

Introduction

## Modelling parallel systems

Transition systems

Modeling hard- and software systems

Parallelism and communication



Linear Time Properties

Regular Properties

Linear Temporal Logic

Computation-Tree Logic

Equivalences and Abstraction



representation of data-dependent parallel systems with

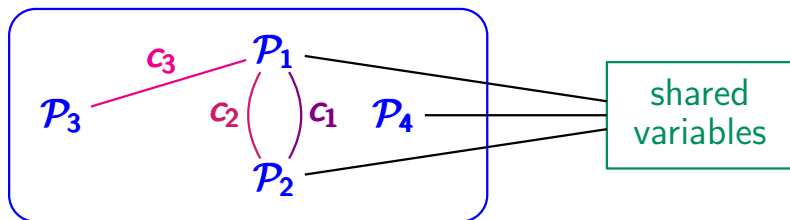
- communication over **shared variables**
- **synchronous** message passing
- **asynchronous** message passing

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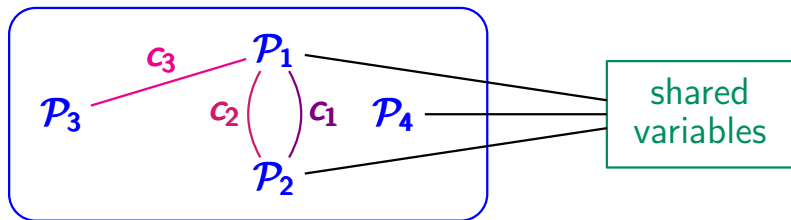
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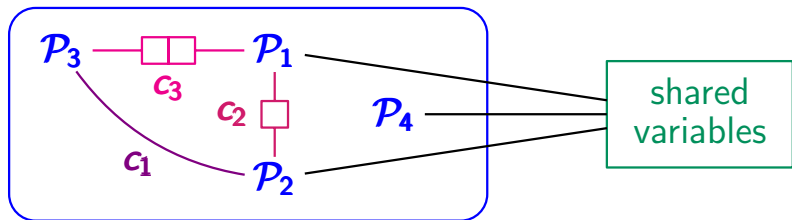
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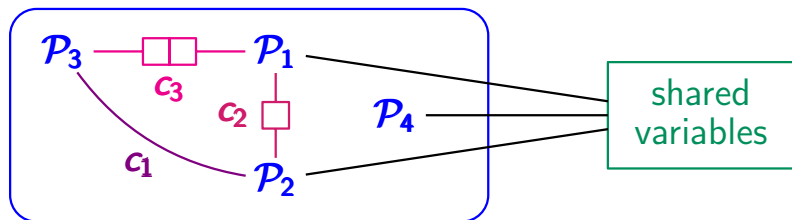


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↑  
**capacity**  $\hat{=}$  number of buffer cells

representation of data-dependent parallel systems with

- communication over **shared variables**
- **synchronous** message passing ← **capacity 0**
- **asynchronous** message passing ← **capacity  $\geq 1$**



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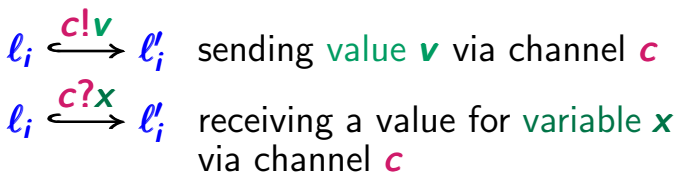
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- and **communication actions**



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s.t.  $\xi(c)$  is a word over  $Dom(c)$  of length  $\leq cap(c)$



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PC2.2-25

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# Effect of communication actions in CS

PC2.2-26

*asynchronous message passing* via channels of capacity  $\geq 1$

|                    | enabled if ... | effect |
|--------------------|----------------|--------|
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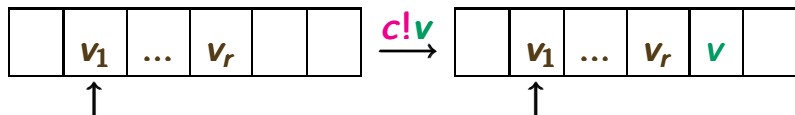


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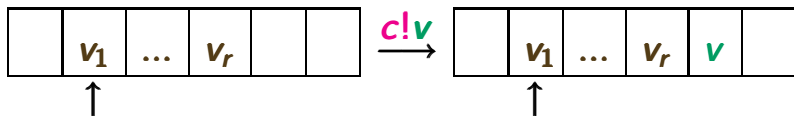


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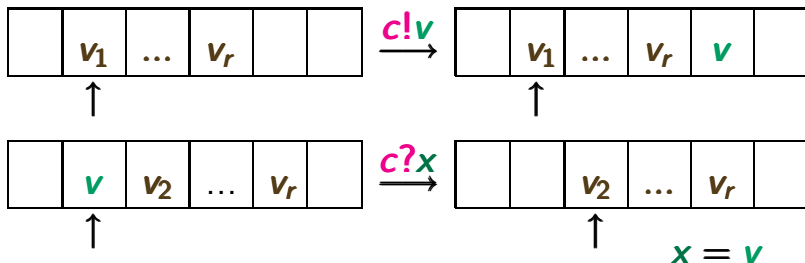


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*synchronous message passing* via channels of capacity 0

- $c!v$  and  $c?x$  are executed at the same time
- effect  $x := v$

channel system over (*Var*, *Chan*)

$$\mathcal{C} = [\mathcal{P}_1 | \dots | \mathcal{P}_n]$$



transition system  $\mathcal{T}_{\mathcal{C}}$

channel system over ( $\mathit{Var}$ ,  $\mathit{Chan}$ )  
 $\mathcal{C} = [\mathcal{P}_1 \mid \dots \mid \mathcal{P}_n]$



transition system  $\mathcal{T}_{\mathcal{C}}$

states of  $\mathcal{T}_{\mathcal{C}}$  have the form

$\langle l_1, \dots, l_n, \eta, \xi \rangle$

locations of  $\mathcal{P}_1, \dots, \mathcal{P}_n$       variable valuation      channel evaluation

states  $\langle \ell_1, \dots, \ell_n, \eta, \xi \rangle$  where

$\ell_i$  location of program graph  $\mathcal{P}_i$ ,

$\eta \in \mathit{Eval}(\mathit{Var})$  variable evaluation

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variable evaluation:

$$\eta : \mathit{Var} \longrightarrow \bigcup_{x \in \mathit{Var}} \mathit{Dom}(x) \quad \text{with } \eta(x) \in \mathit{Dom}(x)$$

channel evaluation:

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only channels  $c$  with  $\mathit{cap}(c) \geq 1$  are relevant

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transition relation  $\longrightarrow$  is given by SOS-rules:

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interleaving rule for actions  $\alpha \in \mathbf{Act}_i$ :

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↑

does not affect the channel evaluation  $\xi$

# SOS-rules for asynchronous message passing

pc2.2-29

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for synchronous channel  $c$ :

$$l_i \xrightarrow{c?x}_i l'_i \wedge l_j \xrightarrow{c!v}_j l'_j \wedge i \neq j$$

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has a transition system for a channel system with ... ?

- 2 processes with 2 locations each
- 2 Boolean variables
- 2 channels of capacity 10 and Boolean values

# How many states...

PC2.2-31

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*answer:*

$$2 * 2 * 2 * 2 * (2^{11} - 1) * (2^{11} - 1)$$

$$\text{note: } 2^{11} - 1 = 1 + 2 + 2^2 + \dots + 2^{10}$$



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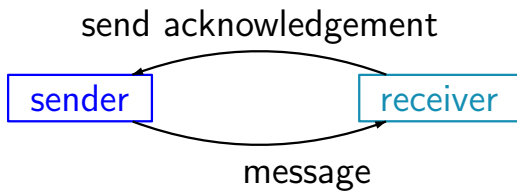
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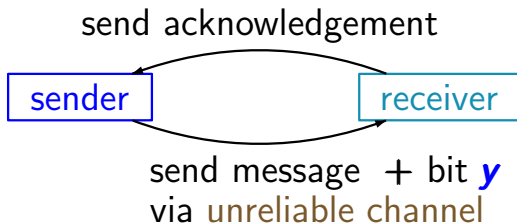
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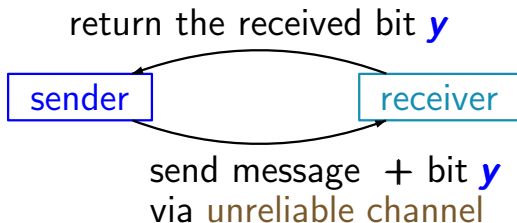
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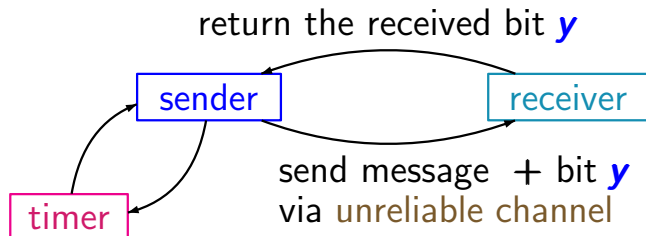
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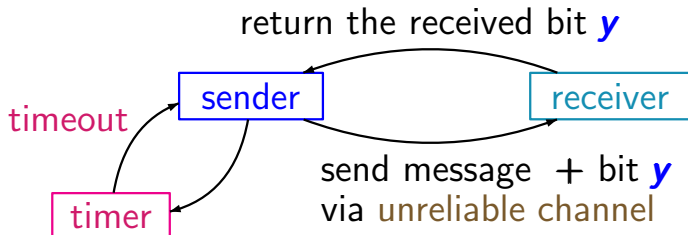
*answer:*  $\infty$











LOOP FOREVER

(1) send message + bit  $y$  and activate timer

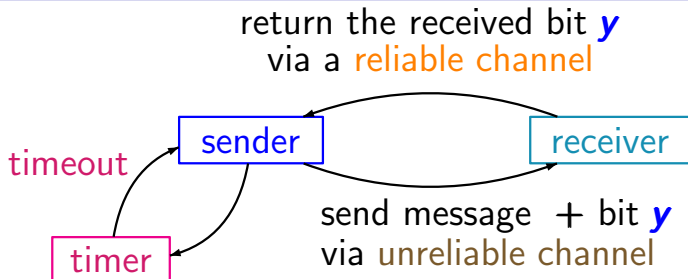
(2) AWAIT timeout or acknowledgement DO

    IF timeout THEN goto (1)

    ELSE turn off timer;  $y := \neg y$

OD





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## If both channels are unreliable ...

PC2.2-33

acknowledgement bit  $x$   
via **unreliable channel d**



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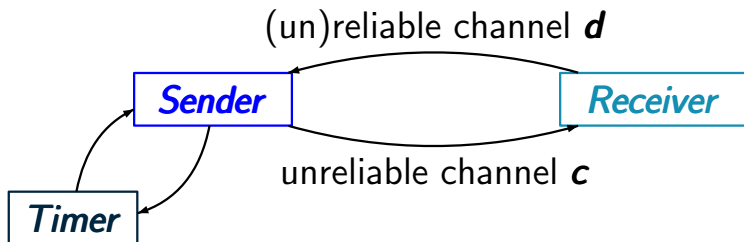


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    IF **timeout** THEN goto (1)  
    ELSE IF  **$x=y$**  THEN turn off timer;  **$y:=\neg y$**   
    ELSE ignore  **$x$**   
    FI  
OD

# Alternating bit protocol (ABP)

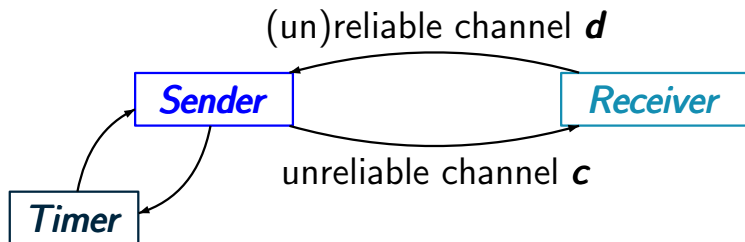
PC2.2-34



channel system: [ **Sender** | **Timer** | **Receiver** ]

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PC2.2-34



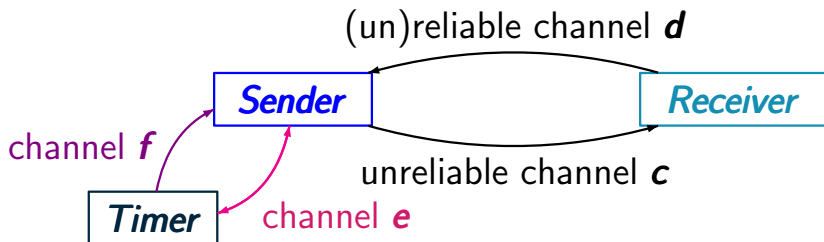
channel system: [ *Sender* | *Timer* | *Receiver* ]

**synchronous** message passing between  
*Timer* and *Sender*

**asynchronous** message passing between  
*Receiver* and *Sender*

# Alternating bit protocol (ABP)

PC2.2-34



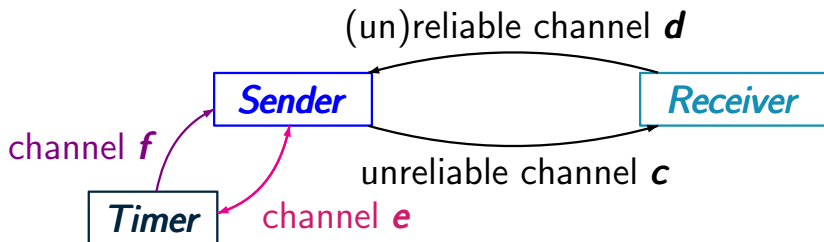
channel system: [ **Sender** | **Timer** | **Receiver** ]

**synchronous** message passing between  
**Timer** and **Sender** ← channels **e** and **f**

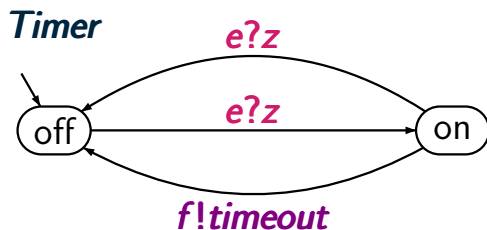
**asynchronous** message passing between  
**Receiver** and **Sender** ← channels **c**, **d**

# Alternating bit protocol (ABP)

PC2.2-34

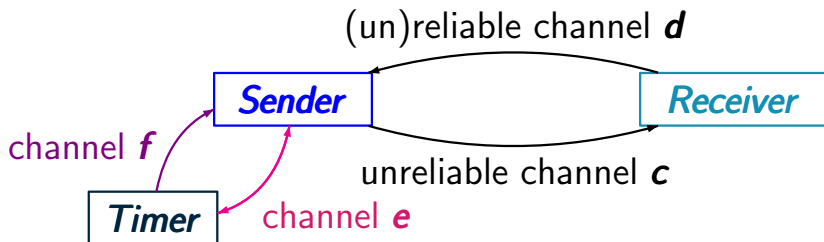


channel system: [ **Sender** | **Timer** | **Receiver** ]



# Alternating bit protocol (ABP)

PC2.2-34



channel system:  $[ \textit{Sender} \mid \textit{Timer} \mid \textit{Receiver} ]$

actions of ***Sender***:

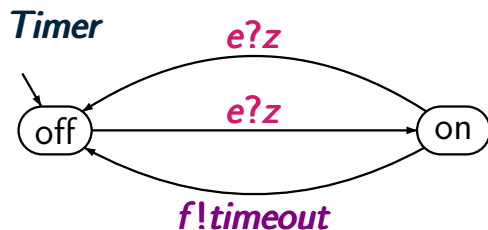
$\vdots$

$e!timer\_on$

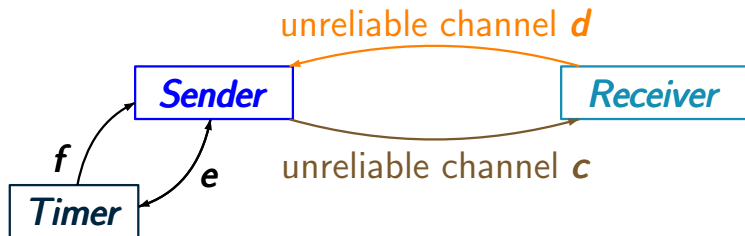
$e!timer\_off$

$f?z'$

$\vdots$

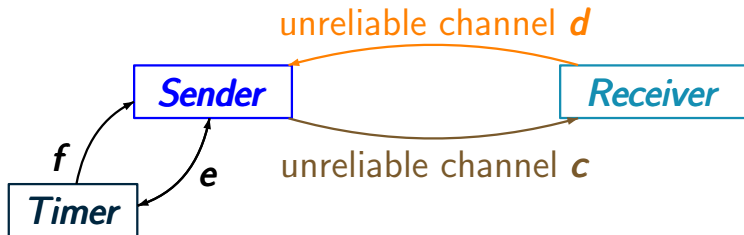






specify the **sender** by a program graph using

- asynchronous channels ***c*** and ***d***
- synchronous channels ***e*** and ***f***

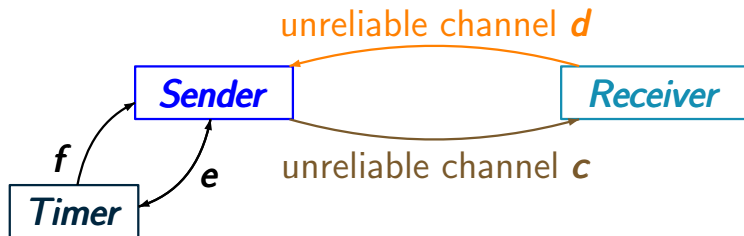


specify the **sender** by a program graph using

- asynchronous channels **c** and **d**
- synchronous channels **e** and **f**

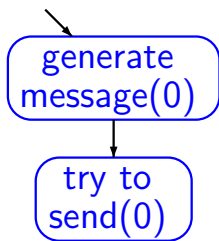
simply write

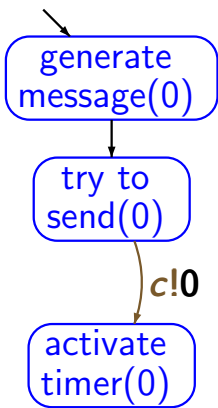
**!timeout**  
**?timer\_on**  
**?timer\_off**

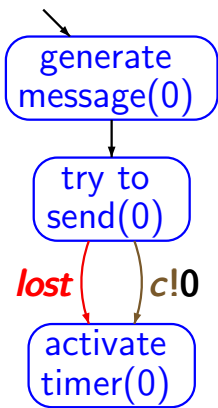


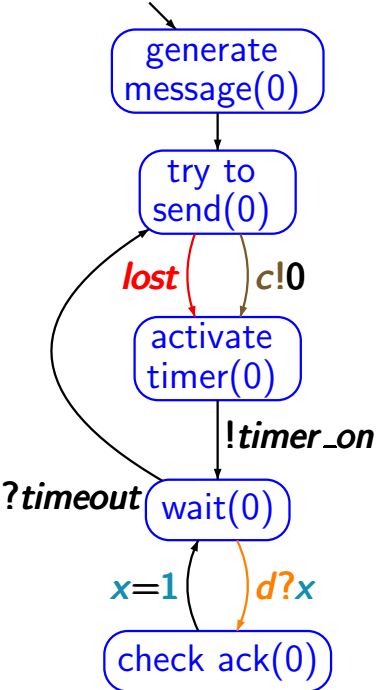
specify the **sender** by a program graph using

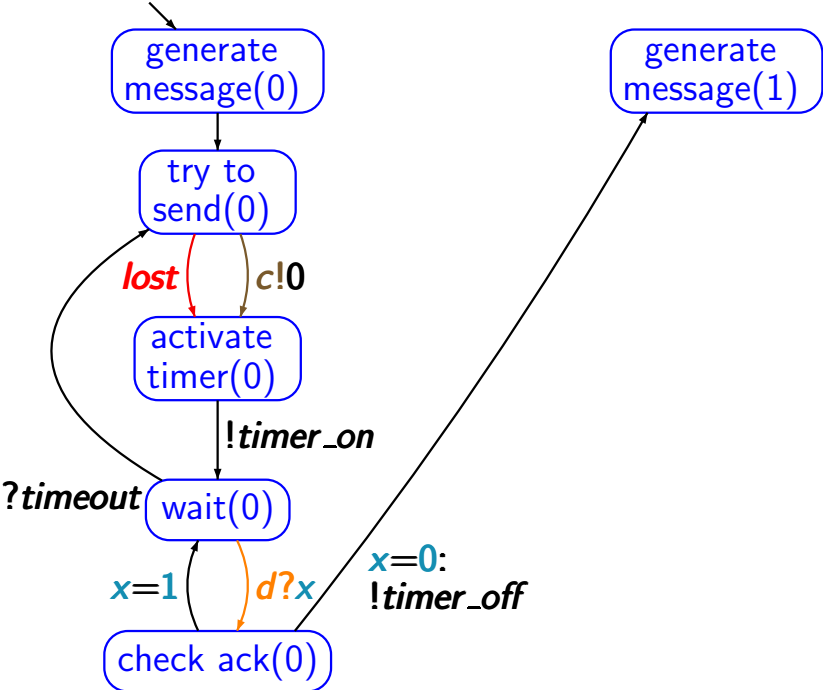
- asynchronous channels **c** and **d**
- synchronous channels **e** and **f**
- Boolean variable **x** for the acknowledgement bit sent by the receiver



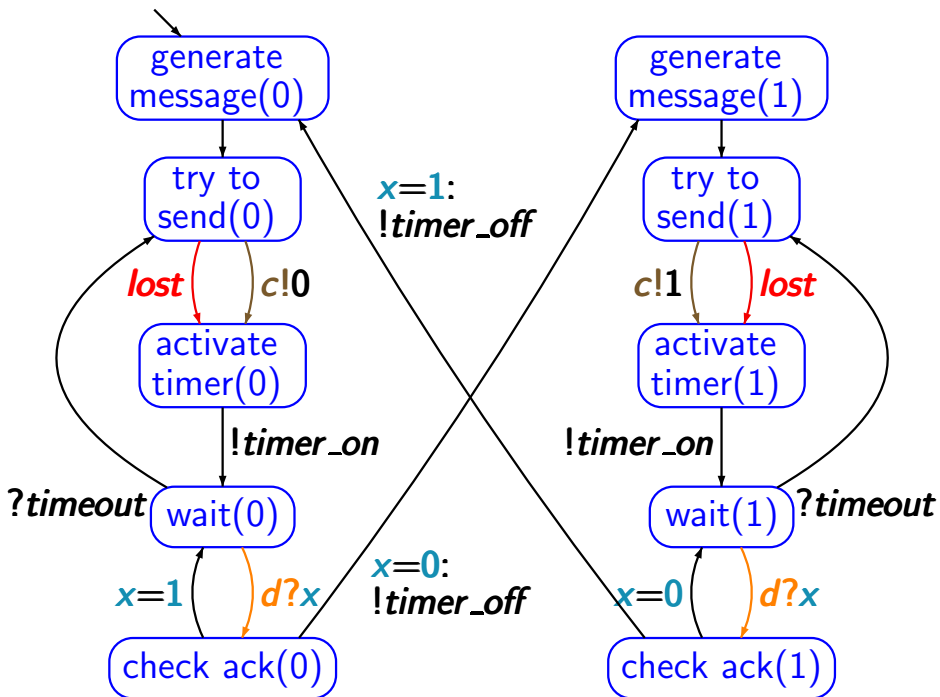






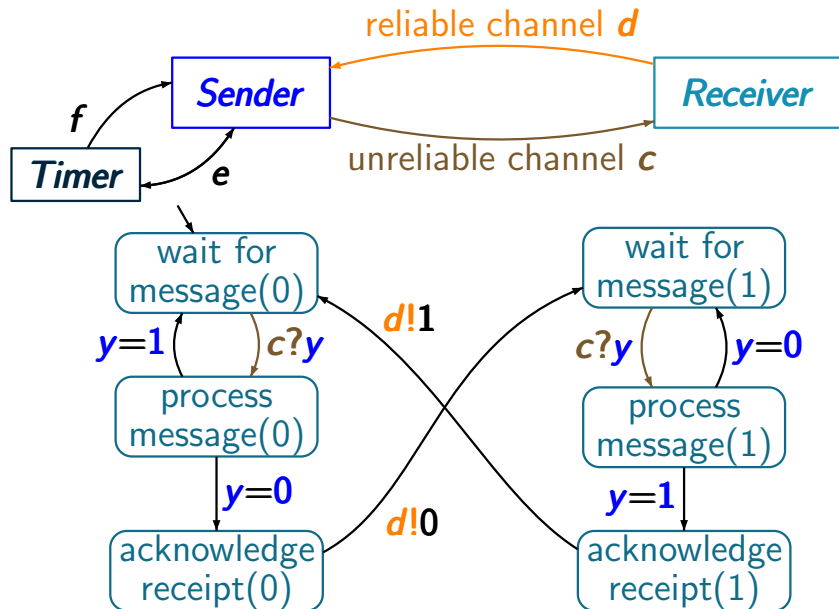


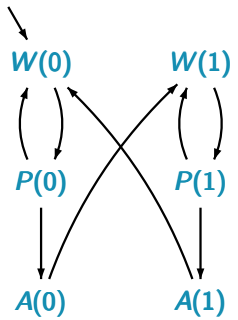
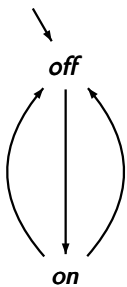
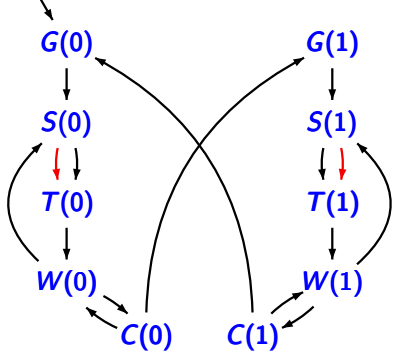


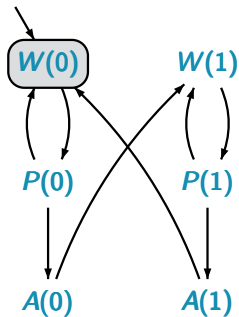
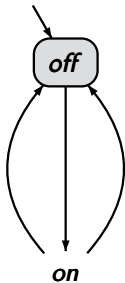
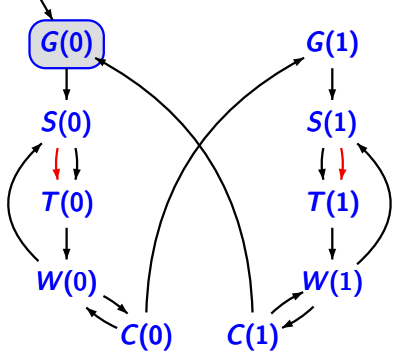


# Program graph for the receiver

PC2.2-36







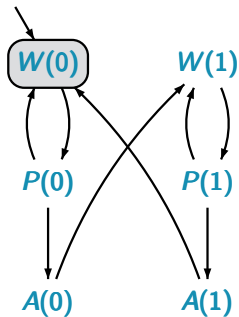
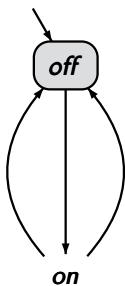
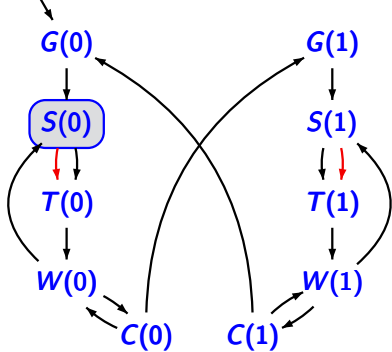
Generate(0)

off

Wait(0)

$c = \epsilon$

$d = \epsilon$



Generate(0)

off

Wait(0)

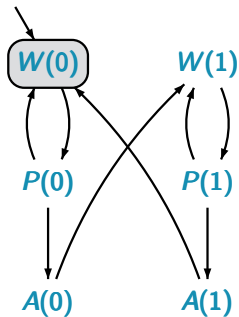
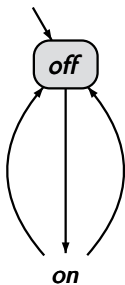
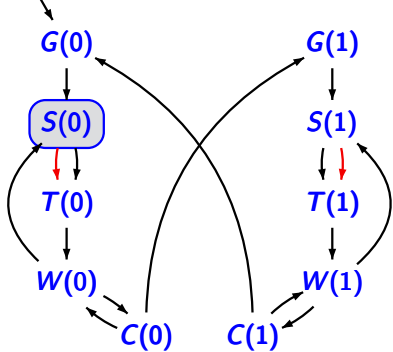
$c = \epsilon$   $d = \epsilon$

Send(0)

off

Wait(0)

$c = \epsilon$   $d = \epsilon$



Generate(0)

off

Wait(0)

$c = \epsilon$

$d = \epsilon$

Send(0)

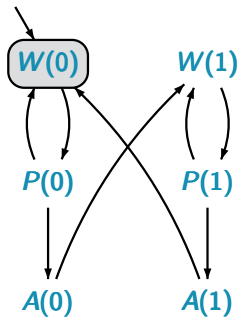
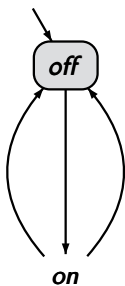
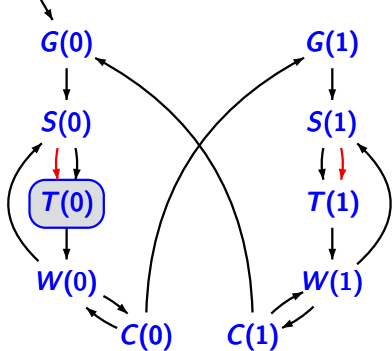
off

Wait(0)

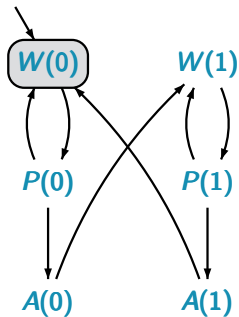
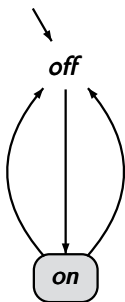
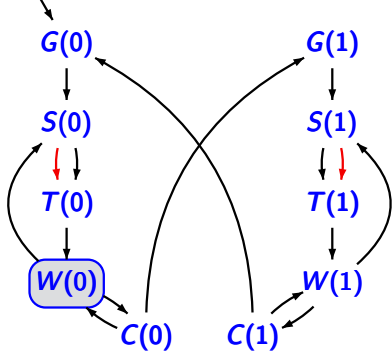
$c = \epsilon$

$d = \epsilon$

message **lost**

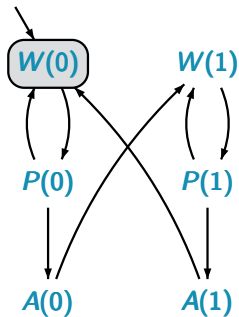
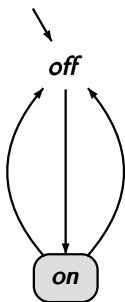
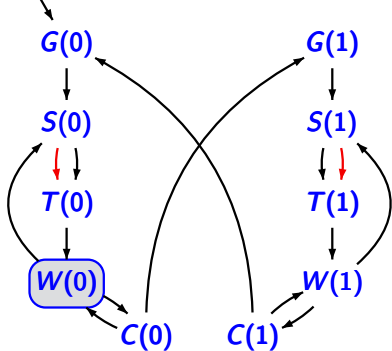


|             |     |         |                |                |                     |
|-------------|-----|---------|----------------|----------------|---------------------|
| Generate(0) | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ |                     |
| Send(0)     | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ | message <b>lost</b> |
| Timer_on(0) | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ |                     |

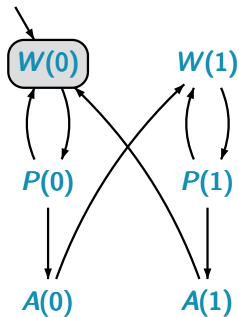
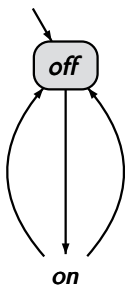
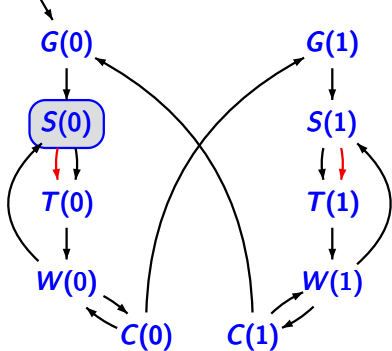


|             |     |         |                |                |                     |
|-------------|-----|---------|----------------|----------------|---------------------|
| Generate(0) | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ |                     |
| Send(0)     | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ | message <b>lost</b> |
| Timer_on(0) | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ |                     |
| Wait(0)     | on  | Wait(0) | $c = \epsilon$ | $d = \epsilon$ |                     |

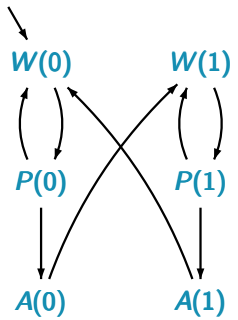
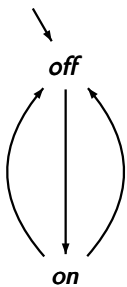
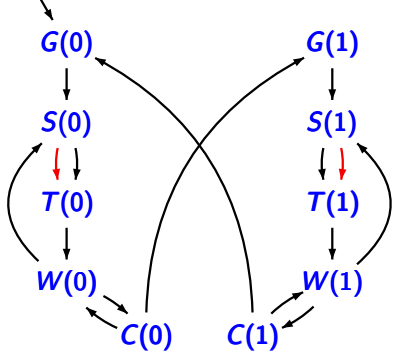


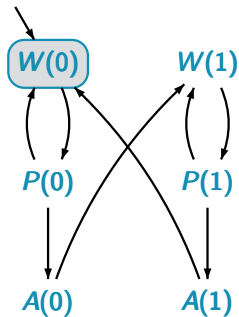
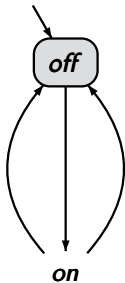
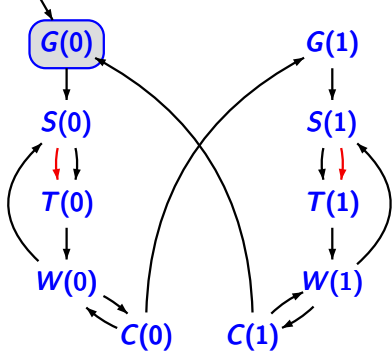


|             |     |         |              |              |                     |
|-------------|-----|---------|--------------|--------------|---------------------|
| Generate(0) | off | Wait(0) | $c=\epsilon$ | $d=\epsilon$ |                     |
| Send(0)     | off | Wait(0) | $c=\epsilon$ | $d=\epsilon$ | message <b>lost</b> |
| Timer_on(0) | off | Wait(0) | $c=\epsilon$ | $d=\epsilon$ |                     |
| Wait(0)     | on  | Wait(0) | $c=\epsilon$ | $d=\epsilon$ | timeout             |

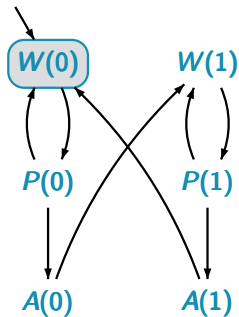
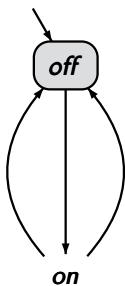
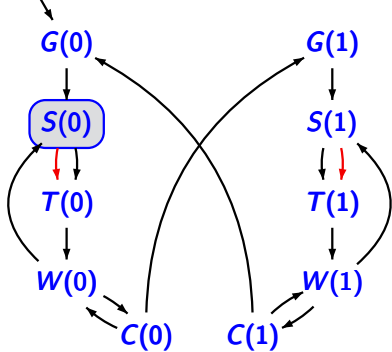


|             |     |         |                |                |                     |
|-------------|-----|---------|----------------|----------------|---------------------|
| Generate(0) | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ |                     |
| Send(0)     | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ | message <b>lost</b> |
| Timer_on(0) | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ |                     |
| Wait(0)     | on  | Wait(0) | $c = \epsilon$ | $d = \epsilon$ | timeout             |
| Send(0)     | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ |                     |
|             | :   |         |                |                | try again           |





Generate(0)    off    Wait(0)     $c=\epsilon$      $d=\epsilon$



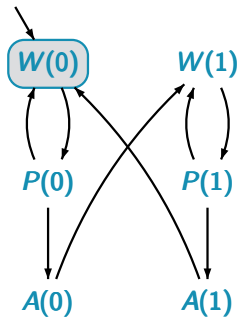
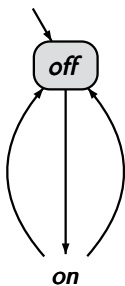
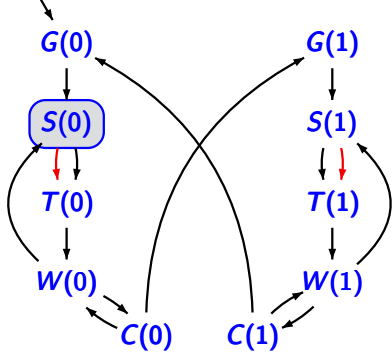
Generate(0)  
Send(0)

off  
off

Wait(0)  
Wait(0)

$c = \epsilon$   
 $c = \epsilon$

$d = \epsilon$   
 $d = \epsilon$



Generate(0)  
Send(0)

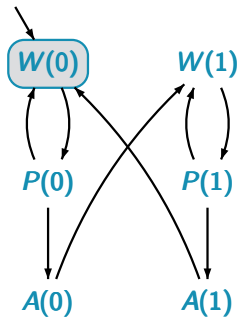
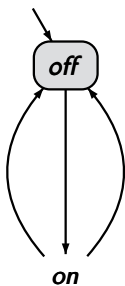
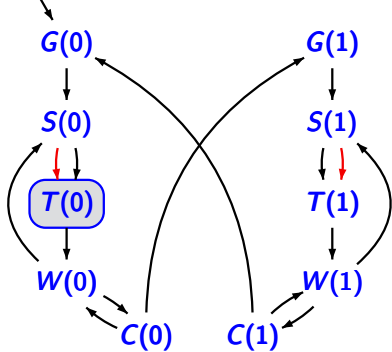
off  
off

Wait(0)  
Wait(0)

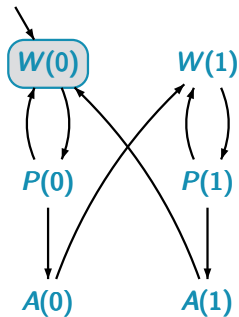
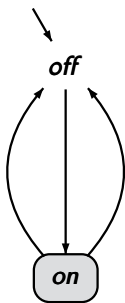
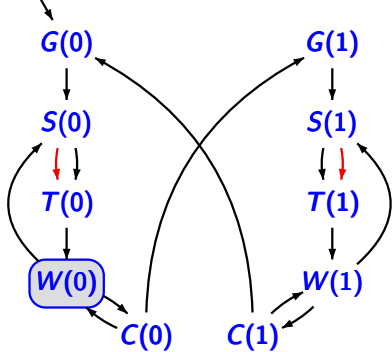
$c = \epsilon$   
 $c = \epsilon$

$d = \epsilon$   
 $d = \epsilon$

message 0 sent

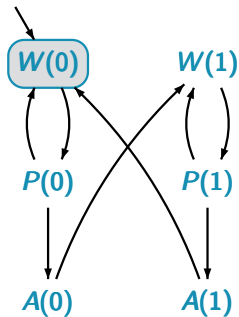
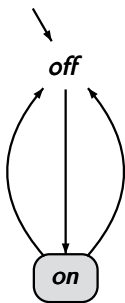
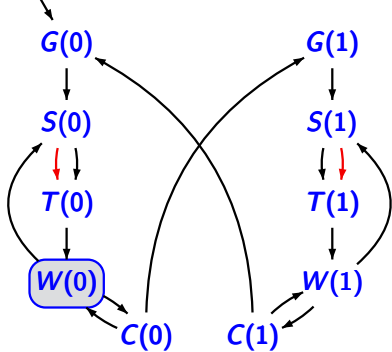


|             |     |         |                |                |                |
|-------------|-----|---------|----------------|----------------|----------------|
| Generate(0) | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ |                |
| Send(0)     | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ | message 0 sent |
| Timer_on(0) | off | Wait(0) | $c = 0$        | $d = \epsilon$ |                |

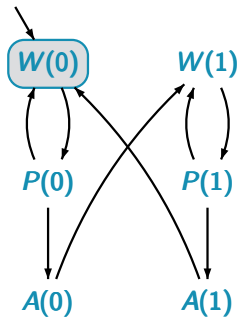
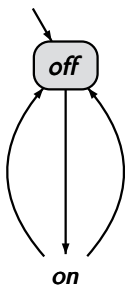
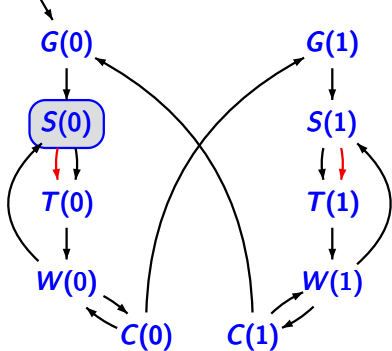


|             |     |         |                |                |                |
|-------------|-----|---------|----------------|----------------|----------------|
| Generate(0) | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ |                |
| Send(0)     | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ | message 0 sent |
| Timer_on(0) | off | Wait(0) | $c = 0$        | $d = \epsilon$ |                |
| Wait(0)     | on  | Wait(0) | $c = 0$        | $d = \epsilon$ |                |

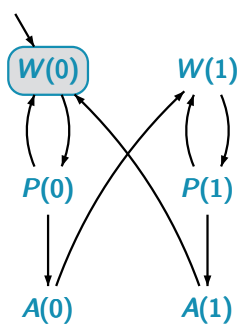
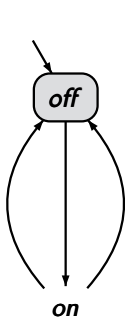
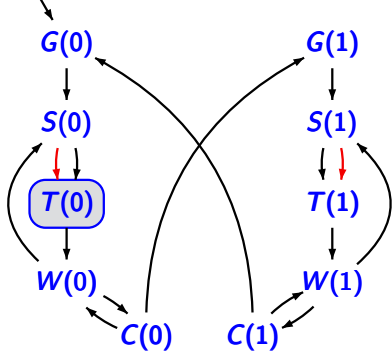




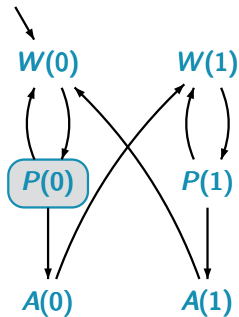
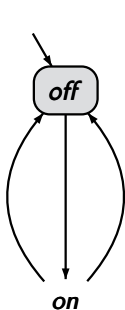
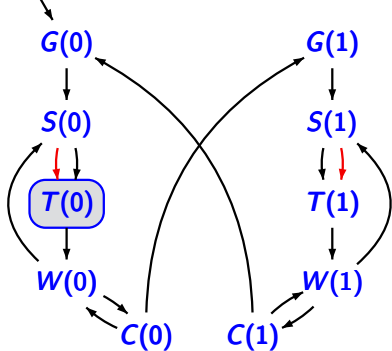
|             |     |         |                |                |                |
|-------------|-----|---------|----------------|----------------|----------------|
| Generate(0) | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ |                |
| Send(0)     | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ | message 0 sent |
| Timer_on(0) | off | Wait(0) | $c = 0$        | $d = \epsilon$ |                |
| Wait(0)     | on  | Wait(0) | $c = 0$        | $d = \epsilon$ | timeout        |



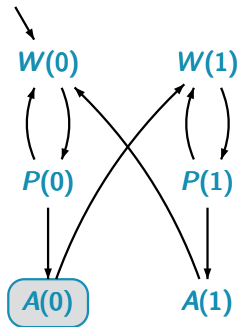
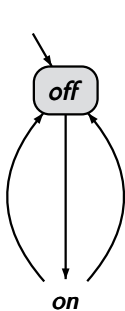
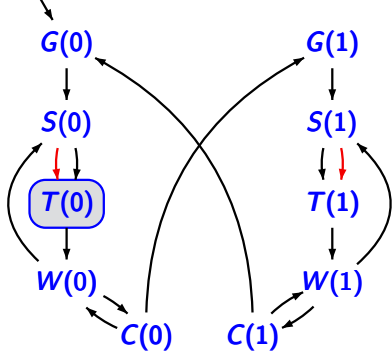
|             |     |         |                |                |                |
|-------------|-----|---------|----------------|----------------|----------------|
| Generate(0) | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ |                |
| Send(0)     | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ | message 0 sent |
| Timer_on(0) | off | Wait(0) | $c = 0$        | $d = \epsilon$ |                |
| Wait(0)     | on  | Wait(0) | $c = 0$        | $d = \epsilon$ | timeout        |
| Send(0)     | off | Wait(0) | $c = 0$        | $d = \epsilon$ |                |



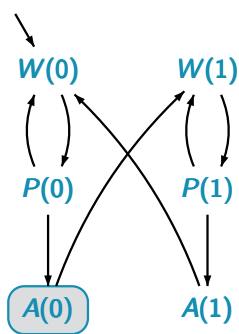
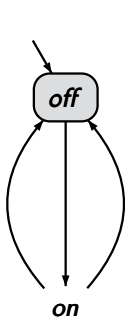
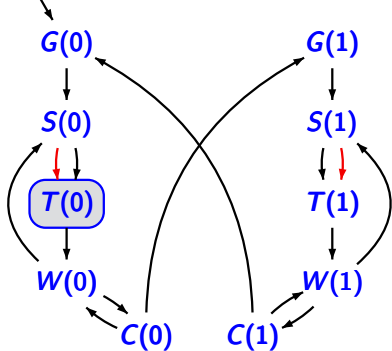
|             |     |         |                |                |                |
|-------------|-----|---------|----------------|----------------|----------------|
| Generate(0) | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ |                |
| Send(0)     | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ | message 0 sent |
| Timer_on(0) | off | Wait(0) | $c = 0$        | $d = \epsilon$ |                |
| Wait(0)     | on  | Wait(0) | $c = 0$        | $d = \epsilon$ | timeout        |
| Send(0)     | off | Wait(0) | $c = 0$        | $d = \epsilon$ | 0 sent again   |
| Timer_on(0) | off | Wait(0) | $c = 00$       | $d = \epsilon$ |                |



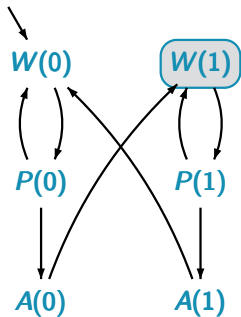
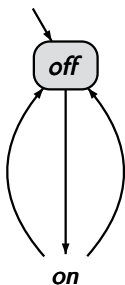
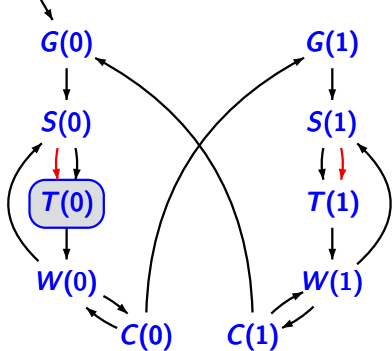
|             |     |         |                |                |                  |
|-------------|-----|---------|----------------|----------------|------------------|
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| Timer_on(0) | off | Wait(0) | $c = 0$        | $d = \epsilon$ |                  |
| Wait(0)     | on  | Wait(0) | $c = 0$        | $d = \epsilon$ | timeout          |
| Send(0)     | off | Wait(0) | $c = 0$        | $d = \epsilon$ | 0 sent again     |
| Timer_on(0) | off | Wait(0) | $c = 00$       | $d = \epsilon$ |                  |
| Timer_on(0) | off | Proc(0) | $c = 0$        | $d = \epsilon$ | message received |



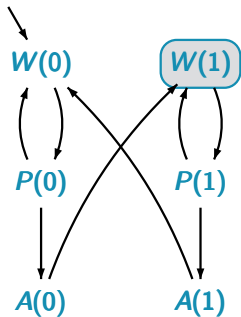
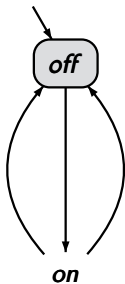
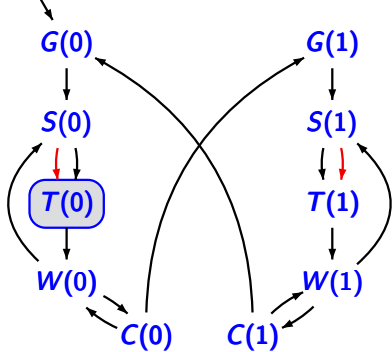
|             |     |         |                |                |                  |
|-------------|-----|---------|----------------|----------------|------------------|
| Generate(0) | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ |                  |
| Send(0)     | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ | message 0 sent   |
| Timer_on(0) | off | Wait(0) | $c = 0$        | $d = \epsilon$ |                  |
| Wait(0)     | on  | Wait(0) | $c = 0$        | $d = \epsilon$ | timeout          |
| Send(0)     | off | Wait(0) | $c = 0$        | $d = \epsilon$ | 0 sent again     |
| Timer_on(0) | off | Wait(0) | $c = 00$       | $d = \epsilon$ |                  |
| Timer_on(0) | off | Proc(0) | $c = 0$        | $d = \epsilon$ | message received |
| Timer_on(0) | off | Ack(0)  | $c = 0$        | $d = \epsilon$ |                  |



|             |     |         |                |                |                  |
|-------------|-----|---------|----------------|----------------|------------------|
| Generate(0) | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ |                  |
| Send(0)     | off | Wait(0) | $c = \epsilon$ | $d = \epsilon$ | message 0 sent   |
| Timer_on(0) | off | Wait(0) | $c = 0$        | $d = \epsilon$ |                  |
| Wait(0)     | on  | Wait(0) | $c = 0$        | $d = \epsilon$ | timeout          |
| Send(0)     | off | Wait(0) | $c = 0$        | $d = \epsilon$ | 0 sent again     |
| Timer_on(0) | off | Wait(0) | $c = 00$       | $d = \epsilon$ |                  |
| Timer_on(0) | off | Proc(0) | $c = 0$        | $d = \epsilon$ | message received |
| Timer_on(0) | off | Ack(0)  | $c = 0$        | $d = \epsilon$ | send ack via $d$ |



|             |     |         |        |              |                           |
|-------------|-----|---------|--------|--------------|---------------------------|
| ⋮           | ⋮   | ⋮       | ⋮      | ⋮            |                           |
| Wait(0)     | on  | Wait(0) | $c=0$  | $d=\epsilon$ | timeout                   |
| Send(0)     | off | Wait(0) | $c=0$  | $d=\epsilon$ | 0 sent again              |
| Timer_on(0) | off | Wait(0) | $c=00$ | $d=\epsilon$ |                           |
| Timer_on(0) | off | Proc(0) | $c=0$  | $d=\epsilon$ | message received          |
| Timer_on(0) | off | Ack(0)  | $c=0$  | $d=\epsilon$ | send ack via $d$          |
| Timer_on(0) | off | Wait(1) | $c=0$  | $d=0$        | receiver changes its mode |



⋮  
Timer\_on(0)

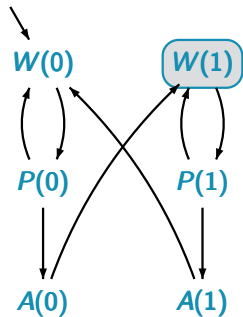
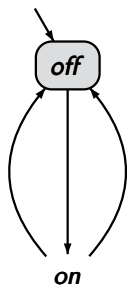
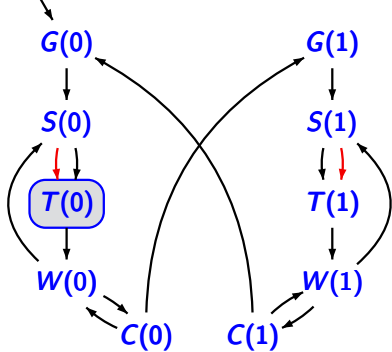
⋮  
off

⋮  
Wait(1)

⋮  
 $c=0$

⋮  
 $d=0$





⋮  
Timer\_on(0)

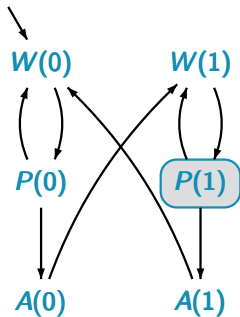
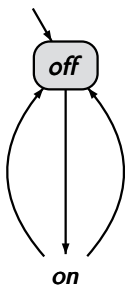
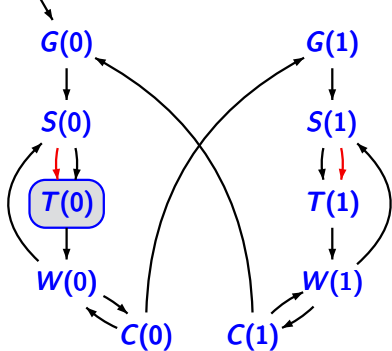
⋮  
off

⋮  
Wait(1)

⋮  
 $c=0$

⋮  
 $d=0$

receiver reads the  
same message again



⋮  
Timer\_on(0)

⋮  
off

⋮  
Wait(1)

⋮  
 $c=0$

⋮  
 $d=0$

receiver reads the  
same message again

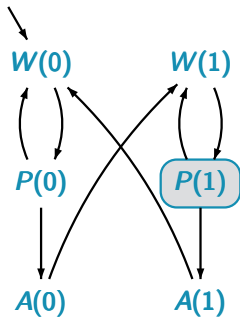
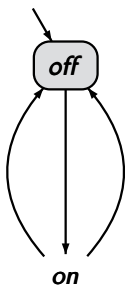
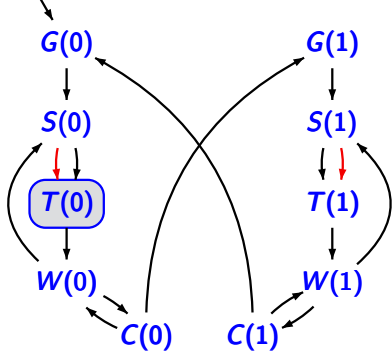
Timer\_on(0)

off

Proc(1)

$c=\epsilon$

$d=0$



⋮  
Timer\_on(0)

⋮  
off

⋮  
Wait(1)

⋮  
 $c=0$

⋮  
 $d=0$

receiver reads the  
same message again

Timer\_on(0)

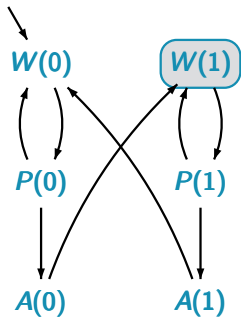
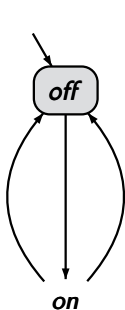
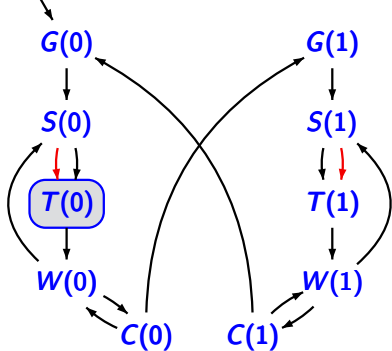
off

Proc(1)

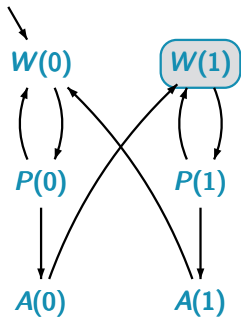
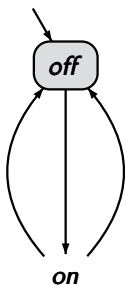
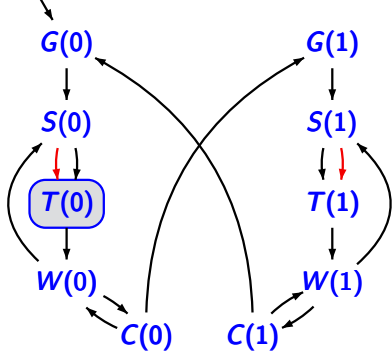
$c=\epsilon$

$d=0$

receiver discards  
the message



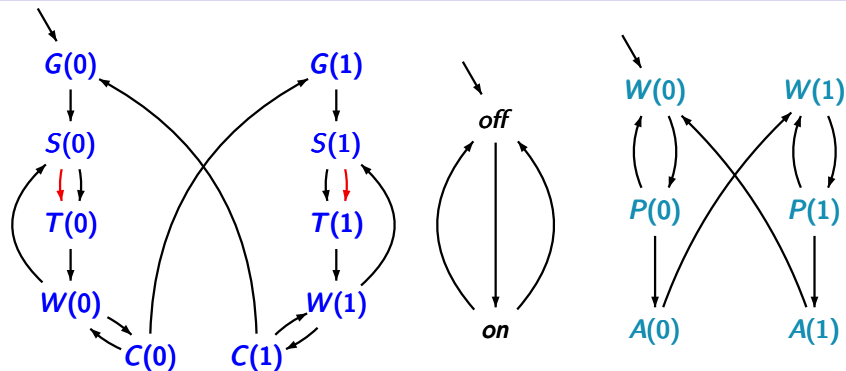
|             |          |          |              |          |                                       |
|-------------|----------|----------|--------------|----------|---------------------------------------|
| $\vdots$    | $\vdots$ | $\vdots$ | $\vdots$     | $\vdots$ |                                       |
| Timer_on(0) | off      | Wait(1)  | $c=0$        | $d=0$    | receiver reads the same message again |
| Timer_on(0) | off      | Proc(1)  | $c=\epsilon$ | $d=0$    | receiver discards the message         |
| Timer_on(0) | off      | Wait(1)  | $c=\epsilon$ | $d=0$    |                                       |



|             |     |         |              |       |                                       |
|-------------|-----|---------|--------------|-------|---------------------------------------|
| ⋮           | ⋮   | ⋮       | ⋮            | ⋮     |                                       |
| Timer_on(0) | off | Wait(1) | $c=0$        | $d=0$ | receiver reads the same message again |
| Timer_on(0) | off | Proc(1) | $c=\epsilon$ | $d=0$ | receiver discards the message         |
| Timer_on(0) | off | Wait(1) | $c=\epsilon$ | $d=0$ |                                       |
| ⋮           | ⋮   | ⋮       | ⋮            | ⋮     |                                       |

# Alternating bit protocol (ABP)

PC2.2-37C

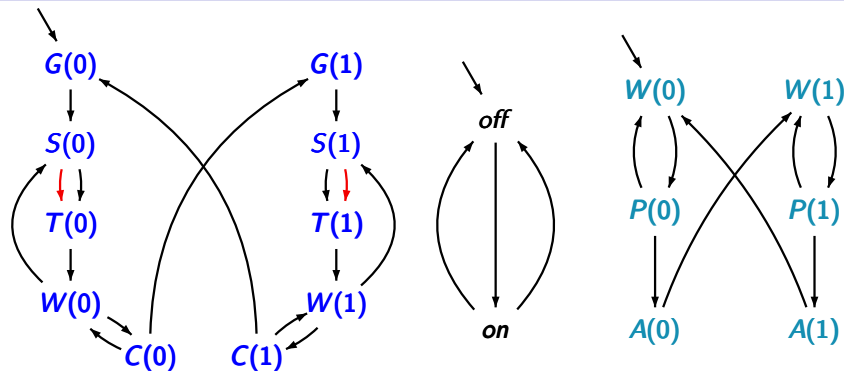


number of states in the TS:

$$10 \cdot 2 \cdot 6 \cdot \# \text{channel evaluations}$$

# Alternating bit protocol (ABP)

PC2.2-37C



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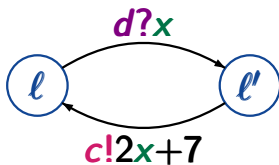
$> 10^8$  for FIFOs with capacity **10**

- conditional communication actions  $l \xleftrightarrow{g:c?x} l'$



- conditional communication actions  $l \xrightarrow{g:c?x} l'$
- generalized sending instructions  $c!expr$  instead of  $c!v$

e.g.

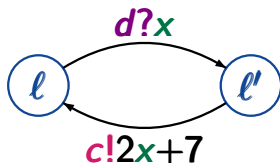


# Variants of channel systems

pc2.2-38

- conditional communication actions  $l \xleftrightarrow{g:c?x} l'$
- generalized sending instructions  $c!expr$  instead of  $c!v$

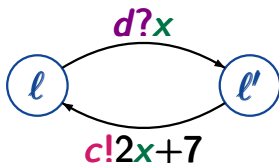
e.g.



- communication as conditions  $l \xleftrightarrow{c?x:\alpha} l'$

- conditional communication actions  $l \xleftrightarrow{g:c?x} l'$
- generalized sending instructions  $c!expr$  instead of  $c!v$

e.g.



- communication as conditions  $l \xleftrightarrow{c?x:\alpha} l'$

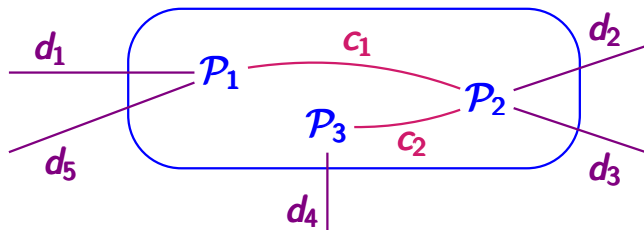
$\rightsquigarrow$  more compact TS-representations

- conditional communication actions  $l \xleftrightarrow{g:c?x} l'$
- generalized sending instructions  $c!expr$  instead of  $c!v$
- communication as conditions  $l \xleftrightarrow{c?x:\alpha} l'$
- *open* channel systems  $\mathcal{P}_1 | \dots | \mathcal{P}_n$   
instead of *closed* channel systems  $[\mathcal{P}_1 | \dots | \mathcal{P}_n]$

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pc2.2-38

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*(pure) interleaving* for TS  $\mathcal{T}_1 \parallel \mathcal{T}_2$

- only concurrency, no communication
- not applicable for competing systems

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- synchronization via actions in *Syn*



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*channel systems*: open  $\mathcal{P}_1 | \dots | \mathcal{P}_n$  or closed  $[\mathcal{P}_1 | \dots | \mathcal{P}_n]$

- interleaving, shared variables, message passing

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- only concurrency, no communication

*synchronous message passing* for TS  $\mathcal{T}_1 \parallel_{\text{Syn}} \mathcal{T}_2$

- interleaving, synchronization via actions in *Syn*

*interleaving* for program graphs  $\mathcal{P}_1 \parallel \mathcal{P}_2$

- interleaving, shared variables

*channel systems*: open  $\mathcal{P}_1 | \dots | \mathcal{P}_n$  or closed  $[\mathcal{P}_1 | \dots | \mathcal{P}_n]$

- interleaving, shared variables
- synchronous and asynchronous message passing

**synchronous product** for TS  $\mathcal{T}_1 \otimes \mathcal{T}_2$

- no interleaving, “pure” synchronization

for parallel systems with fully synchronized processes

$$\left. \begin{array}{l} \mathcal{T}_1 = (\mathbf{S}_1, \mathbf{Act}_1, \longrightarrow_1, \dots) \\ \mathcal{T}_2 = (\mathbf{S}_2, \mathbf{Act}_2, \longrightarrow_2, \dots) \end{array} \right\} \text{two TS}$$

synchronous product:

$$\mathcal{T}_1 \otimes \mathcal{T}_2 = (\mathbf{S}_1 \times \mathbf{S}_2, \mathbf{Act}, \longrightarrow, \dots)$$

for parallel systems with fully synchronized processes

$$\left. \begin{array}{l} \mathcal{T}_1 = (S_1, Act_1, \longrightarrow_1, \dots) \\ \mathcal{T}_2 = (S_2, Act_2, \longrightarrow_2, \dots) \end{array} \right\} \text{two TS}$$

synchronous product:

$$\mathcal{T}_1 \otimes \mathcal{T}_2 = (S_1 \times S_2, Act, \longrightarrow, \dots)$$

where the action set  $Act$  is given by a function

$$Act_1 \times Act_2 \longrightarrow Act, (\alpha, \beta) \mapsto \alpha * \beta$$

↑  
action name for the concurrent  
execution of  $\alpha$  and  $\beta$

# Synchronous product

PC2.2-41

for parallel systems with fully synchronized processes

$$\left. \begin{array}{l} \mathcal{T}_1 = (\mathcal{S}_1, \text{Act}_1, \longrightarrow_1, \dots) \\ \mathcal{T}_2 = (\mathcal{S}_2, \text{Act}_2, \longrightarrow_2, \dots) \end{array} \right\} \text{two TS}$$

synchronous product:

$$\mathcal{T}_1 \otimes \mathcal{T}_2 = (\mathcal{S}_1 \times \mathcal{S}_2, \text{Act}, \longrightarrow, \dots)$$

where the action set  $\text{Act}$  is given by a function

$$\text{Act}_1 \times \text{Act}_2 \longrightarrow \text{Act}, \quad (\alpha, \beta) \mapsto \alpha * \beta$$

↑  
action name for the concurrent  
execution of  $\alpha$  and  $\beta$

if action names are irrelevant:  $\text{Act}_1 = \text{Act}_2 = \text{Act} = \{\tau\}$

for parallel systems with fully synchronized processes

$$\left. \begin{array}{l} \mathcal{T}_1 = (\mathbf{S}_1, \mathbf{Act}_1, \longrightarrow_1, \dots) \\ \mathcal{T}_2 = (\mathbf{S}_2, \mathbf{Act}_2, \longrightarrow_2, \dots) \end{array} \right\} \text{two TS}$$

synchronous product:

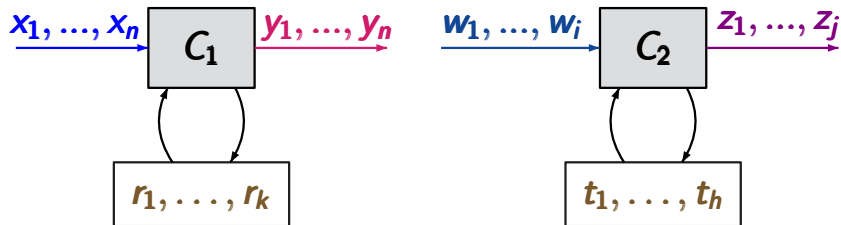
$$\mathcal{T}_1 \otimes \mathcal{T}_2 = (\mathbf{S}_1 \times \mathbf{S}_2, \mathbf{Act}, \longrightarrow, \dots)$$

transition relation  $\longrightarrow$ :

$$\frac{s_1 \xrightarrow{\alpha}_1 s'_1 \wedge s_2 \xrightarrow{\beta}_2 s'_2}{\langle s_1, s_2 \rangle \xrightarrow{\alpha * \beta} \langle s'_1, s'_2 \rangle}$$

# Synchronous product for composing circuits

PC2.2-40

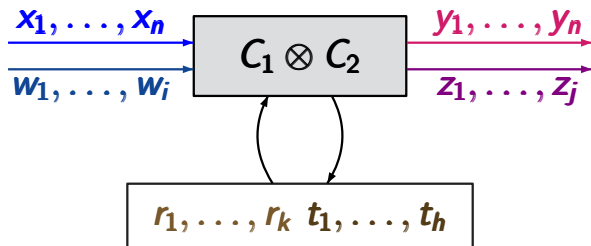
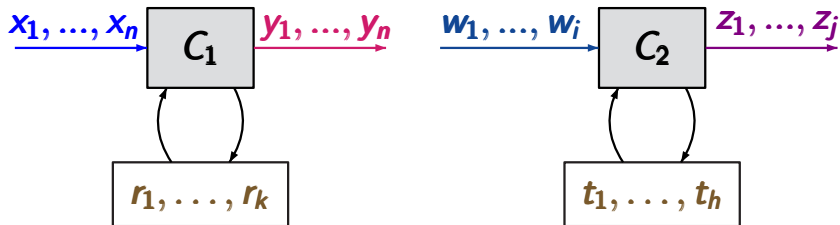


2 sequential circuits



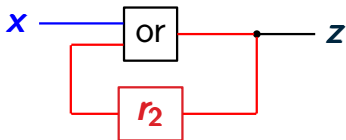
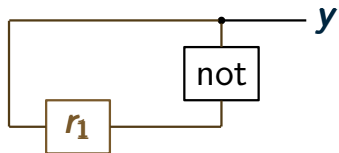
# Synchronous product for composing circuits

PC2.2-40



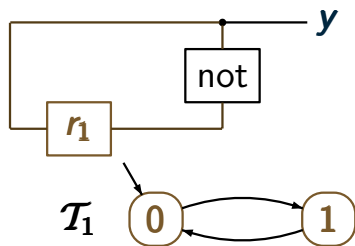
# Synchronous product: example

PC2.2-52



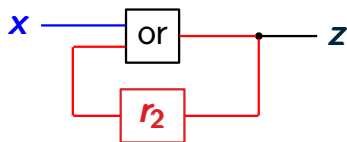
# Synchronous product: example

PC2.2-52



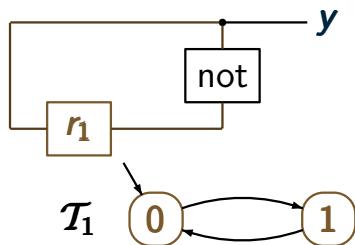
initially:  
 $r_1 = 0$

transition function:  
 $\delta_{r_1} = \neg r_1$



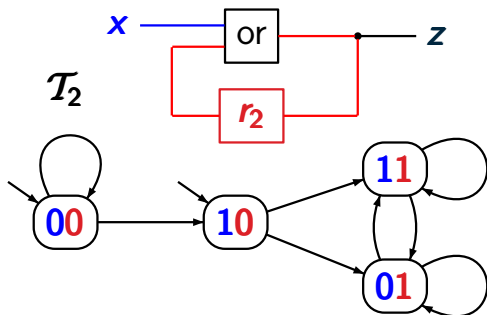
# Synchronous product: example

PC2.2-52



initially:  
 $r_1 = 0$

transition function:  
 $\delta_{r_1} = \neg r_1$

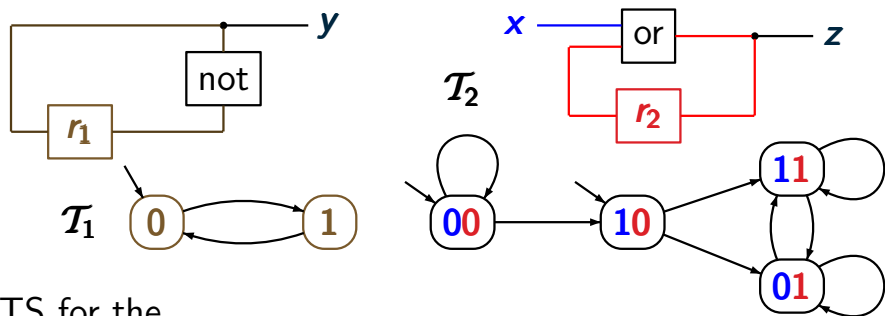


initially:  
 $r_2 = 0$

transition function:  
 $\delta_{r_2} = r_2 \vee x$

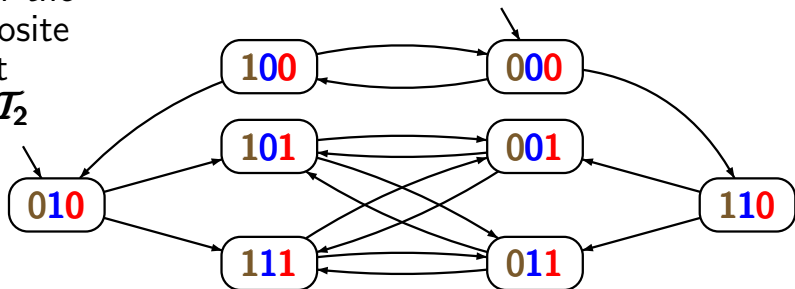
# Synchronous product: example

PC2.2-52



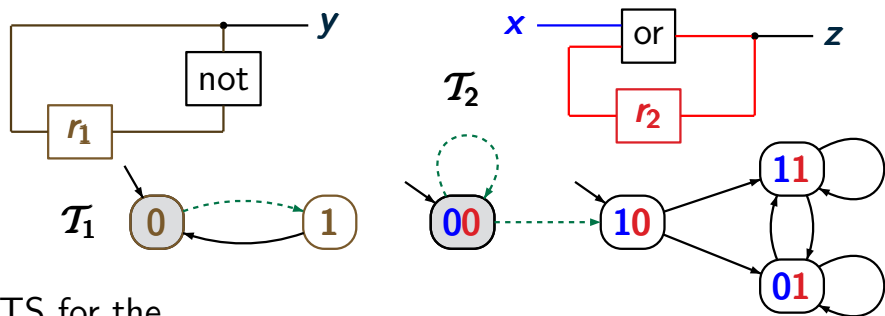
TS for the  
composite  
circuit

$\mathcal{T}_1 \otimes \mathcal{T}_2$



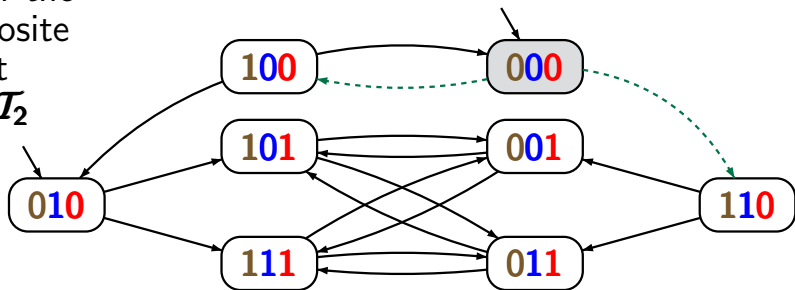
# Synchronous product: example

PC2.2-52



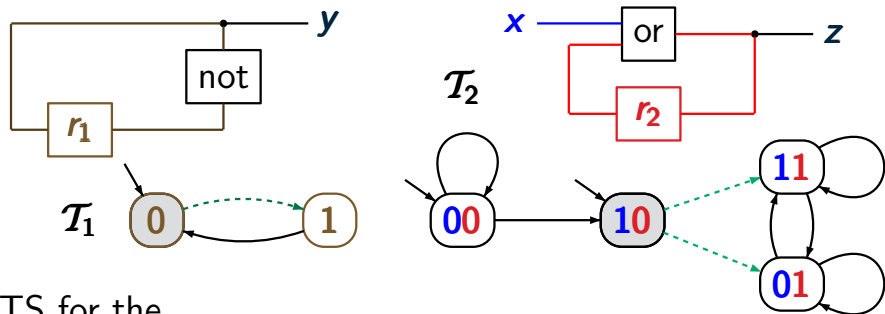
TS for the  
composite  
circuit

$\mathcal{T}_1 \otimes \mathcal{T}_2$



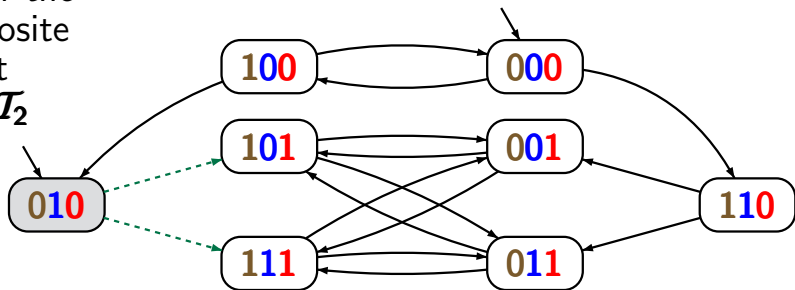
# Synchronous product: example

PC2.2-52



TS for the  
composite  
circuit

$\mathcal{T}_1 \otimes \mathcal{T}_2$



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e.g., for channel systems: size of the state space is

$$|Loc_1| \cdot \dots \cdot |Loc_n| \cdot \prod_{x \in Var} |Dom(x)| \cdot \prod_{c \in Chan} |Dom(c)|^{cap(c)}$$

