Modeling and Verification of Probabilistic Systems

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http://moves.rwth-aachen.de/teaching/ws-1516/movep15/

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Overview

1 Recall: continuous-time Markov chains

- 2 Transient distribution
- 3 Uniformization
- 4 Strong and weak bisimulation
- 5 Computing transient probabilities
- 6 Summary

Density of exponential distribution

The density of an *exponentially distributed* r.v. Y with rate $\lambda \in \mathbb{R}_{>0}$ is:

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 for $x > 0$ and $f_Y(x) = 0$ otherwise

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• Expectation
$$E[Y] = \int_0^\infty x \cdot \lambda \cdot e^{-\lambda \cdot x} dx = \frac{1}{\lambda}$$

• Variance
$$Var[Y] = \int_0^\infty (x - E[X])^2 \lambda \cdot e^{-\lambda \cdot x} dx = \frac{1}{\lambda^2}$$

Continuous-time Markov chain

Continuous-time Markov chain

A CTMC is a tuple $(S, \mathbf{P}, \mathbf{r}, \iota_{\text{init}}, AP, L)$ where

- $(S, \mathbf{P}, \iota_{init}, AP, L)$ is a DTMC, and
- $r: S \to \mathbb{R}_{>0}$, the exit-rate function

Let $\mathbf{R}(s, s') = \mathbf{P}(s, s') \cdot r(s)$ be the transition rate of transition (s, s')

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- residence time in state s is exponentially distributed with rate r(s).
- phrased alternatively, the average residence time of state s is $\frac{1}{r(s)}$.

Enabledness

The probability that transition $s \to s'$ is *enabled* in [0, t] is $1 - e^{-\mathbf{R}(s,s') \cdot t}$.

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Residence time distribution

The probability to *take some* outgoing transition from s in [0, t] is:

$$\int_0^t r(s) \cdot e^{-r(s) \cdot x} dx = 1 - e^{-r(s) \cdot t}$$

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$$\underline{p}'(t) = \underline{p}(t) \cdot (\mathbf{R} - \mathbf{r})$$
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where \mathbf{r} is the diagonal matrix of vector \underline{r} .

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On the blackboard.

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But: numerical instability due to fill-in of $(\mathbf{R}-\mathbf{r})^i$ in presence of positive and negative entries in the matrix $\mathbf{R}-\mathbf{r}$.

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It follows that $\overline{\mathbf{P}}$ is a stochastic matrix and unif(r, C) is a CTMC.

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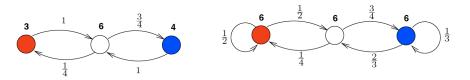
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CTMC C and its uniformized counterpart unif(6, C)

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That is, slow down state s whenever r(s) < r.

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Strong and weak bisimulation

Strong bisimulation on DTMCs

Probabilistic bisimulation

[Larsen & Skou, 1989]

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Let $\mathcal{D} = (S, \mathbf{P}, \iota_{\text{init}}, AP, L)$ be a DTMC and $R \subseteq S \times S$ an equivalence.

Probabilistic bisimulation

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For states in R, the conditional probability of moving by a single transition to another equivalence class is equal. In addition, either all states in an equivalence class C almost surely stay there, or have an option to escape from C.

Joost-Pieter Katoen

Modeling and Verification of Probabilistic Systems

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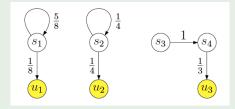
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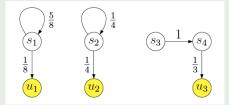
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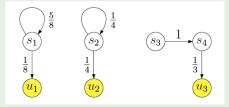
Strong and weak bisimulation

Weak bisimulation on DTMC: example

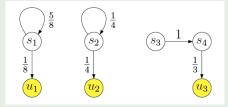




The equivalence relation R with $S/R = \{ \{s_1, s_2, s_3, s_4\}, \{u_1, u_2, u_3\} \}$ is a weak bisimulation.

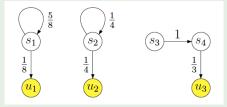


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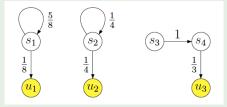
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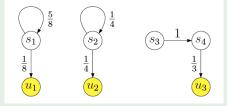
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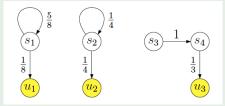
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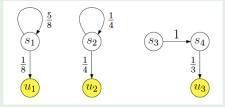
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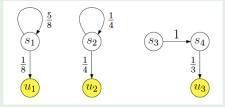
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Note that $\mathbf{P}(s_3, [s_3]_R) = 1$. Since s_3 can reach a state outside $[s_3]$ as s_1, s_2 and s_4 , it follows that $s_1 \approx_p s_2 \approx_p s_3 \approx_p s_4$.

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Consider the following DTMC:

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Let $C = (S, \mathbf{P}, r, \iota_{init}, AP, L)$ be a CTMC and $R \subseteq S \times S$ an equivalence. Then: R is a *weak probabilistic bisimulation* on S if for any $(s, t) \in R$: 1. L(s) = L(t), and 2. $\mathbf{R}(s, C) = \mathbf{R}(t, C)$ for all $C \in S/R$ with $C \neq [s]_R = [t]_R$

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Weak bisimulation on CTMCs

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Weak probabilistic bisimilarity

Let C be a CTMC and s, t states in C. Then: s is *weak probabilistically bisimilar* to t, denoted $s \approx_m t$, if there exists a weak probabilistic bisimulation R with $(s, t) \in R$.

Let C be a CTMC and R an equivalence relation on S with $(s, t) \in R$, $P(s, [s]_R) < 1$ and $P(t, [t]_R) < 1$.

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$$C \in S/R$$
, $C \neq [s]_R = [t]_R$:

$$\frac{\mathsf{P}(s,C)}{1-\mathsf{P}(s,[s]_R)} = \frac{\mathsf{P}(t,C)}{1-\mathsf{P}(t,[t]_R)} \quad \text{and} \quad \mathsf{R}(s,S\setminus[s]_R) = \mathsf{R}(t,S\setminus[t]_R)$$

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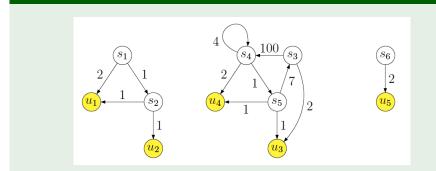
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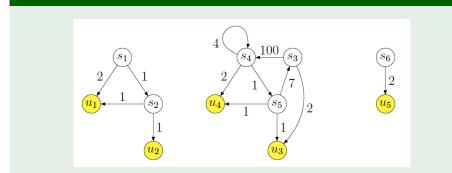
Proof:

Left as an exercise.

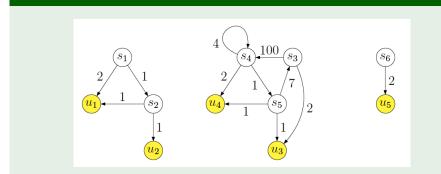
Strong and weak bisimulation

Weak bisimulation on CTMCs: example

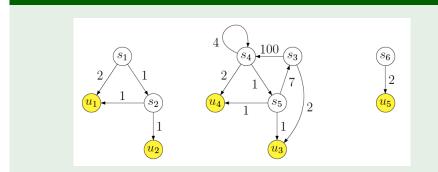




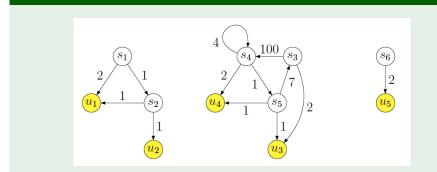
Equivalence relation R with $S/R = \{ \{s_1, s_2, s_3, s_4, s_5, s_6\}, \{u_1, u_2, u_3, u_4, u_5\} \}$ is a weak bisimulation on the CTMC depicted above.



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Strong and weak bisimulation in uniform CTMCs

For all uniform CTMCs C and states s, u in C, we have:

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 iff $s \approx_m u$ iff $s \sim_p u$.

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Preservation of transient probabilities

For all CTMCs C with states s, u in C and $t \in \mathbb{R}_{\geq 0}$, we have:

 $s \approx_m u$ implies $\underline{p}^s(t) = \underline{p}^u(t)$

where $\underline{p}^{s}(0) = \mathbf{1}_{s}$ and $\underline{p}^{u}(0) = \mathbf{1}_{u}$ where $\mathbf{1}_{s}$ is the characteristic function for state s, i.e., $\mathbf{1}_{s}(s') = 1$ iff s = s'.

Overview

1 Recall: continuous-time Markov chains

- 2 Transient distribution
- 3 Uniformization
- 4 Strong and weak bisimulation
- 6 Computing transient probabilities

Summary

The transient probability vector $\underline{p}(t) = (p_{s_1}(t), \dots, p_{s_k}(t))$ satisfies:

$$\underline{p}'(t) = \underline{p}(t) \cdot (\mathbf{R} - \mathbf{r})$$
 given $\underline{p}(0)$.

Standard knowledge yields: $p(t) = p(0) \cdot e^{(\mathbf{R}-\mathbf{r}) \cdot t}$.

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Computing a matrix exponential

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As $\overline{\mathbf{P}}$ is a stochastic matrix, computing the matrix exponential $\overline{\mathbf{P}}'$ is numerically stable.

Poisson distribution

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where r is the mean of the Poisson distribution.

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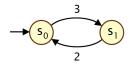
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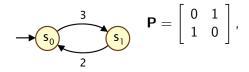
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Remark

The Poisson distribution can be derived as a limiting case to the binomial distribution as the number of trials goes to infinity and the expected number of successes remains fixed.





$$\mathbf{P} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \underline{r} = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$$

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Let initial distribution $\underline{p}(0) = (1, 0)$, and time bound t=1.

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<u>p</u>(1)

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$$= (1,0) \cdot e^{-3} \frac{1}{0!} \cdot \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + (1,0) \cdot e^{-3} \frac{3}{1!} \cdot \begin{bmatrix} 0 & 1 \\ \frac{2}{3} & \frac{1}{3} \end{bmatrix}$$

$$+ (1,0) \cdot e^{-3} \frac{9}{2!} \cdot \begin{bmatrix} 0 & 1 \\ \frac{2}{3} & \frac{1}{3} \end{bmatrix}^{2} + \dots$$

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$$= (1,0) \cdot e^{-3} \frac{1}{0!} \cdot \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + (1,0) \cdot e^{-3} \frac{3}{1!} \cdot \begin{bmatrix} 0 & 1 \\ \frac{2}{3} & \frac{1}{3} \end{bmatrix}$$

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$$\approx (0.404043, 0.595957)$$

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Summation can be truncated *a priori* for a given error bound $\varepsilon > 0$.

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$$\sum_{i=0}^{\infty} e^{-rt} \frac{(rt)^i}{i!} = 1 \text{ due to the fact that } e^{-rt} \frac{(rt)^i}{i!} \text{ is a (Poisson) distribution}$$

Overview

Recall: continuous-time Markov chains

- 2 Transient distribution
- 3 Uniformization
- 4 Strong and weak bisimulation
- 5 Computing transient probabilities



Main points

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- Transient distribution are obtained by solving a system of linear differential equations.
- These equations can be solved conveniently on the uniformized CTMC.