\cdot), f_2(\cdot)\} \\ \exists z. f(\cdot) &= f(\cdot)|_{z=0} \vee f(\cdot)|_{z=1}, \text{ and} \\ \forall z. f(\cdot) &= f(\cdot)|_{z=0} \wedge f(\cdot)|_{z=1} \end{aligned}$$

## Polynomial-size data structure impossible

- There is **no** poly-size data structure for all switching functions
  - $|Eval(z_1, \dots, z_m)| = 2^m$ , so #functions  $Eval(z_1, \dots, z_m) \rightarrow \{0, 1\}$  is  $2^{2^m}$
- Suppose there is a data structure that can represent  $K_m$  switching functions by at most  $2^{m-1}$  bits

- Then  $K_m \leq \sum_{i=0}^{2^{m-1}} 2^i = 2^{2^{m-1}+1} - 1 < 2^{2^{m-1}+1}$

- But then there are at least

$$2^{2^m} - 2^{2^{m-1}+1} = 2^{2^{m-1}+1} \cdot \left( 2^{2^m - 2^{m-1} - 1} - 1 \right) = 2^{2^{m-1}+1} \cdot \left( 2^{2^{m-1} - 1} - 1 \right)$$

switching functions whose representation needs more than  $2^{m-1}$  bits

# Representing switching functions

- **Truth tables**
  - very space inefficient:  $2^n$  entries for  $n$  variables
  - satisfiability and equivalence check: easy; boolean operations also easy
  - . . . but have to consider exponentially many lines (so are hard)
- **. . . in Disjunctive Normal Form (DNF)**
  - satisfiability is easy: find a disjunct that does not have complementary literals
  - negation and conjunction complicated
  - equivalence checking ( $f = g?$ ) is coNP-complete
- **. . . in Conjunctive Normal Form (CNF)**
  - satisfiability problem is NP-complete (Cook's theorem)
  - negation and disjunction complicated

# Representing switching functions

<i>representation</i>	<i>compact?</i>	<i>sat</i>	<i>equi</i>	$\wedge$	$\vee$	$\neg$
propositional formula	often	hard	hard	easy	easy	easy
DNF	sometimes	easy	hard	hard	easy	hard
CNF	sometimes	hard	hard	easy	hard	hard
(ordered) truth table	never	hard	hard	hard	hard	hard

## There is hope . . . . . perhaps

Nevertheless there are data structures which yield compact representations for many switching functions that appear in practical applications

for hardware circuits, ordered binary decision diagrams (OBDDs) are successful

## Representing boolean functions

<i>representation</i>	<i>compact?</i>	<i>sat</i>	<i>equ</i>	$\wedge$	$\vee$	$\neg$
propositional formula	often	hard	hard	easy	easy	easy
DNF	sometimes	easy	hard	hard	easy	hard
CNF	sometimes	hard	hard	easy	hard	hard
(ordered) truth table	never	hard	hard	hard	hard	hard
reduced ordered binary decision diagram	often	easy	easy*	medium	medium	easy

\* provided appropriate implementation techniques are used



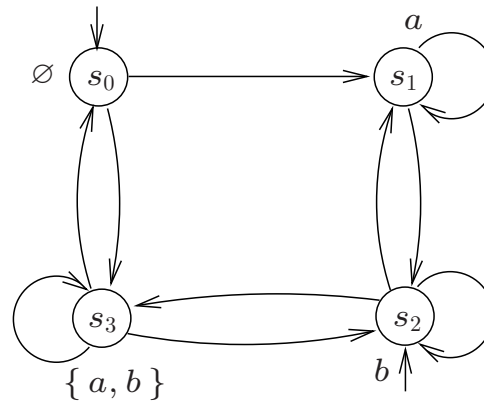
## Binary decision tree

- The BDT for function  $f$  on  $Var = \{z_1, \dots, z_m\}$  has depth  $m$ 
  - outgoing edges for node at level  $i$  stand for  $z_i = 0$  (dashed) and  $z_i = 1$  (solid)
- For evaluation  $s = [z_1 = b_1, \dots, z_m = b_m]$ ,  $f(s)$  is the value of the leaf
  - reached by traversing the BDT from the root using branch  $z_i = b_i$  for at level  $i$
- The subtree of node  $v$  at level  $i$  for variable ordering  $z_1 < \dots < z_m$  represents

$$f_v = f|_{z_1=b_1, \dots, z_{i-1}=b_{i-1}}$$

- which is a switching function over  $\{z_i, \dots, z_m\}$  and
- where  $z_1 = b_1, \dots, z_{i-1} = b_{i-1}$  is the sequence of decisions made along the path from the root to node  $v$

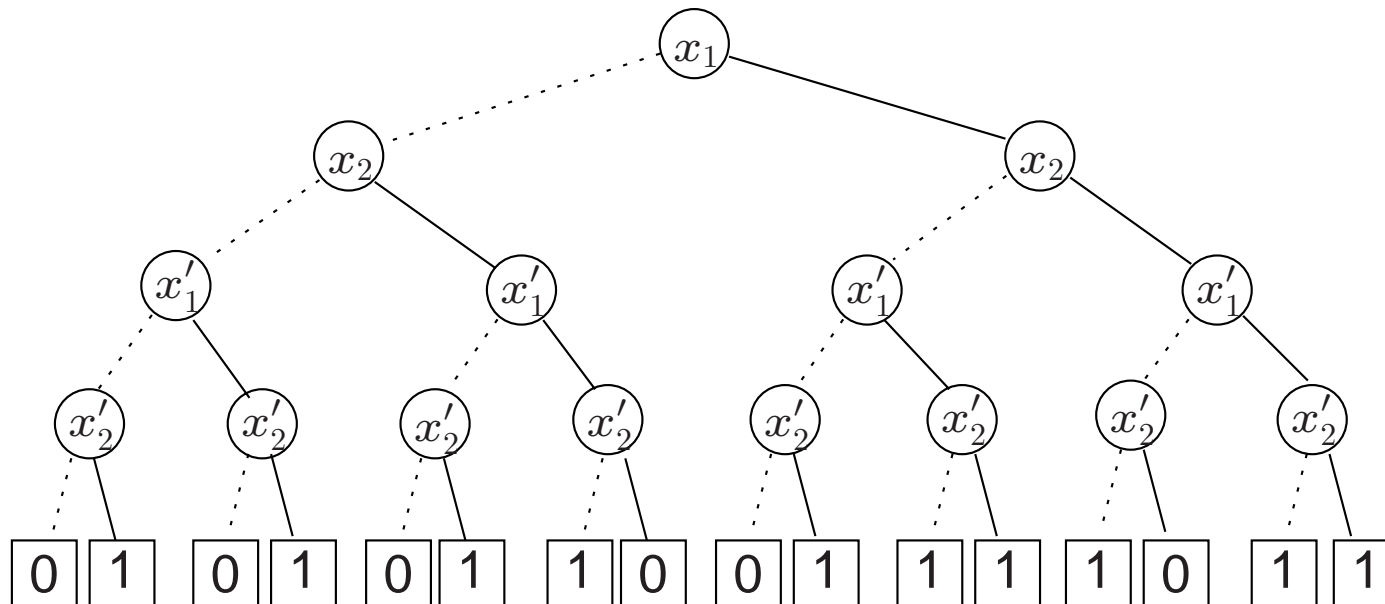
# Symbolic representation of a transition system



Switching function:  $\Delta(\underbrace{x_1, x_2}_s, \underbrace{x'_1, x'_2}_{s'}) = 1$  if and only if  $s \rightarrow s'$

$$\begin{aligned} \Delta(x_1, x_2, x'_1, x'_2) = & (\neg x_1 \wedge \neg x_2 \wedge \neg x'_1 \wedge x'_2) \\ & \vee (\neg x_1 \wedge \neg x_2 \wedge x'_1 \wedge x'_2) \\ & \vee (\neg x_1 \wedge x_2 \wedge x'_1 \wedge \neg x'_2) \\ & \vee \dots \\ & \vee (x_1 \wedge x_2 \wedge x'_1 \wedge x'_2) \end{aligned}$$

## Transition relation as a BDT



A BDT representing  $\Delta$  for our example using ordering  $x_1 < x_2 < x'_1 < x'_2$

## Considerations on BDTs

- BDTs are **not compact**
  - a BDT for switching function  $f$  on  $n$  variables has  $2^n$  leafs
  - ⇒ they are as space inefficient as truth tables!
- ⇒ BDTs contain quite some **redundancy**
  - all leafs with value one (zero) could be collapsed into a single leaf
  - a similar scheme could be adopted for isomorphic subtrees
- The size of a BDT does not change if the variable order changes

## Ordered Binary Decision Diagram

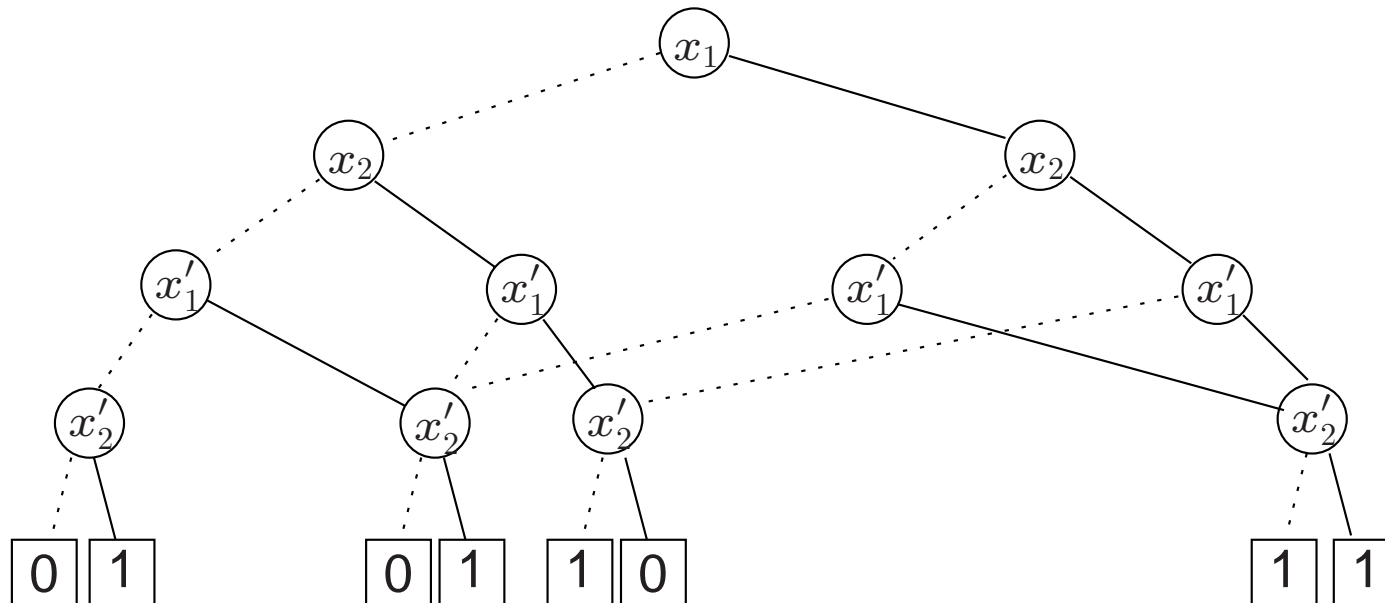
Let  $\wp$  be a **variable ordering** for  $Var$  where  $z_1 <_{\wp} \dots <_{\wp} z_m$

An  $\wp$ -OBDD is a tuple  $\mathfrak{B} = (V, V_I, V_T, succ_0, succ_1, var, val, v_0)$  with

- a finite set  $V$  of nodes, partitioned into  $V_I$  (**inner**) and  $V_T$  (**terminals**)
  - and a distinguished **root**  $v_0 \in V$
- **successor functions**  $succ_0, succ_1 : V_I \rightarrow V$ 
  - such that each node  $v \in V \setminus \{v_0\}$  has at least one predecessor
- **labeling functions**  $var : V_I \rightarrow Var$  and  $val : V_T \rightarrow \{0, 1\}$  satisfying

$$v \in V_I \wedge w \in \{succ_0(v), succ_1(v)\} \cap V_I \Rightarrow var(v) <_{\wp} var(w)$$

## Transition relation as an OBDD



An example OBDD representing  $f_{\rightarrow}$  for our example using  $x_1 < x_2 < x'_1 < x'_2$

## Bottom-up characterization of $f_{\mathfrak{B}}$

Let  $\mathfrak{B}$  be a  $\wp$ -OBDD. Switching function  $f_v$  for node  $v \in V$  :

- If  $v \in V_T$ , then  $f_v$  is the constant switching function with value  $val(v)$
- If  $v \in V_I$  with  $var(v) = z$ , then  $f_v = \underbrace{(\neg z \wedge f_{succ_0(v)}) \vee (z \wedge f_{succ_1(v)})}_{\text{Shannon expansion}}$

Furthermore,  $f_{\mathfrak{B}} = f_{v_0}$  for the root  $v_0$  of  $\mathfrak{B}$

## Consistent co-factors in OBDDs

- Let  $f$  be a switching function for  $Var$
- Let  $\wp = (z_1, \dots, z_m)$  a variable ordering for  $Var$ , i.e.,  $z_1 <_{\wp} \dots <_{\wp} z_m$
- Switching function  $g$  is a  *$\wp$ -consistent cofactor* of  $f$  if

$$g = f|_{z_1=b_1, \dots, z_i=b_i} \quad \text{for some } i \in \{0, 1, \dots, m\}$$

- Then it holds that:
  1. for each node  $v$  of an  $\wp$ -OBDD  $\mathfrak{B}$ ,  $f_v$  is a  $\wp$ -consistent cofactor of  $f_{\mathfrak{B}}$
  2. for each  $\wp$ -consistent cofactor  $g$  of  $f_{\mathfrak{B}}$  there is a node  $v \in \mathfrak{B}$  with  $f_v = g$



## Reduced OBDDs

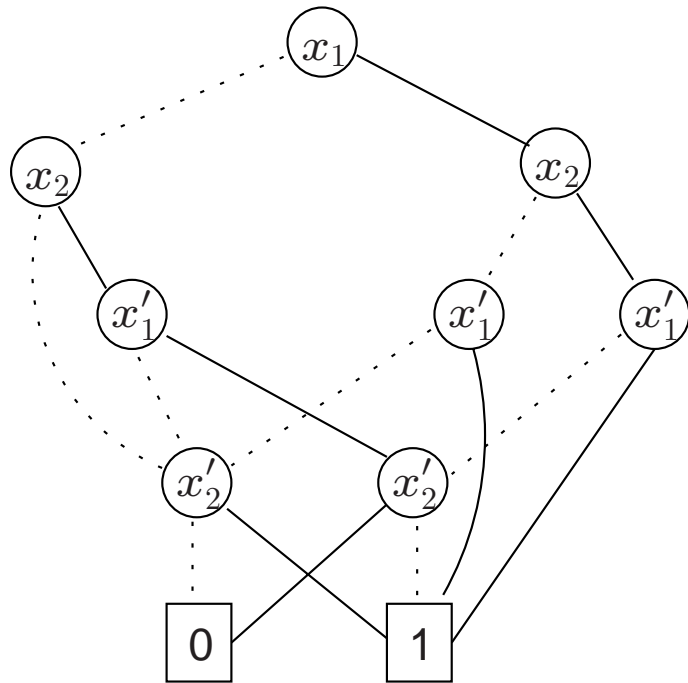
A  $\wp$ -OBDD  $\mathfrak{B}$  is *reduced* if for every pair  $(v, w)$  of nodes in  $\mathfrak{B}$ :

$$v \neq w \text{ implies } f_v \neq f_w$$

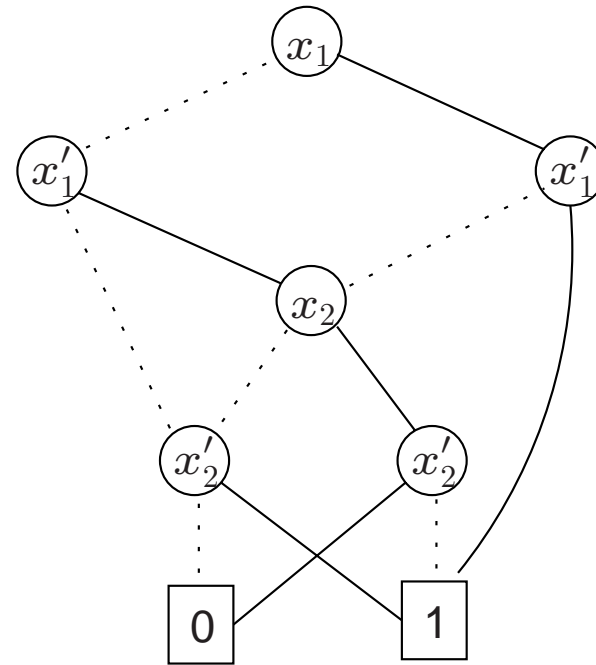
(A *reduced*  $\wp$ -OBDD is abbreviated as  $\wp$ -ROBDD)

$\Rightarrow$  in  $\wp$ -ROBDDs any  $\wp$ -consistent cofactor is represented by *exactly one node*

## Transition relation as an ROBDD



(a) ordering  $x_1 < x_2 < x'_1 < x'_2$



(b) ordering  $x_1 < x'_1 < x_2 < x'_2$

# Universality and canonicity theorem

[Fortune, Hopcroft & Schmidt, 1978]

Let  $Var$  be a finite set of Boolean variables and  $\wp$  a variable ordering for  $Var$ . Then:

- (a) For each switching function  $f$  for  $Var$  there **exists** a  $\wp$ -ROBDD  $\mathfrak{B}$  with  $f_{\mathfrak{B}} = f$
- (b) Any  $\wp$ -ROBDDs  $\mathfrak{B}$  and  $\mathfrak{C}$  with  $f_{\mathfrak{B}} = f_{\mathfrak{C}}$  are **isomorphic**

Any  $\wp$ -OBDD  $\mathfrak{B}$  for  $f$  is reduced iff  $size(\mathfrak{B}) \leq size(\mathfrak{C})$  for each  $\wp$ -OBDD  $\mathfrak{C}$  for  $f$

# Proofs

## The importance of canonicity

- **Absence of redundant vertices**
  - if  $f_{\mathfrak{B}}$  does not depend on  $z_i$ , ROBDD  $\mathfrak{B}$  does not contain an  $x_i$  node
- Test for **equivalence**:  $f(x_1, \dots, x_n) \equiv g(x_1, \dots, x_n)$ ?
  - generate ROBDDs  $\mathfrak{B}_f$  and  $\mathfrak{B}_g$ , and check isomorphism
- Test for **validity**:  $f(x_1, \dots, x_n) = 1$ ?
  - generate ROBDD  $\mathfrak{B}_f$  and check whether it only consists of a 1-leaf
- Test for **implication**:  $f(x_1, \dots, x_n) \rightarrow g(x_1, \dots, x_n)$ ?
  - generate ROBDD  $\mathfrak{B}_{f \wedge \neg g}$  and check if it just consists of a 0-leaf
- Test for **satisfiability**
  - $f$  is satisfiable if and only if  $\mathfrak{B}_f$  has a reachable 1-leaf

## Minimality of ROBDDs

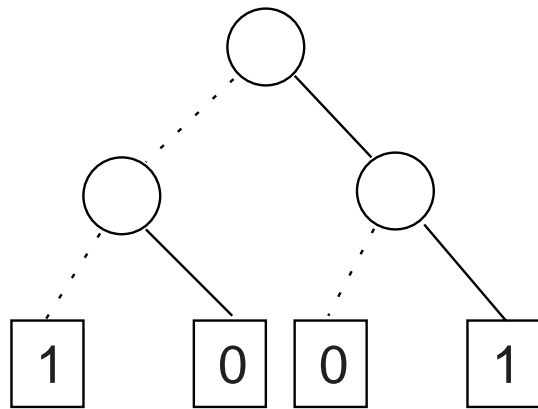
For any  $\wp$ -OBDD  $\mathfrak{B}$  for  $f$   $\mathfrak{B}$  is reduced iff  $size(\mathfrak{B}) \leq size(\mathfrak{C})$  for each  $\wp$ -OBDD  $\mathfrak{C}$  for  $f$

## Reducing OBDDs

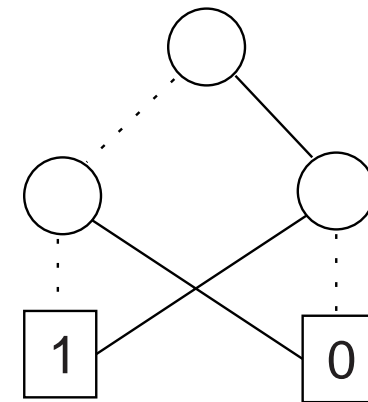
- Generate an OBDD (or BDT) for a switching function, then **reduce**
  - by means of a recursive descent over the OBDD
- **Elimination of duplicate leaves**
  - for a duplicate 0-leaf (or 1-leaf), redirect all incoming edges to just one of them
- **Elimination of “don’t care” (non-leaf) vertices**
  - if  $succ_0(v) = succ_1(v) = w$ , delete  $v$  and redirect all its incoming edges to  $w$
- **Elimination of isomorphic subtrees**
  - if  $v \neq w$  are roots of isomorphic subtrees, remove  $w$  and redirect all incoming edges to  $w$  to  $v$

note that the first reduction is a special case of the latter

# How to reduce an OBDD?



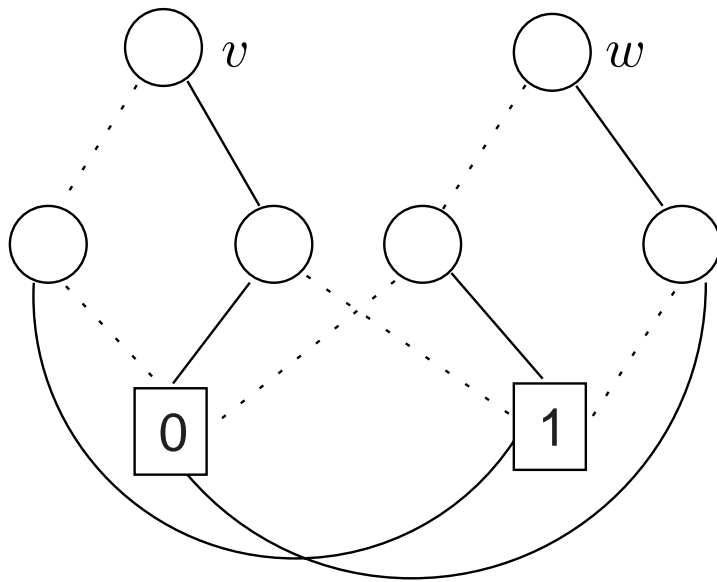
becomes



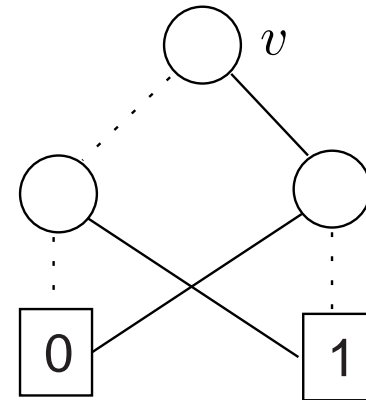
*elimination of duplicated leaves*



# How to reduce an OBDD?

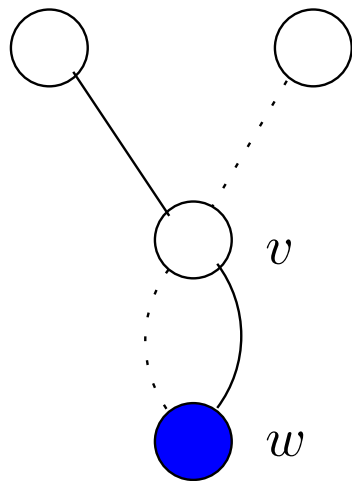


becomes

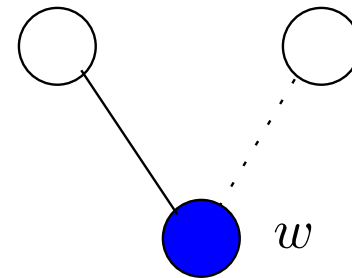


*isomorphism rule*

# How to reduce an OBDD?



becomes



*elimination rule*

## Soundness and completeness

if  $\mathcal{C}$  arises from a  $\wp$ -OBDD  $\mathfrak{B}$  by applying the elimination or isomorphism rule, then:

$\mathcal{C}$  is a  $\wp$ -OBDD with  $f_{\mathfrak{B}} = f_{\mathcal{C}}$

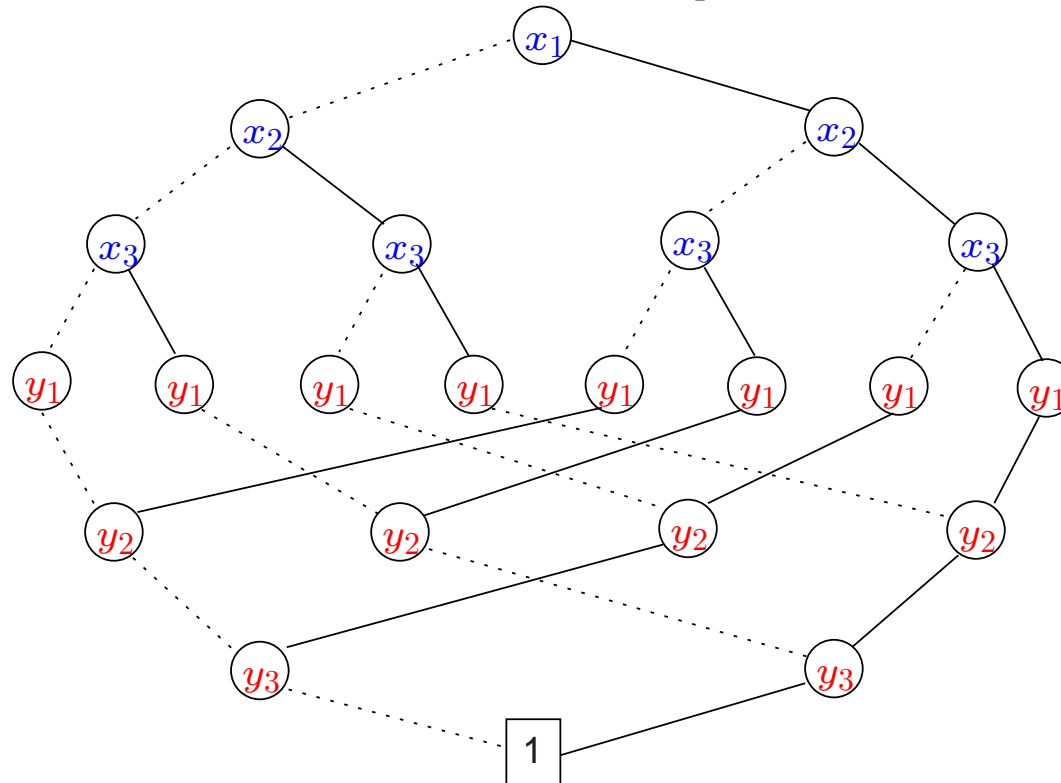
$\wp$ -OBDD  $\mathfrak{B}$  is reduced if and only if no reduction rule is applicable to  $\mathfrak{B}$

# Proof

## Variable ordering

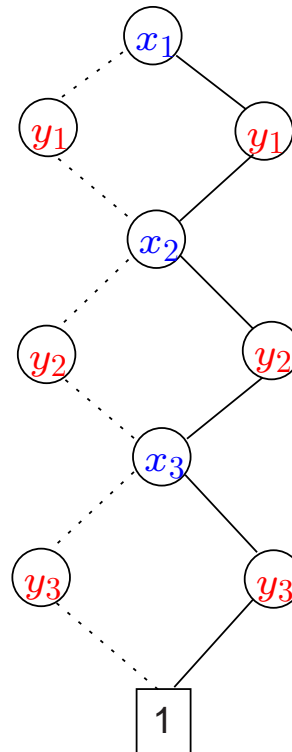
- ROBDDs are canonical for a **fixed** variable ordering
  - the size of the ROBDD crucially depends on the variable ordering
  - $\#$  nodes in ROBDD  $\mathcal{B} = \#$  of  $\wp$ -consistent co-factors of  $f$
- Some switching functions have **linear and exponential** ROBDDs
  - e.g., the addition function, or the stable function
- Some switching functions only have **polynomial** ROBDDs
  - this holds, e.g., for symmetric functions (see next)
  - examples  $f(\dots) = x_1 \oplus \dots \oplus x_n$ , or  $f(\dots) = 1$  iff  $\geq k$  variables  $x_i$  are true
- Some switching functions only have **exponential** ROBDDs
  - this holds, e.g., for the middle bit of the multiplication function

## The function stable with exponential ROBDD



The ROBDD of  $f_{stab}(\bar{x}, \bar{y}) = (x_1 \leftrightarrow y_1) \wedge \dots \wedge (x_n \leftrightarrow y_n)$   
 has  $3 \cdot 2^n - 1$  vertices under ordering  $x_1 < \dots < x_n < y_1 < \dots < y_n$

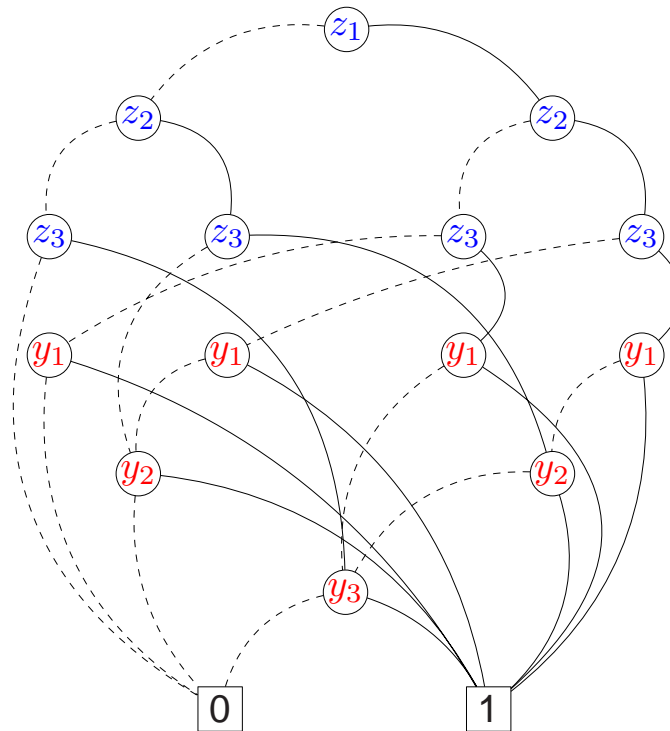
## The function stable with linear ROBDD



The ROBDD of  $f_{stab}(\bar{x}, \bar{y}) = (x_1 \leftrightarrow y_1) \wedge \dots \wedge (x_n \leftrightarrow y_n)$

has  $3 \cdot n + 2$  vertices under ordering  $x_1 < y_1 < \dots < x_n < y_n$

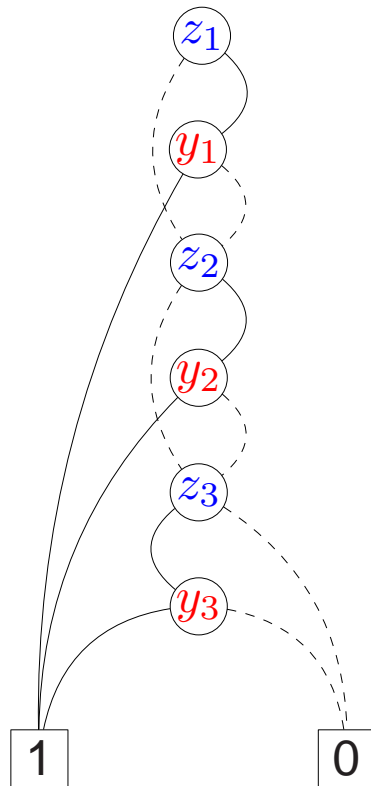
## Another function with an exponential ROBDD



ROBDD for  $f_3(\bar{z}, \bar{y}) = (z_1 \wedge y_1) \vee (z_2 \wedge y_2) \vee (z_3 \wedge y_3)$   
 for the variable ordering  $z_1 < z_2 < z_3 < y_1 < y_2 < y_3$



## And an optimal linear ROBDD



- ROBDD for  $f_3(\cdot) = (z_1 \wedge y_1) \vee (z_2 \wedge y_2) \vee (z_3 \wedge y_3)$
- for ordering  $z_1 < y_1 < z_2 < y_2 < z_3 < y_3$
- as all variables are essential for  $f$ , this ROBDD is **optimal**
- that is, for no variable ordering a smaller ROBDD exists

## Symmetric functions

$f \in Eval(z_1, \dots, z_m)$  is **symmetric** if and only if

$$f([z_1 = b_1, \dots, z_m = b_m]) = f([z_1 = b_{i_1}, \dots, z_m = b_{i_m}])$$

for each permutation  $(i_1, \dots, i_m)$  of  $(1, \dots, m)$

E.g.:  $z_1 \vee z_2 \vee \dots \vee z_m$ ,  $z_1 \wedge z_2 \wedge \dots \wedge z_m$ , the parity function, and the majority function

If  $f$  is a symmetric function with  $m$  essential variables, then for each variable ordering  $\wp$  the  $\wp$ -ROBDD has size  $\mathcal{O}(m^2)$

## The even parity function

$f_{\text{even}}(x_1, \dots, x_n) = 1$  iff the number of variables  $x_i$  with value 1 is even

*truth table or propositional formula for  $f_{\text{even}}$  has exponential size*

*but an ROBDD of linear size is possible*

## The multiplication function

- Consider two  $n$ -bit integers
  - let  $b_{n-1}b_{n-2} \dots b_0$  and  $c_{n-1}c_{n-2} \dots c_0$
  - where  $b_{n-1}$  is the most significant bit, and  $b_0$  the least significant bit
- Multiplication yields a  $2n$ -bit integer
  - the ROBDD  $\mathfrak{B}_{f_{n-1}}$  has at least  $1.09^n$  vertices
  - where  $f_{n-1}$  denotes the  $(n-1)$ -st output bit of the multiplication

## Optimal variable ordering

- The size of ROBDDs is dependent on the variable ordering
- Is it possible to determine  $\wp$  such that the ROBDD has minimal size?
  - to check whether a variable ordering is optimal is NP-hard
  - polynomial reduction from the 3SAT problem [Bollig & Wegener, 1996]
- There are many switching functions with large ROBDDs
  - for almost all switching functions the minimal size is in  $\Omega(\frac{2^n}{n})$
- How to deal with this problem in practice?
  - guess a variable ordering in advance
  - rearrange the variable ordering during the ROBDD manipulations
  - not necessary to test all  $n!$  orderings, best known algorithm in  $\mathcal{O}(3^n \cdot n^2)$

# Variable swapping

# Sifting algorithm

[Rudell, 1993]

Dynamic variable ordering using variable swapping:

1. Select a variable  $x_i$  in OBDD at hand
  2. Successively swap  $x_i$  to determine  $size(\mathfrak{B})$  at any position for  $x_i$
  3. Shift  $x_i$  to position for which  $size(\mathfrak{B})$  is minimal
  4. Go back to the first step until no improvement is made
- Characteristics:
    - a variable may change position several times during a single sifting iteration
    - often yields a local optimum, but works well in practice

## Interleaved variable ordering

- Which variable ordering to use for transition relations?
- The **interleaved** variable ordering:
  - for encodings  $x_1, \dots, x_n$  and  $y_1, \dots, y_n$  of state  $s$  and  $t$  respectively:

$$x_1 < y_1 < x_2 < y_2 < \dots < x_n < y_n$$

- This variable ordering yields compact ROBDDs for binary relations
  - for transition relation with  $z_1 \dots z_m$  be the encoding of action  $\alpha$ , take:

$$\underbrace{z_1 < z_2 < \dots < z_m}_{\text{encoding of } \alpha} < \underbrace{x_1 < y_1 < x_2 < y_2 < \dots < x_n < y_n}_{\text{interleaved order of states}}$$