



Modelling and Analysing Concurrent Systems

RIO 2023 Summer School of Informatics

Rio Cuarto, Argentina; February 13–17, 2023

Lecture 4: Application to Mutual-Exclusion Protocols

Thomas Noll

Software Modelling and Verification Group

RWTH Aachen University

<https://moves.rwth-aachen.de/teaching/ws-22-23/rio/>

Outline of Lecture 4

Modelling Mutual Exclusion Algorithms

Evaluating the CCS Model

Verifying Properties by Model Checking

Verifying Mutual Exclusion by Bisimulation Checking

The End

Peterson's Mutual Exclusion Algorithm

- **Goal:** ensuring **exclusive access to non-shared resources**
- Here: two competing processes P_1, P_2 and shared variables
 - b_1, b_2 (Boolean, both initially **false**) – b_i indicates that P_i wants to enter critical section
 - k (in $\{1, 2\}$, arbitrary initial value) – index of prioritised process
- P_i uses local variable $j := 2 - i$ (index of other process)

Peterson's Mutual Exclusion Algorithm

- **Goal:** ensuring **exclusive access to non-shared resources**
- Here: two competing processes P_1, P_2 and shared variables
 - b_1, b_2 (Boolean, both initially **false**) – b_i indicates that P_i wants to enter critical section
 - k (in $\{1, 2\}$, arbitrary initial value) – index of prioritised process
- P_i uses local variable $j := 2 - i$ (index of other process)

Algorithm 4.1 (Peterson's algorithm for P_i)

```
while true do
    "non-critical section";
     $b_i := \text{true}$ ;
     $k := j$ ;
    while  $b_j \wedge k = j$  do skip end;
    "critical section";
     $b_i := \text{false}$ ;
end
```

Representing Shared Variables in CCS

- Not directly expressible in CCS (communication by handshaking)
- Idea: consider **variables as processes** that communicate with environment by processing read/write requests

Representing Shared Variables in CCS

- Not directly expressible in CCS (communication by handshaking)
- Idea: consider **variables as processes** that communicate with environment by processing read/write requests

Example 4.2 (Shared variables in Peterson's algorithm)

- Encoding of b_1 with two (process) **states** B_{1t} (value **tt**) and B_{1f} (value **ff**)
- **Read access** along ports $b1rt$ (in state B_{1t}) and $b1rf$ (in state B_{1f})
- **Write access** along ports $b1wt$ and $b1wf$ (in both states)

Representing Shared Variables in CCS

- Not directly expressible in CCS (communication by handshaking)
- Idea: consider **variables as processes** that communicate with environment by processing read/write requests

Example 4.2 (Shared variables in Peterson's algorithm)

- Encoding of b_1 with two (process) **states** B_{1t} (value tt) and B_{1f} (value ff)
- **Read access** along ports $b1rt$ (in state B_{1t}) and $b1rf$ (in state B_{1f})
- **Write access** along ports $b1wt$ and $b1wf$ (in both states)
- Possible behaviours:

$$\begin{aligned} B_{1f} &= \overline{b1rf}.B_{1f} + b1wf.B_{1f} + b1wt.B_{1t} \\ B_{1t} &= \overline{b1rt}.B_{1t} + b1wf.B_{1f} + b1wt.B_{1t} \end{aligned}$$

Representing Shared Variables in CCS

- Not directly expressible in CCS (communication by handshaking)
- Idea: consider **variables as processes** that communicate with environment by processing read/write requests

Example 4.2 (Shared variables in Peterson's algorithm)

- Encoding of b_1 with two (process) **states** B_{1t} (value tt) and B_{1f} (value ff)
- **Read access** along ports $b1rt$ (in state B_{1t}) and $b1rf$ (in state B_{1f})
- **Write access** along ports $b1wt$ and $b1wf$ (in both states)
- Possible behaviours:

$$\begin{aligned} B_{1f} &= \overline{b1rf}.B_{1f} + b1wf.B_{1f} + b1wt.B_{1t} \\ B_{1t} &= \overline{b1rt}.B_{1t} + b1wf.B_{1f} + b1wt.B_{1t} \end{aligned}$$

- Similarly for b_2 and k :

$$\begin{aligned} B_{2f} &= \overline{b2rf}.B_{2f} + b2wf.B_{2f} + b2wt.B_{2t} \\ B_{2t} &= \overline{b2rt}.B_{2t} + b2wf.B_{2f} + b2wt.B_{2t} \end{aligned}$$

$$\begin{aligned} K_1 &= \overline{kr1}.K_1 + kw1.K_1 + kw2.K_2 \\ K_2 &= \overline{kr2}.K_2 + kw1.K_1 + kw2.K_2 \end{aligned}$$

Modelling the Processes in CCS

Assumption: P_i cannot fail or terminate within critical section

Peterson's algorithm

```
while true do
  "non-critical section";
   $b_i := \text{true}$ ;
   $k := j$ ;
  while  $b_j \wedge k = j$  do skip end;
  "critical section";
   $b_i := \text{false}$ ;
end
```

Modelling the Processes in CCS

Assumption: P_i cannot fail or terminate within critical section

Peterson's algorithm

```
while true do
  "non-critical section";
   $b_i := \text{true};$ 
   $k := j;$ 
  while  $b_j \wedge k = j$  do skip end;
  "critical section";
   $b_i := \text{false};$ 
end
```

CCS representation

$$\begin{aligned} P_1 &= \overline{b1wt}.\overline{kw2}.P_{11} \\ P_{11} &= b2rf.P_{12} + \\ &\quad b2rt.(kr1.P_{12} + kr2.P_{11}) \\ P_{12} &= enter1.exit1.\overline{b1wf}.P_1 \\ P_2 &= \overline{b2wt}.\overline{kw1}.P_{21} \\ P_{21} &= b1rf.P_{22} + \\ &\quad b1rt.(kr1.P_{21} + kr2.P_{22}) \\ P_{22} &= enter2.exit2.\overline{b2wf}.P_2 \end{aligned}$$
$$\begin{aligned} Peterson &= (P_1 \parallel P_2 \parallel B_{1f} \parallel B_{2f} \parallel K_1) \setminus L \\ \text{for } L &= \{b1rf, b1rt, b1wf, b1wt, \\ &\quad b2rf, b2rt, b2wf, b2wt, \\ &\quad kr1, kr2, kw1, kw2\} \end{aligned}$$

Modelling the Processes in CCS

Assumption: P_i cannot fail or terminate within critical section

Peterson's algorithm

```
while true do
  "non-critical section";
   $b_i := \text{true};$ 
   $k := j;$ 
  while  $b_j \wedge k = j$  do skip end;
  "critical section";
   $b_i := \text{false};$ 
end
```

CCS representation

$$\begin{aligned} P_1 &= \overline{b1wt}. \overline{kw2}. P_{11} \\ P_{11} &= b2rf. P_{12} + \\ &\quad b2rt. (kr1. P_{12} + kr2. P_{11}) \\ P_{12} &= enter1. exit1. \overline{b1wf}. P_1 \\ P_2 &= \overline{b2wt}. \overline{kw1}. P_{21} \\ P_{21} &= b1rf. P_{22} + \\ &\quad b1rt. (kr1. P_{21} + kr2. P_{22}) \\ P_{22} &= enter2. exit2. \overline{b2wf}. P_2 \\ Peterson &= (P_1 \parallel P_2 \parallel B_{1f} \parallel B_{2f} \parallel K_1) \setminus L \\ \text{for } L &= \{b1rf, b1rt, b1wf, b1wt, \\ &\quad b2rf, b2rt, b2wf, b2wt, \\ &\quad kr1, kr2, kw1, kw2\} \end{aligned}$$

Modelling the Processes in CCS

Assumption: P_i cannot fail or terminate within critical section

Peterson's algorithm

```
while true do
  "non-critical section";
   $b_i := \text{true};$ 
   $k := j;$ 
  while  $b_j \wedge k = j$  do skip end;
  "critical section";
   $b_i := \text{false};$ 
end
```

CCS representation

$$\begin{aligned} P_1 &= \overline{b1wt}.\overline{kw2}.P_{11} \\ P_{11} &= b2rf.P_{12} + \\ &\quad b2rt.(kr1.P_{12} + kr2.P_{11}) \\ P_{12} &= enter1.exit1.\overline{b1wf}.P_1 \\ P_2 &= \overline{b2wt}.\overline{kw1}.P_{21} \\ P_{21} &= b1rf.P_{22} + \\ &\quad b1rt.(kr1.P_{21} + kr2.P_{22}) \\ P_{22} &= enter2.exit2.\overline{b2wf}.P_2 \end{aligned}$$
$$\begin{aligned} Peterson &= (P_1 \parallel P_2 \parallel B_{1f} \parallel B_{2f} \parallel K_1) \setminus L \\ \text{for } L &= \{b1rf, b1rt, b1wf, b1wt, \\ &\quad b2rf, b2rt, b2wf, b2wt, \\ &\quad kr1, kr2, kw1, kw2\} \end{aligned}$$

Modelling the Processes in CCS

Assumption: P_i cannot fail or terminate within critical section

Peterson's algorithm

```
while true do
  "non-critical section";
   $b_i := \text{true};$ 
   $k := j;$ 
  while  $b_j \wedge k = j$  do skip end;
  "critical section";
   $b_i := \text{false};$ 
end
```

CCS representation

$$\begin{aligned} P_1 &= \overline{b1wt}.\overline{kw2}.P_{11} \\ P_{11} &= b2rf.P_{12} + b2rt.(kr1.P_{12} + kr2.P_{11}) \\ P_{12} &= enter1.exit1.\overline{b1wf}.P_1 \\ P_2 &= \overline{b2wt}.\overline{kw1}.P_{21} \\ P_{21} &= b1rf.P_{22} + b1rt.(kr1.P_{21} + kr2.P_{22}) \\ P_{22} &= enter2.exit2.\overline{b2wf}.P_2 \\ Peterson &= (P_1 \parallel P_2 \parallel B_{1f} \parallel B_{2f} \parallel K_1) \setminus L \\ \text{for } L &= \{b1rf, b1rt, b1wf, b1wt, \\ &\quad b2rf, b2rt, b2wf, b2wt, \\ &\quad kr1, kr2, kw1, kw2\} \end{aligned}$$

Modelling the Processes in CCS

Assumption: P_i cannot fail or terminate within critical section

Peterson's algorithm

```
while true do
  "non-critical section";
   $b_i := \text{true};$ 
   $k := j;$ 
  while  $b_j \wedge k = j$  do skip end;
  "critical section";
   $b_i := \text{false};$ 
end
```

CCS representation

$$\begin{aligned} P_1 &= \overline{b1wt}.\overline{kw2}.P_{11} \\ P_{11} &= b2rf.P_{12} + \\ &\quad b2rt.(\textcolor{red}{kr1}.P_{12} + \textcolor{red}{kr2}.P_{11}) \\ P_{12} &= enter1.exit1.\overline{b1wf}.P_1 \\ P_2 &= \overline{b2wt}.\overline{kw1}.P_{21} \\ P_{21} &= b1rf.P_{22} + \\ &\quad b1rt.(\textcolor{red}{kr1}.P_{21} + \textcolor{red}{kr2}.P_{22}) \\ P_{22} &= enter2.exit2.\overline{b2wf}.P_2 \\ Peterson &= (P_1 \parallel P_2 \parallel B_{1f} \parallel B_{2f} \parallel K_1) \setminus L \\ \text{for } L &= \{b1rf, b1rt, b1wf, b1wt, \\ &\quad b2rf, b2rt, b2wf, b2wt, \\ &\quad kr1, kr2, kw1, kw2\} \end{aligned}$$

Modelling the Processes in CCS

Assumption: P_i cannot fail or terminate within critical section

Peterson's algorithm

```
while true do
  "non-critical section";
   $b_i := \text{true};$ 
   $k := j;$ 
  while  $b_j \wedge k = j$  do skip end;
  "critical section";
   $b_i := \text{false};$ 
end
```

CCS representation

$$\begin{aligned} P_1 &= \overline{b1wt}.\overline{kw2}.P_{11} \\ P_{11} &= b2rf.P_{12} + \\ &\quad b2rt.(kr1.P_{12} + kr2.P_{11}) \\ P_{12} &= \text{enter1.exit1}.\overline{b1wf}.P_1 \\ P_2 &= \overline{b2wt}.\overline{kw1}.P_{21} \\ P_{21} &= b1rf.P_{22} + \\ &\quad b1rt.(kr1.P_{21} + kr2.P_{22}) \\ P_{22} &= \text{enter2.exit2}.\overline{b2wf}.P_2 \\ \text{Peterson} &= (P_1 \parallel P_2 \parallel B_{1f} \parallel B_{2f} \parallel K_1) \setminus L \\ \text{for } L &= \{b1rf, b1rt, b1wf, b1wt, \\ &\quad b2rf, b2rt, b2wf, b2wt, \\ &\quad kr1, kr2, kw1, kw2\} \end{aligned}$$

Modelling the Processes in CCS

Assumption: P_i cannot fail or terminate within critical section

Peterson's algorithm

```
while true do
  "non-critical section";
   $b_i := \text{true};$ 
   $k := j;$ 
  while  $b_j \wedge k = j$  do skip end;
  "critical section";
   $b_i := \text{false};$ 
end
```

CCS representation

$$\begin{aligned} P_1 &= \overline{b1wt}.\overline{kw2}.P_{11} \\ P_{11} &= b2rf.P_{12} + \\ &\quad b2rt.(kr1.P_{12} + kr2.P_{11}) \\ P_{12} &= enter1.exit1.\overline{b1wf}.P_1 \\ P_2 &= \overline{b2wt}.\overline{kw1}.P_{21} \\ P_{21} &= b1rf.P_{22} + \\ &\quad b1rt.(kr1.P_{21} + kr2.P_{22}) \\ P_{22} &= enter2.exit2.\overline{b2wf}.P_2 \\ Peterson &= (P_1 \parallel P_2 \parallel B_{1f} \parallel B_{2f} \parallel K_1) \setminus L \\ \text{for } L &= \{b1rf, b1rt, b1wf, b1wt, \\ &\quad b2rf, b2rt, b2wf, b2wt, \\ &\quad kr1, kr2, kw1, kw2\} \end{aligned}$$

Outline of Lecture 4

Modelling Mutual Exclusion Algorithms

Evaluating the CCS Model

Verifying Properties by Model Checking

Verifying Mutual Exclusion by Bisimulation Checking

The End

Obtaining the LTS using CAAL I

CAAL

Project ▾

Edit

Explore

Verify

Games ▾

About

Syntax

✉

🔄

MutEx

Parse

CCS

TCCS

16 ▴ ▾

```
1  * Peterson's algorithm for mutual exclusion.
2  * See Chapter 7 of "Reactive Systems" for a full description.
3
4  B1f = 'b1rf.B1f + b1wf.B1f + b1wt.B1t;
5  B1t = 'b1rt.B1t + b1wf.B1f + b1wt.B1t;
6
7  B2f = 'b2rf.B2f + b2wf.B2f + b2wt.B2t;
8  B2t = 'b2rt.B2t + b2wf.B2f + b2wt.B2t;
9
10 K1 = 'kr1.K1 + kw1.K1 + kw2.K2;
11 K2 = 'kr2.K2 + kw1.K1 + kw2.K2;
12
13 P1 = 'b1wt.'kw2.P11;
14 P11 = b2rf.P12 + b2rt.(kr2.P11 + kr1.P12);
15 P12 = enter1.exit1.'b1wf.P1;
16
17 P2 = 'b2wt.'kw1.P21;
18 P21 = b1rf.P22 + b1rt.(kr1.P21 + kr2.P22);
19 P22 = enter2.exit2.'b2wf.P2;
20
21 set L = {b1rf, b2rf, b1rt, b2rt, b1wf, b2wf, b1wt, b2wt, kr1, kr2, kw1, kw2};
22 Peterson = (P1 | P2 | B1f | B2f | K1) \ L;
23
24 MutExCCS = enter1.exit1.MutExCCS + enter2.exit2.MutExCCS;
```

Obtaining the LTS using CAAL II

CAAL

Project ▾

Edit

Explore

Verify

Games ▾

About

Syntax

✉

🔄

Peterson ▾

Options ▾

Fullscreen

10

🔒

📄

Source	Action	Target
Peterson	tau	1
Peterson	tau	2

Outline of Lecture 4

Modelling Mutual Exclusion Algorithms

Evaluating the CCS Model

Verifying Properties by Model Checking

Verifying Mutual Exclusion by Bisimulation Checking

The End

The Mutual Exclusion Property

- **Done:** formal description of Peterson's algorithm
- **To do:** analysing its behaviour
- **Question:** what does “ensuring mutual exclusion” formally mean?

The Mutual Exclusion Property

- **Done:** formal description of Peterson's algorithm
- **To do:** analysing its behaviour
- **Question:** what does “ensuring mutual exclusion” formally mean?

Mutual exclusion

At **no point** in the execution of the algorithm, processes P_1 and P_2 will **both** be in their critical section at the same time.

Equivalently:

It is **always** the case that either P_1 or P_2 or both are **not** in their critical section.

Specifying Mutual Exclusion in HML

Mutual exclusion

It is **always** the case that either P_1 or P_2 or both are **not** in their critical section.

Specifying Mutual Exclusion in HML

Mutual exclusion

It is **always** the case that either P_1 or P_2 or both are **not** in their critical section.

Observations:

- Mutual exclusion is an **invariance property** (“always”)
- P_i is in its critical section iff action **exit i** is enabled

Specifying Mutual Exclusion in HML

Mutual exclusion

It is **always** the case that either P_1 or P_2 or both are **not** in their critical section.

Observations:

- Mutual exclusion is an **invariance property** (“always”)
- P_i is in its critical section iff action **exit i** is enabled

Mutual exclusion in HML

$$MutExHML := Inv(NotBoth)$$

$$Inv(F) \stackrel{max}{=} F \wedge [Act]Inv(F) \quad (\text{cf. Example 3.11})$$

$$NotBoth := [exit1]ff \vee [exit2]ff$$

Model Checking Mutual Exclusion

- Using CAAL Tool
- Supports **property specifications by recursive HML formulae**:

$\text{MutexHML max} = ([\text{exit1}]ff \text{ or } [\text{exit2}]ff) \text{ and } [-]\text{MutexHML};$

CAAL

Project ▾

Edit

Explore

Verify

Games ▾

About

Syntax

✉

🔄

Add Property

Stop

Verify All

Status	Time	Property	Verify	Edit	Delete	Options
✓	25 ms	Peterson \models MutexHML MutexHML max= ([exit1]ff or [exit2]ff) and [-]MutexHML	▶	✎	🗑	☰

Absence of Deadlocks

Absence of deadlocks

It is **always** the case that the system can progress, i.e., perform any action.

Absence of Deadlocks

Absence of deadlocks

It is **always** the case that the system can progress, i.e., perform any action.

Absence of deadlocks in HML

$$NoDeadlocks := Inv(CanProgress)$$
$$Inv(F) \stackrel{max}{=} F \wedge [Act]Inv(F)$$
$$CanProgress := \langle Act \rangle tt$$

Fairness

Fairness

Whenever a process requires access to the critical section, it will **eventually** be granted.

Fairness

Whenever a process requires access to the critical section, it will **eventually** be granted.

Observation: requires **nesting** of recursive formulae

- outer: “whenever” \Rightarrow invariant \Rightarrow greatest fixed point
- inner: “eventually” \Rightarrow to be ensured after finitely many steps \Rightarrow least fixed point

Fairness

Fairness

Whenever a process requires access to the critical section, it will **eventually** be granted.

Observation: requires **nesting** of recursive formulae

- outer: “whenever” \Rightarrow invariant \Rightarrow greatest fixed point
- inner: “eventually” \Rightarrow to be ensured after finitely many steps \Rightarrow least fixed point

Fairness in HML (only first process)

$$\begin{aligned} Fair_1 &:= Inv(EventuallyLeaves_1) \\ Inv(F) &\stackrel{max}{=} F \wedge [Act]Inv(F) \\ EventuallyLeaves_1 &:= Evt(Exits_1) \\ Evt(G) &\stackrel{min}{=} G \vee [Act]Evt(G) \\ Exits_1 &:= \langle exit1 \rangle tt \end{aligned}$$

Outline of Lecture 4

Modelling Mutual Exclusion Algorithms

Evaluating the CCS Model

Verifying Properties by Model Checking

Verifying Mutual Exclusion by Bisimulation Checking

The End

Specifying Mutual Exclusion in CCS

- **Goal:** express **desired behaviour** of algorithm as an “abstract” CCS process

Specifying Mutual Exclusion in CCS

- **Goal:** express **desired behaviour** of algorithm as an “abstract” CCS process
- Intuitively:
 - (1) Initially, either P_1 or P_2 can enter its critical section.
 - (2) Once this happened, the other process cannot enter the critical section before the first has exited it .

Specifying Mutual Exclusion in CCS

- **Goal:** express **desired behaviour** of algorithm as an “abstract” CCS process
- Intuitively:
 - (1) Initially, either P_1 or P_2 can enter its critical section.
 - (2) Once this happened, the other process cannot enter the critical section before the first has exited it .

Mutual exclusion in CCS

$$MutExCCS = enter1.exit1.MutExCCS + enter2.exit2.MutExCCS$$

Specifying Mutual Exclusion in CCS

- **Goal:** express **desired behaviour** of algorithm as an “abstract” CCS process
- Intuitively:
 - (1) Initially, either P_1 or P_2 can enter its critical section.
 - (2) Once this happened, the other process cannot enter the critical section before the first has exited it .

Mutual exclusion in CCS

$$MutExCCS = enter1.exit1.MutExCCS + enter2.exit2.MutExCCS$$

- **Weak bisimulation** does *not* hold as *Peterson* satisfies additional fairness constraints (prioritisation via variable k).
- However, *Peterson* and *MutExSpec* share the same **weak traces** (i.e., action sequences ignoring τ -transitions).

Specifying Mutual Exclusion in CCS

- **Goal:** express **desired behaviour** of algorithm as an “abstract” CCS process
- Intuitively:
 - (1) Initially, either P_1 or P_2 can enter its critical section.
 - (2) Once this happened, the other process cannot enter the critical section before the first has exited it .

Mutual exclusion in CCS

$$MutExCCS = enter1.exit1.MutExCCS + enter2.exit2.MutExCCS$$

- **Weak bisimulation** does *not* hold as *Peterson* satisfies additional fairness constraints (prioritisation via variable k).
- However, *Peterson* and *MutExSpec* share the same **weak traces** (i.e., action sequences ignoring τ -transitions).

CAAL	Project ▾	Edit	Explore	Verify	Games ▾	About	Syntax	✉	🔄
Add Property					Stop Verify All				
Status	Time	Property	Verify	Edit	Delete	Options			
✖	52 ms	Peterson \approx MutExCCS	▶	✎	🗑	☰			
✔	51 ms	Traces \Rightarrow (Peterson) = Traces \Rightarrow (MutExCCS)	▶	✎	🗑	☰			

Outline of Lecture 4

Modelling Mutual Exclusion Algorithms

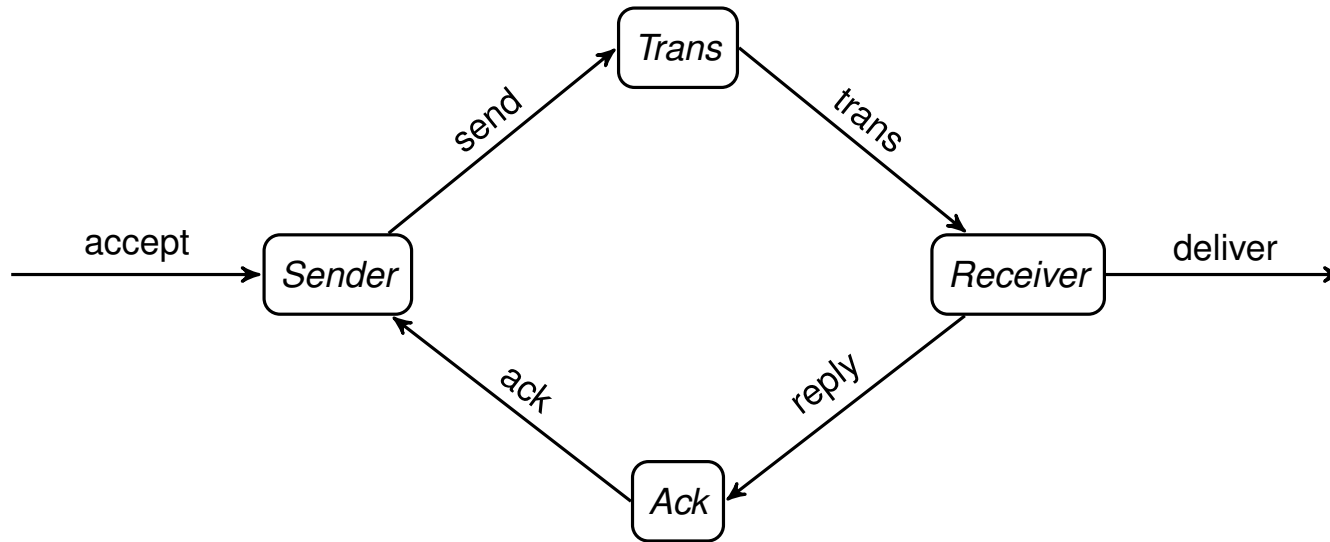
Evaluating the CCS Model

Verifying Properties by Model Checking

Verifying Mutual Exclusion by Bisimulation Checking

The End

Homework: The Alternating-Bit Protocol



To do (using CAAL):

- **Implementation** as CCS process definition
- Abstract **specification** in CCS and bisimilarity checking
- **Model checking** for deadlocks and livelocks
- Deliverable: short **experience report** with description of outcomes
- Deadline: **March 31, 2023**
- More details in <https://moves.rwth-aachen.de/wp-content/uploads/abp.pdf>