

# Static Program Analysis

## Lecture 9: Dataflow Analysis VIII

### (Conditional Interval Analysis & Java Virtual Machine)

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Winter Semester 2014/15

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- **Solution:** introduce transfer functions for branches
- **First approach:** attach (negated) conditions as labels to control flow edges
  - advantage: no language modification required
  - disadvantage: entails extension of DFA framework
  - will not further be considered here
- **Second approach:** encode conditions as assertions (statements)
  - advantage: DFA framework can be reused
  - disadvantage: entails extension of WHILE language
  - the way we will follow

## Definition (Labelled WHILE programs with assertions)

The syntax of labelled WHILE programs with assertions is defined by the following context-free grammar:

$$\begin{aligned} a &::= z \mid x \mid a_1 + a_2 \mid a_1 - a_2 \mid a_1 * a_2 \in AExp \\ b &::= t \mid a_1 = a_2 \mid a_1 > a_2 \mid \neg b \mid b_1 \wedge b_2 \mid b_1 \vee b_2 \in BExp \\ c &::= [\text{skip}]' \mid [x := a]' \mid c_1 ; c_2 \mid \\ &\quad \text{if } [b]' \text{ then } c_1 \text{ else } c_2 \mid \text{while } [b]' \text{ do } c \mid [\text{assert } b]' \in Cmd \end{aligned}$$

## To be done:

- Definition of **transfer functions** for **assert** blocks  
(depending on analysis problem)
- Idea: assertions as **filters** that let only “valid” information pass

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# Interval Analysis with Assertions I

So far:

- The domain  $(\text{Int}, \subseteq)$  of intervals over  $\mathbb{Z}$  is defined by

$$\text{Int} := \{[z_1, z_2] \mid z_1 \in \mathbb{Z} \cup \{-\infty\}, z_2 \in \mathbb{Z} \cup \{+\infty\}\}, z_1 \leq z_2\} \cup \{\emptyset\}$$

where

- $-\infty \leq z, z \leq +\infty$ , and  $-\infty \leq +\infty$  (for all  $z \in \mathbb{Z}$ )
- $\emptyset \subseteq J$  (for all  $J \in \text{Int}$ )
- $[y_1, y_2] \subseteq [z_1, z_2]$  iff  $y_1 \geq z_1$  and  $y_2 \leq z_2$

- Transfer functions  $\{\varphi_I \mid I \in \text{Lab}\}$  are defined by

$$\varphi_I(\delta) := \begin{cases} \delta & \text{if } B^I = \text{skip or } B^I \in BExp \\ \delta[x \mapsto \text{val}_\delta(a)] & \text{if } B^I = (x := a) \end{cases}$$

where

$$\begin{array}{ll} \text{val}_\delta(x) := \delta(x) & \text{val}_\delta(a_1 + a_2) := \text{val}_\delta(a_1) \oplus \text{val}_\delta(a_2) \\ \text{val}_\delta(z) := [z, z] & \text{val}_\delta(a_1 - a_2) := \text{val}_\delta(a_1) \ominus \text{val}_\delta(a_2) \\ & \text{val}_\delta(a_1 * a_2) := \text{val}_\delta(a_1) \odot \text{val}_\delta(a_2) \end{array}$$

with

$$\emptyset \oplus J := J \oplus \emptyset := \emptyset \ominus J := \dots := \emptyset$$

$$[y_1, y_2] \oplus [z_1, z_2] := [y_1 + z_1, y_2 + z_2]$$

$$[y_1, y_2] \ominus [z_1, z_2] := [y_1 - z_2, y_2 - z_1]$$

$$[y_1, y_2] \odot [z_1, z_2] := [\prod\{y_1 z_1, y_1 z_2, y_2 z_1, y_2 z_2\}, \bigcup\{y_1 z_1, y_1 z_2, y_2 z_1, y_2 z_2\}]$$

Additionally for  $B^I = (\text{assert } b)$ ,  $\delta : \text{Var}_c \rightarrow \text{Int}$  and  $x \in \text{Var}_c$ :

$$\varphi_I(\delta)(x) := \begin{cases} \emptyset & \text{if } Z = \emptyset \\ \left[ \prod_{Z \cup \{-\infty\}} Z, \bigcup_{Z \cup \{+\infty\}} Z \right] & \text{otherwise} \end{cases}$$

where

- $Z := \{\sigma(x) \mid \sigma \in \Sigma_\delta, \text{val}_\sigma(b) = \text{true}\}$
- $\Sigma_\delta := \{\sigma : \text{Var}_c \rightarrow \mathbb{Z} \mid \forall y \in \text{Var}_c : \sigma(y) \in \delta(y)\}$   
(and thus  $\Sigma_\delta = \emptyset$  iff  $\delta(y) = \emptyset$  for some  $y \in \text{Var}_c$ )
- $\text{val}_\sigma : BExp \rightarrow \mathbb{B}$  as before

## Example 9.1

$$\text{Var}_c = \{x, y\}, \delta = (\underbrace{[-\infty, 2]}_x, \underbrace{[0, +\infty]}_y)$$

$$\implies \varphi_{\text{assert } x > 0}(\delta) = ([1, 2], [0, +\infty])$$

$$\varphi_{\text{assert } x = y}(\delta) = ([0, 2], [0, 2])$$

$$\varphi_{\text{assert } x > y}(\delta) = ([1, 2], [0, 1])$$

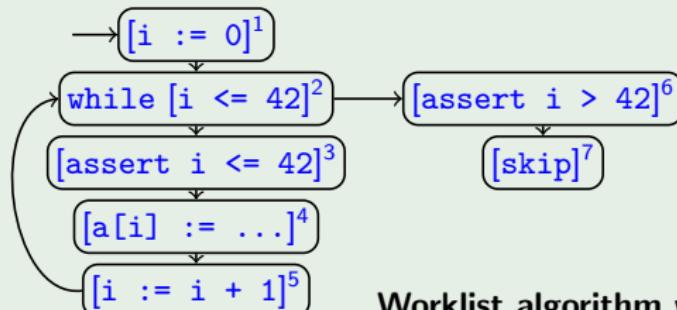
$$\varphi_{\text{assert } x < y}(\delta) = ((-\infty, 2], [0, +\infty])$$

## Remarks:

- Again for  $B^I = (\text{assert } b)$  and  $\delta : \text{Var}_c \rightarrow \text{Int}$ ,  $\varphi_I(\delta) \sqsubseteq \delta$  and hence  $\Sigma_{\varphi_I(\delta)} \subseteq \Sigma_\delta$  ("filter")
- Again if  $\text{AI}_I(x) = \emptyset$  for some  $I \in \text{Lab}_c$  and  $x \in \text{Var}_c$ , then  $I$  is **unreachable** (and  $\text{AI}_I(y) = \emptyset$  for all  $y \in \text{Var}_c$ )

# Interval Analysis with Assertions IV

Example 9.2 (Interval analysis for array index; cf. Example 7.6)



$$\varphi_1(J) = [0, 0]$$

$$\varphi_2(J) = J$$

$$\varphi_3(J) = J \cap [-\infty, 42]$$

$$\varphi_4(J) = J$$

$$\varphi_5(\emptyset) = \emptyset$$

$$\varphi_5([i_1, i_2]) = [i_1 + 1, i_2 + 1]$$

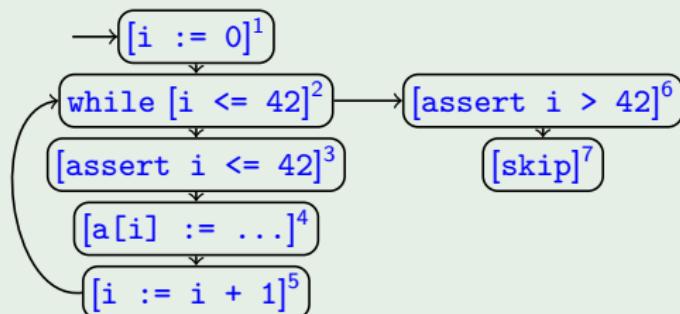
$$\varphi_6(J) = J \cap [43, +\infty]$$

Worklist algorithm with widening:

$W$	$AI_1$	$AI_2$	$AI_3$	$AI_4$	$AI_5$	$AI_6$	$AI_7$
12, 23, 34, 45, 52, 26, 67	$[-\infty, +\infty]$	$\emptyset$	$\emptyset$	$\emptyset$	$\emptyset$	$\emptyset$	$\emptyset$
23, 34, 45, 52, 26, 67	$[-\infty, +\infty]$	$[0, 0]$	$\emptyset$	$\emptyset$	$\emptyset$	$\emptyset$	$\emptyset$
34, 45, 52, 26, 67	$[-\infty, +\infty]$	$[0, 0]$	$[0, 0]$	$\emptyset$	$\emptyset$	$\emptyset$	$\emptyset$
45, 52, 26, 67	$[-\infty, +\infty]$	$[0, 0]$	$[0, 0]$	$[0, 0]$	$\emptyset$	$\emptyset$	$\emptyset$
52, 26, 67	$[-\infty, +\infty]$	$[0, 0]$	$[0, 0]$	$[0, 0]$	$[0, 0]$	$\emptyset$	$\emptyset$
23, 26, 67	$[-\infty, +\infty]$	$[0, +\infty]$	$[0, 0]$	$[0, 0]$	$[0, 0]$	$\emptyset$	$\emptyset$
34, 26, 67	$[-\infty, +\infty]$	$[0, +\infty]$	$[0, +\infty]$	$[0, 0]$	$[0, 0]$	$\emptyset$	$\emptyset$
45, 26, 67	$[-\infty, +\infty]$	$[0, +\infty]$	$[0, +\infty]$	$[0, +\infty]$	$[0, 0]$	$\emptyset$	$\emptyset$
52, 26, 67	$[-\infty, +\infty]$	$[0, +\infty]$	$[0, +\infty]$	$[0, +\infty]$	$[0, +\infty]$	$\emptyset$	$\emptyset$
26, 67	$[-\infty, +\infty]$	$[0, +\infty]$	$[0, +\infty]$	$[0, +\infty]$	$[0, +\infty]$	$\emptyset$	$\emptyset$
67	$[-\infty, +\infty]$	$[0, +\infty]$	$\emptyset$				
$\varepsilon$	$[-\infty, +\infty]$	$[0, +\infty]$	$[43, +\infty]$				

# Interval Analysis with Assertions V

## Example 9.2 (Interval analysis for array index; continued)



$$\begin{aligned}\varphi_1(J) &= [0, 0] \\ \varphi_2(J) &= J \\ \varphi_3(J) &= J \cap [-\infty, 42] \\ \varphi_4(J) &= J \\ \varphi_5(\emptyset) &= \emptyset \\ \varphi_5([i_1, i_2]) &= [i_1 + 1, i_2 + 1] \\ \varphi_6(J) &= J \cap [43, +\infty]\end{aligned}$$

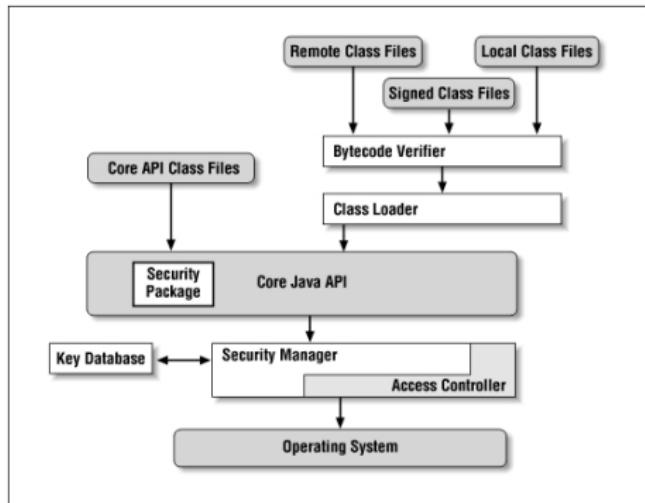
Narrowing:

	AI <sub>1</sub>	AI <sub>2</sub>	AI <sub>3</sub>	AI <sub>4</sub>	AI <sub>5</sub>	AI <sub>6</sub>	AI <sub>7</sub>
$\text{fix}^{\nabla}(\Phi_S)$	$[-\infty, +\infty]$	$[0, +\infty]$	$[0, +\infty]$	$[0, +\infty]$	$[0, +\infty]$	$[0, +\infty]$	$[43, +\infty]$
$\Phi_S(\text{fix}^{\nabla}(\Phi_S))$	$[-\infty, +\infty]$	$[0, +\infty]$	$[0, +\infty]$	$[0, 42]$	$[0, +\infty]$	$[0, +\infty]$	$[43, +\infty]$
$\Phi_S^2(\text{fix}^{\nabla}(\Phi_S))$	$[-\infty, +\infty]$	$[0, +\infty]$	$[0, +\infty]$	$[0, 42]$	$[0, 42]$	$[0, +\infty]$	$[43, +\infty]$
$\Phi_S^3(\text{fix}^{\nabla}(\Phi_S))$	$[-\infty, +\infty]$	$[0, 43]$	$[0, +\infty]$	$[0, 42]$	$[0, 42]$	$[0, +\infty]$	$[43, +\infty]$
$\Phi_S^4(\text{fix}^{\nabla}(\Phi_S))$	$[-\infty, +\infty]$	$[0, 43]$	$[0, 43]$	$[0, 42]$	$[0, 42]$	$[0, 43]$	$[43, +\infty]$
$\Phi_S^5(\text{fix}^{\nabla}(\Phi_S))$	$[-\infty, +\infty]$	$[0, 43]$	$[0, 43]$	$[0, 42]$	$[0, 42]$	$[0, 43]$	$[43, 43]$
$\Phi_S^6(\text{fix}^{\nabla}(\Phi_S))$	$[-\infty, +\infty]$	$[0, 43]$	$[0, 43]$	$[0, 42]$	$[0, 42]$	$[0, 43]$	$[43, 43]$

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- **Intermediate language** between high-level language and machine code
- Execution on **Java Virtual Machine (JVM)**
- **Advantages:**
  - architecture independency (especially for web applications)
  - faster than pure (i.e., source code) interpretation
- **Problem: security issues**
  - destruction of data
  - modification of data
  - disclosure of personal information
  - modification of other programs

- **Insulation layer** providing indirect access to system resources
- Hardware access via **API classes and methods**
- **Bytecode verification** upon uploading
  - well-typedness
  - proper object referencing
  - proper control flow



- Conventional stack-based abstract machine
- Supports object-oriented features: classes, methods, etc.
- Stack for intermediate results of expression evaluations
- Registers for source-level local variables and method parameters
- Both part of method activation record  
(and thus preserved across method calls)
- Method entry point specifies required number of registers ( $m_r$ ) and stack slots ( $m_s$ ; for memory allocation)
- (Most) instructions are typed

# Example: Factorial Function

## Example 9.3 (Factorial function)

Java source code:

```
static int factorial(int n)
{ int res;
  for (res = 1; n > 0; n--) res = res * n;
  return res; }
```

Corresponding JVM bytecode:

```
method static int factorial(int), 2 registers, 2 stack slots
  1: istore 0    // store n in register 0
  2: iconst_1    // push constant 1
  3: istore 1    // store res in register 1
  4: iload 0     // push n
  5: ifle 12     // if <= 0, go to end
  6: iload 1     // push res
  7: iload 0     // push n
  8: imul        // res * n on top of stack
  9: istore 1    // store in res
 10: iinc 0, -1 // decrement n
 11: goto 4     // go to loop header
 12: iload 1     // push res
 13: ireturn     // return res to caller
```

# JVM Instruction Set (excerpt)

`iload n:` push integer from register *n*

`istore n:` pop integer into register *n*

`iconst_<Z>:` push integer *Z*

`aconst_null:` push null reference

`iadd:` add two topmost integers on stack and push sum

`getfield C f τ:` pops reference to object (of class *C*) and pushes value of field *f* (of type *τ*)

`putfield C f τ:` pops value *v* (of type *τ*) and reference to object *o* (of class *C*) and assigns *v* to field *f* of *o*

`new C:` creates new object (of class *C*) and pushes reference

`invoke C M τ₀(τ₁, …, τₙ):` pops values *v₁, …, vₙ* (of type *τ₁, …, τₙ*) and reference to object (of class *C*), calls method *M* with parameters *v₁, …, vₙ*, and pushes return value (of type *τ₀*)

`if_icmpneq l:` pop two topmost integers from stack and jump to line *l* if equal

`ireturn:` return to caller with integer result on top of stack

( $\approx$  200 instructions in total)

## Example 9.4 (Malicious bytecode)

```
1:  iconst_5  
2:  iconst_1  
3:  putfield A f int
```

interprets second stack entry (5) as reference to object of class `A` and assigns first stack entry (1) to field `f` of this object

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# Correctness of Bytecode

**Conditions** to ensure proper operation:

Type correctness: arguments of instructions always of expected type

No stack over-/underflow: never push to full stack or pop from empty stack

Code containment: PC must always point into the method code

Register initialization: load from non-parameter register only after store

Object initialization: constructor must be invoked before using class instance

Access control: operations must respect visibility modifiers  
(private/protected/public)

**Options:**

- dynamic checking at execution time ("defensive JVM approach")
  - expensive, slows down execution
- static checking at loading time (here)
  - verified code executable at full speed without extra dynamic checks

**Summary:** dataflow analysis applied to type-level abstract interpretation of JVM

- ① Association of type information with register and stack contents
  - set of types forms a complete lattice
- ② Simulation of execution of instructions at type level
- ③ Use dataflow analysis to cover all concrete executions
- ④ Modularity: analysis proceeds method per method

(see X. Leroy: *Java Bytecode Verification: Algorithms and Formalizations*, Journal of Automated Reasoning 30(3-4), 2003, 235–269)

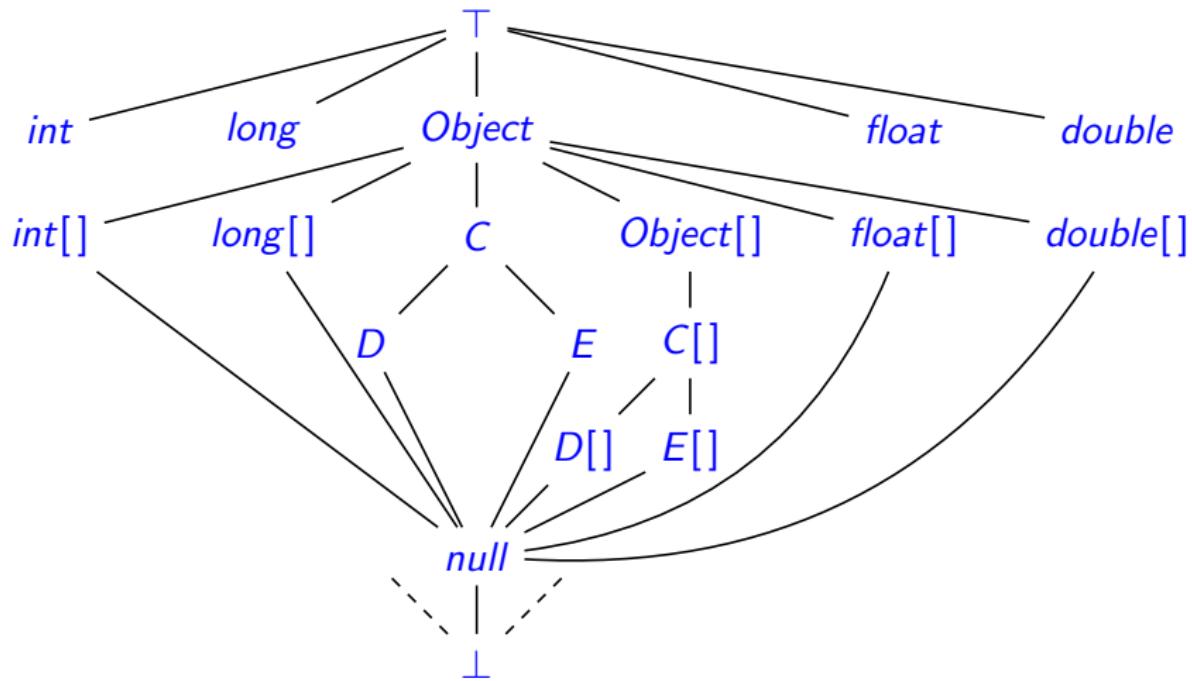
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The set of types,  $Typ$ , is composed of

- Primitive types:
  - $int$  (covering  $boolean$ ,  $byte$ ,  $char$ ,  $short$ )
  - $long$
  - $float$
  - $double$
- Object reference types:  $C$  for every class name  $C$
- Array types:  $\tau[]$  for every primitive or object reference type  $\tau$
- Method types:  $\tau_0(\tau_1, \dots, \tau_n)$  for  $n \in \mathbb{N}$ ,  $\tau_i \in Typ$
- Special types:
  - $null$  (null reference)
  - $Object$  (any object)
  - $\top$  (contents of uninitialized registers, i.e., any value)
  - $\perp$  (absence of any value)

# The Subtyping Relation (excerpt)

( $C, D, E$  user-defined classes;  $D, E$  extending  $C$ )



Notation:  $\tau_1 \sqsubseteq_t \tau_2$

- **Idea:** execute JVM instructions on **types** (rather than concrete values)

- stack type  $S \in \text{Typ}^{\leq m_s}$  (top to the left)
- register type  $R : \{0, \dots, m_r - 1\} \rightarrow \text{Typ}$

- Represented as **transition relation**

$$i : (S, R) \rightarrow (S', R')$$

where

- $i$ : current instruction
- $(S, R)$ : stack/register type before execution
- $(S', R')$ : stack/register type after execution
- **Errors** (type mismatch, stack over-/underflow, ...) denoted by absence of transition

# The Type-Level Abstract Interpreter II

Some transition rules:

<code>iconst_z :</code>	$(S, R) \rightarrow (\text{int}.S, R)$	if $ S  < m_s$
<code>aconst_null :</code>	$(S, R) \rightarrow (\text{null}.S, R)$	if $ S  < m_s$
<code>iadd :</code>	$(\text{int}.\text{int}.S, R) \rightarrow (\text{int}.S, R)$	
<code>if_icmpneq / :</code>	$(\text{int}.\text{int}.S, R) \rightarrow (S, R)$	
<code>iload n :</code>	$(S, R) \rightarrow (\text{int}.S, R)$	
		if $0 \leq n < m_r, R(n) = \text{int},  S  < m_s$
<code>aload n :</code>	$(S, R) \rightarrow (R(n).S, R)$	
		if $0 \leq n < m_r, R(n) \sqsubseteq_t \text{Object},  S  < m_s$
<code>istore n :</code>	$(\text{int}.S, R) \rightarrow (S, R[n \mapsto \text{int}])$	if $0 \leq n < m_r$
<code>astore n :</code>	$(\tau.S, R) \rightarrow (S, R[n \mapsto \tau])$	
		if $0 \leq n < m_r, \tau \sqsubseteq_t \text{Object}$
<code>getfield C f τ :</code>	$(D.S, R) \rightarrow (\tau.S, R)$	if $D \sqsubseteq_t C$
<code>putfield C f τ :</code>	$(\tau'.D.S, R) \rightarrow (S, R)$	
		if $\tau' \sqsubseteq_t \tau, D \sqsubseteq_t C$
<code>invoke C M σ :</code>	$(\tau'_n \dots \tau'_1.\tau'.S, R) \rightarrow (\tau_0.S, R)$	
		if $\sigma = \tau_0(\tau_1, \dots, \tau_n), \tau'_i \sqsubseteq_t \tau_i$ for $1 \leq i \leq n, \tau' \sqsubseteq_t C$

## Lemma 9.5

- ①  $(\text{Typ}, \sqsubseteq_t)$  is a *complete lattice satisfying ACC*.
- ② (*Determinacy*) The transitions of the abstract interpreter define a partial function: If  $i : (S, R) \rightarrow (S_1, R_1)$  and  $i : (S, R) \rightarrow (S_2, R_2)$ , then  $S_1 = S_2$  and  $R_1 = R_2$ .
- ③ (*Soundness*) If  $i : (S, R) \rightarrow (S', R')$ , then for all concrete states  $(s, r)$  matching  $(S, R)$ , the defensive JVM will not stop with a run-time type exception when applying  $i$  to  $(s, r)$  (but rather change to some  $(s', r')$  matching  $(S', R')$ ).

## Proof.

see X. Leroy: *Java Bytecode Verification: Algorithms and Formalizations*

