Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks

# Interpolation over Nonlinear Arithmetic

#### Towards Program Reasoning and Verification

#### Mingshuai Chen



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—Joint work with J. Wang, B. Zhan, N. Zhan, D. Kapur, J. An, T. Gan, L. Dai, and B. Xia—



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#### Interpolation /intə:pə'leij(ə)n/

MATHEMATICS

"the insertion of an intermediate value or term into a series by estimating or calculating it from surrounding known values."

[OXFORD Dictionary]

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LOGICAL REASONING

 $P \models Q \qquad P \models R \models Q$ 

 $P \land Q \models \bot$   $P \models R$  and  $R \land Q \models \bot$ 

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## Interpolants as Loop Invariants

#### Example ([Sharma et al., CAV '12])

$$\begin{split} & \textbf{x} := 0; \textbf{y} := 0; \\ & \text{while } (*) \\ & \{ \textbf{x} := \textbf{x} + 1; \textbf{y} := \textbf{y} + 1; \} \\ & \text{while } (\textbf{x} \neq 0) \\ & \{ \textbf{x} := \textbf{x} - 1; \textbf{y} := \textbf{y} - 1; \} \\ & \text{if } (\textbf{y} \neq 0) \\ & \text{error ()}; \end{split}$$

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## Interpolants as Loop Invariants

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$$\begin{aligned} & x := 0; y := 0; \\ & \text{while } (*) \\ & \{x := x + 1; y := y + 1; \} \\ & - - - - - \\ & \text{while } (x \neq 0) \\ & \{x := x - 1; y := y - 1; \} \\ & \text{if } (y \neq 0) \\ & \text{error } (); \end{aligned}$$

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$$A \stackrel{=}{=} x_1 = 0 \land y_1 = 0 \land$$
  
ite (b,  
 $x = x_1 \land y = y_1,$   
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$$B \stackrel{=}{=} ite (x = 0,$$
  
 $x_2 = x \land y_2 = y,$   
 $x_2 = x - 1 \land y_2 = y - 1$ )  $\land$   
 $x_2 = 0 \land \neg (y_2 = 0)$ 

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### Interpolants as Loop Invariants

#### Example ([Sharma et al., CAV'12])

$$x := 0; y := 0;$$
  
while (\*)  
{ $x := x + 1; y := y + 1;$ }  
while ( $x \neq 0$ )  
{ $x := x - 1; y := y - 1;$ }  
if ( $y \neq 0$ )  
error ();

$$A \cong x_1 = 0 \land y_1 = 0 \land$$
  
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 $A \wedge B \models \bot$ .  $I(x, y) \cong x = y$  s.t.  $A \models I$  and  $I \wedge B \models \bot$ .

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 $A \wedge B \models \bot$ .  $I(x, y) \stackrel{c}{=} x = y$  s.t.  $A \models I$  and  $I \wedge B \models \bot$ .



Figure – Bounded model checking.



Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks

## Interpolation-based Verification

© The bottleneck of existing formal verification techniques lies in scalability.

Implementation & Evaluation

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© The bottleneck of existing formal verification techniques lies in scalability.

© Interpolation helps in scaling these verification techniques due to its inherent capability of local and modular reasoning :

- Nelson-Oppen method : equivalently decomposing a formula of a composite theory into formulas of its component theories;
- SMT : combining different decision procedures to verify programs with complicated data structures;
- Bounded model-checking : generating invariants to verify infinite-state systems due to McMillan;

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## Interpolation-based Verification

Interpolant synthesis plays the central role in interpolation-based techniques :

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# Interpolation-based Verification

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© Well-established methods to synthesize interpolants for various theories, e.g., decidable fragments of FOL, LA, multi-sets, etc., and combinations thereof.

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Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks

### Outline

- 1 Interpolation vs. Classification
- 2 Learning Nonlinear Interpolants
- 3 Implementation and Evaluation
- 4 Concluding Remarks

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#### 1 Interpolation vs. Classification

- Craig Interpolation
- Binary Classification
- Interpolants as Classifiers

#### 2 Learning Nonlinear Interpolants

- SVMs with Nonlinear Space Transformation
- The NIL Algorithm and its Variants

#### 3 Implementation and Evaluation

- Performance over Benchmarks
- Perturbations in Parameters

#### 4 Concluding Remarks

Summary

Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
0000			
Craig Interpolation			
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# Craig Interpolant

Given  $\phi$  and  $\psi$  in a theory  $\mathcal{T}$  s.t.  $\phi \land \psi \models_{\mathcal{T}} \bot$ , a formula *I* is a *(reverse) interpolant* of  $\phi$  and  $\psi$  if (1)  $\phi \models_{\mathcal{T}} I$ ; (2)  $I \land \psi \models_{\mathcal{T}} \bot$ ; and (3)  $var(I) \subseteq var(\phi) \cap var(\psi)$ .

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Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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Binary Classification			
Binary Classificat	ion		



Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
0000			
Binary Classification			
Binary Classificat	ion		

Given a training dataset  $X = X^+ \uplus X^-$  of positive/negative sample points, find a classifier  $C: X \mapsto \{\top, \bot\}$ , s.t. (1)  $\forall \vec{x} \in X^+$ .  $C(\vec{x}) = \top$ ; and (2)  $\forall \vec{x} \in X^-$ .  $C(\vec{x}) = \bot$ .



There could be (infinitely) many valid classifiers.

Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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Support Vector Machine (SVM) finds a separating hyperplane that yields the largest distance (functional margin) to the nearest positive and negative samples (support vectors), which boils down to convex optimizations.

Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	<b>Concluding Remarks</b>
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Interpolants as Classifiers			

 $\odot$  Linear interpolants can be viewed as hyperplane classifiers, [Sharma et al., CAV '12] : sampling from  $[\![\phi]\!]$  and  $[\![\psi]\!] \rightarrow$  building a hyperplane classifier  $\rightarrow$  refining by CEs.

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 $\bigcirc$  X<sup>+</sup> and X<sup>-</sup> might not be linearly separable (often the case when sampled from nonlinear  $\phi$  and  $\psi$ , resp.):

$$A \stackrel{\widehat{=}}{=} (x < 2.5 \Rightarrow y \ge 2\sin(x))$$
  
 
$$\wedge (x \ge 2.5 \land x < 5 \Rightarrow y \ge 0.125x^2 + 0.41)$$
  
 
$$\wedge (x \ge 5 \land x \le 6 \Rightarrow y \ge 6.04 - 0.5x)$$

$$B \quad \widehat{=} \quad (\mathbf{x} < 3 \Rightarrow \mathbf{y} \le \mathbf{x} \cos(0.1 e^{\mathbf{x}}) - 0.083)$$
$$\wedge (\mathbf{x} \ge 3 \land \mathbf{x} \le 6 \Rightarrow \mathbf{y} \le -\mathbf{x}^2 + 10\mathbf{x} - 22.35)$$



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© NIL : learning nonlinear interpolants.

Mingshuai Chen · i2, RWTH Aachen Univ.

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Nonlinear SVMs

# Space Transformation & Kernel Trick



Figure – 2-dimensional input space

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# Space Transformation & Kernel Trick



Figure – 2-dimensional input space

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# Space Transformation & Kernel Trick



Figure – 2-dimensional input space  $\mapsto$  3-dimensional feature (monomial) space with linear separation.

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Nonlinear SVMs

# Space Transformation & Kernel Trick



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# Space Transformation & Kernel Trick



Figure – 2-dimensional input space  $\mapsto$  3-dimensional feature (monomial) space with linear separation.

Optimal-margin classifier /:

$$\sum_{i=1}^{n} \alpha_{i} \kappa(\vec{\mathbf{x}}_{i}, \mathbf{x}) = 0$$

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Nonlinear SVMs

# Space Transformation & Kernel Trick



Figure – 2-dimensional input space  $\mapsto$  3-dimensional feature (monomial) space with linear separation.

Optimal-margin classifier /:



= 0

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Figure – 2-dimensional input space  $\mapsto$  3-dimensional feature (monomial) space with linear separation.

#### Optimal-margin classifier /:

$$\sum_{i=1}^{n} \alpha_{i} \kappa(\vec{\mathbf{x}}_{i}, \mathbf{x}) = \Phi(\vec{\mathbf{x}}_{i})^{\mathrm{T}} \Phi(\mathbf{x}) = 0$$
support vectors

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 $\sum_{i=1}^{n} \alpha_i \kappa(\vec{\mathbf{x}}_i, \mathbf{x}) = \Phi(\vec{\mathbf{x}}_i)^{\mathrm{T}} \Phi(\mathbf{x}) = (\beta \vec{\mathbf{x}}_i^{\mathrm{T}} \mathbf{x} + \theta)^m = 0$ support vectors

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#### Optimal-margin classifier /:



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The NIL Algorithm & its Variants			
The NIL Algorithm			

- I Given mutually contradictory nonlinear  $\phi$  and  $\psi$  over common variables x.
- Generate sample points by, e.g., (uniformly) scattering random points.
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Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
The NIL Algorithm & its Variants			
The NIL Algorithm	1		

- **1** Given mutually contradictory nonlinear  $\phi$  and  $\psi$  over common variables  $\mathbf{x}$ .
- **2** Generate sample points by, e.g., (uniformly) scattering random points.
- **I** Find a classifier by SVMs (with kernel-degree *m*) as a candidate interpolant.
- Refine the candidate by CEs till it being verified as a true interpolant.



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 $\odot$  Sound, and complete when  $[\![\phi]\!]$  and  $[\![\psi]\!]$  are bounded sets with positive functional margin.

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Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	<b>Concluding Remarks</b>
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The NIL Algorithm & its Variants			

	QE-based method	NIL
Logical strength	strongest : $\exists \mathbf{y}, \phi(\mathbf{x}, \mathbf{y})$ weakest : $\forall \mathbf{x}, \neg \psi(\mathbf{x}, \mathbf{z})$	$medium \Rightarrow robust$
Complexity of I	direct projection $\Rightarrow$ complex	single polynomial $\Rightarrow$ simple
Efficiency	doubly exponential	<b>n</b> × doubly exponential

Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	<b>Concluding Remarks</b>
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Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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QE + template?

Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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The NIL Algorithm & its Variants			

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Complexity of I	direct projection $\Rightarrow$ complex	single polynomial $\Rightarrow$ simple
Efficiency	doubly exponential	<i>n</i> × doubly exponential

QE + template? ⇒ Too many unknown parameters.

Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	<b>Concluding Remarks</b>
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Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	<b>Concluding Remarks</b>
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Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	<b>Concluding Remarks</b>
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Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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The NIL Algorithm & its Variants			

### $NIL_{\delta}$ : For Cases with Zero Functional Margin



 $\odot$   $\delta$ -sound, and  $\delta$ -complete if  $\llbracket \phi \rrbracket$  and  $\llbracket \psi \rrbracket$  are bounded sets even with zero functional margin.

Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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The NIL Algorithm & its Variants			



- $\odot$   $\delta$ -sound, and  $\delta$ -complete if  $\llbracket \phi \rrbracket$  and  $\llbracket \psi \rrbracket$  are bounded sets even with zero functional margin.
- $\ \odot$  May not converge to an actual interpolant when  $[\![\phi]\!]$  or  $[\![\psi]\!]$  is unbounded.

Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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The NIL Algerithm & its Variants			



Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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The NIL Algerithm & its Variants			



Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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The NIL Algorithm & its Variants			



Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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The NIL Algorithm 8 its Variants			



Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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The NIL Algorithm 8 its Variants			


Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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The NIL Algorithm 8 its Variants			

# $NIL^*_{\delta,B}$ : For Unbounded Cases with Varying Tolerance



Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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The NUL Algorithm 8 its Variants			

## $NIL_{\delta B}^{*}$ : For Unbounded Cases with Varying Tolerance



© The sequence of candidate interpolants converges to an actual interpolant.

Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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## Outline

## 1 Interpolation vs. Classification

- Craig Interpolation
- Binary Classification
- Interpolants as Classifiers

#### 2 Learning Nonlinear Interpolants

- SVMs with Nonlinear Space Transformation
- The NIL Algorithm and its Variants

## 3 Implementation and Evaluation

- Performance over Benchmarks
- Perturbations in Parameters

# 4 Concluding Remarks

Summary

Performance over Benchmarks

## Implementation Issues

NIL : an open-source tool in Wolfram Mathematica.

- LIBSVM : SVM classifications;
- Reduce<sup>2</sup>: verification of candidate interpolants;
- FindInstance : generation of counterexamples;
- Rational recovery : rounding off floating-point computations [Lang, Springer NY '12].

III · learnin	g poplinear interpolant
ne. rearran	g noninieur interpolarie
The loof AIL is dedicated to onlineatic. It takes as input of (1), p = / and (1), y = / and namely in each iteration it is counter-examples as new r interpotent, USSVM is interp	sprehecting contribute Javanesa Conje interpolarita to the quantifier here through at markness a part is a valid marking contradictory transition was a more an equipment in an interpolar if the javanesa histopharite an classifier and activity part of the sample quantity quantity quantity philosophy. The law was a transition of complex points in an elevation of the sample quantity quanti
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Corresponding e-mail: shee List of contributions: Mingsh	nns (Bies an in) ad Chen, Jain Tilang, Jie An, Bohsa Zhan, Deepat Kapar, and Najan Zhan
Comments and bug-reports 0 2019 MIC, State Key Lab	are high appreciated. of Computer Science, ISCAS: All rights reserved.
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<sup>2.</sup> CAD implementation for quantifier-free fragment of a first-order theory of polynomials over the reals and its appropriate extension to transcendental functions [Strzeboński, J. Symb. Comput. '11].

Interpolation vs. Cla 0000			Learning Nonlinea 000000	r Interpolants	Implementation & Evaluation ○○●○○○	Concluding Remarks
Performance over B	encl	nmarks				
Benchma	гk	: Exa	mples			
Category	ID	Name	¢	ψ.	I.	Time/s
	2	Necklace	x < -1 $y - x^2 - 1 = 0$	$x \ge 1$ $y + x^2 + 1 = 0$	x < 0 -x < 0	0.11 0.21
	3	Taca	$\begin{aligned} &(x+4)^2+y^2-1 \leq 0 \vee \\ &(x-4)^2+y^2-1 \leq 0 \end{aligned}$	$\begin{array}{l} x^2 + y^2 - 64 \leq 0 \wedge \\ (x+4)^2 + y^2 - 9 \geq 0 \wedge \\ (x-4)^2 + y^2 - 9 \geq 0 \end{array}$	$\frac{x}{233} - \frac{255}{356} + x^2 \left(\frac{y}{49} - \frac{y}{170} - \frac{1}{9}\right) +$ $x \left(\frac{y}{39} + \frac{y^2}{68} - \frac{y}{74} - \frac{1}{55}\right) + \frac{y^4}{146} +$ $\frac{y^3}{29} + \frac{y^2}{74} + \frac{y}{146} + 1 < 0$	0.33
	4	Twisted	$x^2 - 2x\theta^2 + 3ar - y^2$ $-yr + x^2 - 1 \ge 0 \land$ $\frac{1}{120}(-x^6 - y^6) + x^2x^2 -$ $x^2 + \frac{1}{6}(x^4 + x^2y^2 + y^4) +$ $y^2x^2 - y^2 - 4 \le 0$	$\begin{split} & w^2 + 4(x-y)^4 + (x+y)^2 - 80 \leq 0 \wedge \\ & - w^2(x-y)^4 + 100(x+y)^2 - 3000 \geq 0 \end{split}$	$\begin{aligned} & x^{2} - \frac{x^{2}}{160} + x^{2} \left( \frac{y}{170} - \frac{1}{113} \right) + x^{2} \left( -\frac{y^{2}}{222} + \frac{y}{70} + \frac{2}{27} \right) + \\ & x \left( \frac{y^{2}}{220} + \frac{y^{2}}{63} + \frac{5y}{51} - \frac{1}{316} \right) - \frac{y^{4}}{183} - \frac{y^{3}}{94} + \frac{y^{2}}{14} + \frac{y}{255} - 1 < \xi \end{aligned}$	140.62
with/without rounding	5	Ubimate	$ \begin{aligned} (x^2 + y^2 - 3.025 \le 0 \land y \ge 0 \lor \\ (x - 1)^2 + y^2 - 0.0025 \le 0 \land \land \\ (x - 1)^2 + y^2 - 0.09 \ge 0 \land \\ (x - 1)^2 + y^2 - 0.09 \ge 0 \land \\ (x + 1)^2 + y^2 - 1.1022 \ge 0 \lor \\ (x + 1)^2 + y^2 - \frac{1}{25} \le 0 \end{aligned} $	$\begin{array}{l} (-3.8025+x^2+y^2\leq 0 \wedge -y\geq 0 \vee \\ -0.9025+(-1-x)^2+y^2\leq 0 ) \wedge \\ -0.08+(-1-x)^2+y^2> 0 \wedge \\ -1.1025+(1-y)^2+y^2\geq 0 \vee \\ -\frac{1}{25}+(1-y)^2+y^2\leq 0 \end{array}$	$\begin{split} & \frac{\tau}{2\tau} + \delta^2 (\frac{\tau}{2} - \frac{1}{2m}) + \delta^2 (\frac{2\pi^2}{2} - \frac{\tau}{2}) - \frac{1}{2}) + \\ & \delta^2 (\frac{2\pi^2}{2} + \frac{\tau}{2} + \frac{1}{2m}) + \delta^2 (\frac{2\pi^2}{2} - \frac{\pi^2}{2m}) - \frac{1}{2m} + \frac{\tau}{2m} + \frac{1}{2m}) + \\ & \delta^2 (\frac{\pi^2}{2m} - \frac{\pi^2}{2m} - \frac{\pi^2}{2m} - \frac{\pi^2}{2m} - \frac{\pi^2}{2m} - \frac{\pi^2}{2m}) + \\ & \delta (\frac{\delta^2}{2m} + \frac{\pi^2}{2m} - \frac{\pi^2}{2m} - \frac{\pi^2}{2m} - \frac{\pi^2}{2m} + \frac{\pi^2}{2m}) + \\ & \delta (\frac{\delta^2}{2m} + \frac{\pi^2}{2m} - \frac{\pi^2}{2m} - \frac{\pi^2}{2m} - \frac{\pi^2}{2m} - \frac{\pi^2}{2m}) + \\ & \delta (\frac{\delta^2}{2m} - \frac{\pi^2}{2m} - \frac{\pi^2}{2m} - \frac{\pi^2}{2m} - \frac{\pi^2}{2m} - \frac{\pi^2}{2m}) + \\ & \delta (\frac{\delta^2}{2m} - \frac{\pi^2}{2m} - \frac{\pi^2}{2m} - \frac{\pi^2}{2m} - \frac{\pi^2}{2m} - \frac{\pi^2}{2m} + \frac{\pi^2}{2m} - \frac{\pi^2}{2m} + \pi^$	48.82
	6	UCAR16-1	$-x_1^2 + 4x_1 + x_2 - 4 \ge 0 \land$	$-3x_1^2 - x_2^2 + 1 \ge 0 \land x_2 - x^2 \ge 0$	48  7  6  2  6  59  85 $1 - \frac{3y}{24} - \frac{x_2}{2} < 0$	0.16
	7	CAV13-1	$\begin{array}{l} -x_1 - x_2 + 3 - y^a > 0 \\ 1 - a^2 - b^2 > 0 \wedge a^2 + b - 1 - x \equiv 0 \wedge \\ b + bx + 1 - y \equiv 0 \end{array}$	$x^2 - 2y^2 - 4 > 0$	$-1 + \frac{x^2}{2} - \frac{y}{3} + \frac{xy}{3} - \frac{y^2}{4} < 0$ $105t^4 + x^2(140t^2 + 24y(5t+7) + 35t(3t+8)) +$	125

 $20 - 3x^2 - 4y^3 - 10x^2 \ge 0 \land$ 

 $x^2 + y^2 - z - 1 = 0$ 

 $w_1 \ge 49.61$ 

y - x < 0 y - x + 1 < 0  $x^{2} + y^{2} - 1 \le 0$   $y + x^{2} <= 0$ 

x + y = 0 $y - x^2 <= 0$ 

 $-y_1 + x_1 - 2 \ge 0 \land 2x_2 - x_1 - 1 > 0 \land$  $-z_1 + 2z_2 + 1 \ge 0 \land 2z_1 - z_2 - 1 > 0 \land$ rounding 16 LICAR16-2  $-y_1^2 - s_1^2 + 2s_1y_1 - 2y_1 + 2s_1 \ge 0 \land$  $-x_1^2 - 4x_2^2 + 4x_2x_1 + 3x_1 - 6x_2 - 2 \ge 0 \wedge$  $x_1 < x_2$  $\begin{array}{l} -y_2^2-y_1^2-x_2^2-4y_1+2s_2-4\geq 0\\ se_1+2ye_1\geq 0 \wedge se_1+2ye_1-s_1\equiv 0 \wedge \end{array}$  $-z_{1}^{2} - z_{1}^{2} - z_{1}^{2} - z_{2}^{2} + 2z_{1} + z_{1} - 2z_{2} - 1 \ge 0$ 17 CAV13-4  $-2xa_1 + ya_1 - y_1 = 0 \land x - x_1 - 1 = 0 \land$ xx + 2yx < 02xx + 4yx > 5 $y = y_1 + x \wedge x_2 = x - 2y \wedge y_2 = 2x + y_1$  $y - x^2 \ge 0$ sin  $x \ge 0.6$  $15x^2 < 4 + 20y$ SVM failed TACAS16 beyond polynomials 12 Transcendental unbalanced 20 Unbalanced Mingshuai Chen · i2, RWTH Aachen Univ. Interpolation over Nonlinear Arithmetic

 $x^2+y^2+z^2-2\geq 0\wedge$ 

 $vc < 49.61 \land fg = 0.5418 vc^2 \land$ 

 $fr \equiv 1000 - fa \wedge ac \equiv 0.0005 fr \wedge$  $vc_1 = vc + ac$ 

 $1.2x^2 + y^2 + xt = 0$ 

 $y - x^2 - 1 \ge 0$ 

 $x + y > 0 \lor x + y < 0$  $y - x^2 > 0$ 

y + 1 < 0

CAV13-3

Sharper-2

Parallel halfplane

10 Parallel parabola

12 Sharper-1

13

14 Coincident

15 Adjacent

with

40.63

4.50

2.46

2.19

2.35

0.25

12.33

3.10

12.71

0.11

 $2(70y^3x + 5y^2(12x^2 + 21x + 28) - 14y(6x^3 + 5x^2 +$ 

 $10) - 35(3x^4 + 8x^2 + 4x - 9)) < 14x(20x^2(x+1) +$  $10y^2(x+2) - 3y(4x^2 - 5x + 4) - 20x(x^2 + 2))$ 

 $-1 + \frac{2w_1}{99} < 0$ 

 $\frac{\frac{1}{2} + x^2}{x < y} < y$ 

y > 0 $(x + y)^2 > 0$  $x^2 < y$ 

Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
Performance over Benchmarks			
Visualizations in <i>i</i>	NIL		

Beyond the scope of concave quadratic formulas as required in [Gan et al., IJCAR '16] :



Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
		000000	
Performance over Benchmarks			
Visualizations in <i>J</i>	NII		

Adjacent and sharper cases as in [Okudono et al., APLAS'17]:



Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
Performance over Benchmarks			
Visualizations in <i>J</i>	NIL		

Formulas sharing parallel or coincident boundaries :



Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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Performance over Benchmarks			
Visualizations in A	///		

Transcendental cases from [Gao & Zufferey, TACAS '16] and [Kupferschmid & Becker, FORMATS '11], yet with simpler interpolants :



Interpolation vs. Classification	Learning Nonlinear Interpolants 000000	Implementation & Evaluation	Concluding Remarks
Performance over Benchmarks			
Visualizations in <i>I</i>	NIL		

Three-dimensional case from [Dai et al., CAV'13], yet with simpler interpolants :



Interpolation vs.	Classification
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Learning Nonlinear Interpolants

Implementation & Evaluation

Concluding Remarks

Performance over Benchmarks

## Interpolants of Simpler Forms

Name	Interpolants by NIL	Interpolants from the sources
IJCAR16-1	$1 - \frac{3x_1}{4} - \frac{x_2}{2} < 0$	$-3 + 2x_1 + x_1^2 + \frac{1}{2}x_2^2 > 0$
CAV13-1	$-1 + \frac{x^2}{2} - \frac{y}{3} + \frac{xy}{3} - \frac{y^2}{4} < 0$	$436.45(x^2 - 2y^2 - 4) + \frac{1}{2} \le 0$
CAV13-2	$\begin{split} &105x^4+x^2\left(140y^2+24y(5z+7)+35z(3z+8)\right)+\\ &2(70y^3z+5y^2(12z^2+21z+28)-14y(6z^3+5z^2+\\ &10)-35(3z^4+8z^2+4z-9)\right)<14x(20x^2(z+1)+\\ &10y^2(z+2)-3y(4z^2-5z+4)-20z(z^2+2)) \end{split}$	$\begin{array}{l} -14629.26+2983.44x_3+10972.97x_3^2+\\ 297.62x_2+297.64x_2x_3+0.02x_2x_3^2+9625.61x_2^2-\\ 1161.80x_2^2x_3+0.01x_2^2x_3^2+811.93x_2^3+\\ 2745.14x_3^2-10648.11x_1+3101.42x_1x_3+\\ 8646.17x_1x_3^2+511.84x_1x_2-1034x_1x_2x_3+\\ 0.02x_1x_2x_3^2+9233.66x_1x_2^2+1342.55x_1x_2^2x_3-\\ 138.70x_1x_2^2+11476.61x_1^2-3737.70x_1^2x_3+\\ 4071.66x_1^2x_3^2-2153.00x_12x_2+373.14x_1^2x_2x_3+\\ 7616.18x_1^2x_2^2+8950.77x_1^3+1937.92x_1^3x_3-\\ 64.07x_1^3x_2+4827.25x_1^4>0\end{array}$
CAV13-3	$-1 + \frac{2vc_1}{99} < 0$	$-1.3983 vc_1 + 69.358 > 0$
Sharper-1	$2 + y < y^2$	$34y^2 - 68y - 102 \ge 0$
Sharper-2	y > 0	$8y + 4x^2 > 0$
IJCAR16-2	$x_1 < x_2$	$-x_1 + x_2 > 0$
CAV13-4	$2x\sigma + 4y\sigma > 5$	$\begin{split} & 716.77 + 1326.74(\textit{ya}) + 1.33(\textit{ya})^2 + 433.90(\textit{ya})^3 + \\ & 668.16(\textit{xa}) - 155.86(\textit{xa})(\textit{ya}) + 317.29(\textit{xa})(\textit{ya})^2 + \\ & 222.00(\textit{xa})^2 + 592.39(\textit{xa})^2(\textit{ya}) + 271.11(\textit{xa})^3 > 0 \end{split}$
TACAS16	$15x^2 < 4 + 20y$	$y > 1.8 \lor (0.59 \le y \le 1.8 \land -1.35 \le x \le 1.35) \lor (0.09 \le y < 0.59 \land -0.77 \le x \le 0.77) \lor (y \ge 0 \land -0.3 \le x \le 0.3)$

Mingshuai Chen · i2, RWTH Aachen Univ.

Interpolation vs.	Classification
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Learning Nonlinear Interpolants

Implementation & Evaluation

Concluding Remarks

Performance over Benchmarks

## Interpolants of Simpler Forms

Name	Interpolants by NIL	Interpolants from the sources
IJCAR16-1	$1 - \frac{3x_1}{4} - \frac{x_2}{2} < 0$	$-3 + 2x_1 + x_1^2 + \frac{1}{2}x_2^2 > 0$
CAV13-1	$-1 + \frac{x^2}{2} - \frac{y}{3} + \frac{xy}{3} - \frac{y^2}{4} < 0$	$436.45(x^2 - 2y^2 - 4) + \frac{1}{2} \le 0$
CAV13-2	$\begin{array}{l} 105x^4+x^2(140y^2+24y(5z+7)+35z(3z+8))+\\ 2(70y^3z+5y^2(12z^2+21z+28)-14y(6z^3+5z^2+\\ 10)-35(3z^4+8z^2+4z-9))<14x(20x^2(z+1)+\\ 10y^2(z+2)-3y(4z^2-5z+4)-20z(z^2+2)) \end{array}$	$\begin{array}{l} -14629.26+2983.44x_3+10972.97x_3^2+\\ 297.62x_2+297.64x_2x_3+0.02x_2x_3^2+9625.61x_2^2-\\ 1161.80x_2^2x_3+0.01x_2^2x_3^2+811.93x_2^2+\\ 2745.14x_3^2-10648.11x_1+3101.42x_1x_3+\\ 8646.17x_1x_3^2+511.84x_1x_2-1034x_1x_2x_3+\\ 0.02x_1x_2x_3^2+9223.66x_1x_2^2+1342.55x_1x_2^2x_3-\\ 138.70x_1x_3^2+11476.61x_1^2-3737.70x_1^2x_3+\\ 4071.66x_1^2x_2^2-2153.00x_1x_2+373.14x_1^2x_2x_3+\\ 7616.18x_1^2x_2^2+8950.77x_1^3+1937.92x_1^3x_3-\\ 64.07x_1^2x_2+4827.25x_1^4>0\end{array}$
CAV13-3	$-1 + \frac{2vc_1}{99} < 0$	$-1.3983 \mathrm{vc}_1 + 69.358 > 0$
Sharper-1	$2 + y < y^2$	$34y^2 - 68y - 102 \ge 0$
Sharper-2	y > 0	$8y + 4x^2 > 0$
IJCAR16-2	$x_1 < x_2$	$-x_1 + x_2 > 0$
CAV13-4	$2x\sigma + 4y\sigma > 5$	$\begin{split} & 716.77 + 1326.74(\texttt{ya}) + 1.33(\texttt{ya})^2 + 433.90(\texttt{ya})^3 + \\ & 668.16(\texttt{xa}) - 155.86(\texttt{xa})(\texttt{ya}) + 317.29(\texttt{xa})(\texttt{ya})^2 + \\ & 222.00(\texttt{xa})^2 + 592.39(\texttt{xa})^2(\texttt{ya}) + 271.11(\texttt{xa})^3 > 0 \end{split}$
TACAS16	$15x^2 < 4 + 20y$	$\begin{array}{l} y > 1.8 \lor (0.59 \le y \le 1.8 \land -1.35 \le x \le 1.35) \lor \\ (0.09 \le y < 0.59 \land -0.77 \le x \le 0.77) \lor \\ (y \ge 0 \land -0.3 \le x \le 0.3) \end{array}$

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Interpolation over Nonlinear Arithmetic

Interpolation vs.	Classification
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Learning Nonlinear Interpolants

Implementation & Evaluation

Concluding Remarks

Perturbations in Parameters

## Perturbation-Resilient Interpolants



Figure – Introducing  $\epsilon$ -perturbations (say with  $\epsilon$  up to 0.5) in  $\phi$  and  $\psi$ . The synthesized interpolant is hence resilient to any  $\epsilon$ -perturbation in the radii satisfying  $-0.5 \le \epsilon \le 0.5$ .

Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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## Outline

## 1 Interpolation vs. Classification

- Craig Interpolation
- Binary Classification
- Interpolants as Classifiers

#### 2 Learning Nonlinear Interpolants

- SVMs with Nonlinear Space Transformation
- The NIL Algorithm and its Variants

## 3 Implementation and Evaluation

- Performance over Benchmarks
- Perturbations in Parameters

# 4 Concluding RemarksSummary

Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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Summary			

## **Concluding Remarks**

#### Problem : We face that

- polynomial constraints have been shown useful to express invariant properties for programs and hybrid systems,
- little work on synthesizing nonlinear interpolants, which either restricts the input formulae or yields complex results.



Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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- a unified, counterexample-guided method for generating polynomial interpolants over the general quantifier-free theory of nonlinear arithmetic,
- soundness of NIL, and sufficient conditions for its completeness and convergence,
- Experimental results indicating that our method suffices to address more interpolation tasks, including those with perturbations in parameters, and in many cases synthesizes simpler interpolants.



Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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#### Future Work : We plan to

- improve the efficiency of NIL by substituting the general purpose QE procedure with alternative methods,
- combine nonlinear arithmetic with EUFs, by resorting to, e.g., predicate-abstraction techniques,
- investigate the performance of NIL over different classification techniques, e.g., the widespread regression-based methods.



Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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# **Probabilistic Craig Interpolants?**



Interpolation vs. Classification	Learning Nonlinear Interpolants	Implementation & Evaluation	Concluding Remarks
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# Probabilistic Craig Interpolants?

Generalized Craig Interpolation for stochastic-SAT : resolution-based BMC of MDPs.

- ⇒ Teige, T., Fränzle, M.: Generalized Craig Interpolation for Stochastic Boolean Satisf. Prob.. TACAS '11.
- Generalized Craig Interpolation for stochastic-SMT : resolution-based UMC of PHA.
  - ⇒ Mahdi, A., Fränzle, M.: Generalized Craig Interpolation for Stochastic Satisf. Modulo Theory Prob.. RP '14.

